

# Analogues of the $3x + 1$ Problem in Polynomial Rings of Characteristic 2 Supplemental Document

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## Abstract

This document contains additional proof details which were left out of the main paper for clarity and brevity. These are mostly straight-forward calculations.

## 1 Terras' theorem in $\mathbb{F}_2[t]$

### 1.1 The map $\Phi_m$

Let  $\Phi_m : \mathbb{F}_2[t]/t^N \rightarrow \{0, 1\}^N$  be defined as the function which maps each element  $f \in \mathbb{F}_2[t]$  of degree less than  $N$  to the first  $N$  terms of its parity sequence.

**Lemma 1.1.** *The map  $\Phi_m$  described above is a set bijection. That is, every sequence  $\{p_0, p_1, \dots, p_{N-1}\}$  with  $p_i \in \{0, 1\}$  is the first  $N$  terms of the parity sequence of a unique polynomial  $f \in \mathbb{F}_2[t]$  with  $\deg f < N$ . Specifically, the parity sequence determines the initial polynomial  $f$  and its  $N$ -th iterate  $T^N(f)$  as follows, up to choice of  $q_N$ :*

$$\begin{aligned} f &= g_{N-1} + t^N q_N, & \deg g_{N-1} &< N \\ T^N(f) &= h_{N-1} + m^{s(N)} q_N, & \deg h_{N-1} &< ds(N) \end{aligned}$$

where  $d = \deg m$  and  $s(N) = \sum_{i=0}^{N-1} p_i$ . Therefore, parity sequences of polynomials in  $\mathbb{F}_2[t]$  of degree  $< N$  are distributed uniformly in  $\{0, 1\}^N$ .

In the paper we prove this lemma by induction on  $N$ . When we come to the inductive step, there are four cases to consider, depending on the values of  $h_{N-1}(0)$  and  $p_N$  in  $\{0, 1\}$ . Here we give the full proof for all four cases.

**Case 1:**  $h_{N-1}(0) = 0$ ,  $p_N = 0$ . That is, the  $N$ -th term of the trajectory is ‘even’ and  $q_N$  is also even. Let  $q_N = tq_{N+1}$ . Then the next term is

$$\begin{aligned} f_{N+1} &= \frac{f_N}{t} = \frac{h_{N-1} + m^{s(N)}q_N}{t} \\ &= \frac{h_{N-1}}{t} + m^{s(N)}q_{N+1} \end{aligned}$$

We can rewrite the initial polynomial as

$$f = g_{N-1} + t^{N+1}q_{N+1}.$$

Since  $\deg h_{N-1}/t < s(N) \deg m$  and  $\deg g_{N-1} < N + 1$ , the theorem holds in this case.

**Case 2:**  $h_{N-1}(0) = 0$ ,  $p_N = 1$ . That is, the  $N$ -th term of the trajectory is odd and  $q_N$  is also odd. Let  $q_N = 1 + tq_{N+1}$ . Then the next term is

$$\begin{aligned} f_{N+1} &= \frac{m[h_{N-1} + m^{s(N)}q_N] + 1}{t} \\ &= \frac{mh_{N-1} + m^{s(N+1)} + 1}{t} + m^{s(N+1)}q_{N+1} \end{aligned}$$

Let  $h_N = \frac{mh_{N-1} + m^{s(N+1)} + 1}{t}$ . Since  $\deg h_{N-1} < 2s(N)$ , we have  $\deg h_N < (\deg m)s(N+1)$  as required. We rewrite the initial polynomial as

$$\begin{aligned} f &= g_{N-1} + t^N(tq_{N+1} + 1) \\ &= (g_{N-1} + t^N) + t^{N+1}q_{N+1}. \end{aligned}$$

Clearly  $\deg(g_{N-1} + t^N) < N + 1$ , so the theorem holds in this case.

**Case 3:**  $h_{N-1}(0) = 1$ ,  $p_N = 0$ . That is, the  $N$ -th term of the trajectory is even and  $q_N$  is odd. Let  $q_N = 1 + tq_{N+1}$ . Then the next term is

$$\begin{aligned} f_{N+1} &= \frac{h_{N-1} + m^{s(N)}q_N}{t} \\ &= \frac{h_{N-1} + m^{s(N)}}{t} + m^{s(N+1)}q_{N+1} \end{aligned}$$

Let  $h_N = (h_{N-1} + m^X)/t$ . Since  $\deg h_{N-1} < 2s(N+1)$ , we have  $\deg h_N < s(N+1) \deg m$  as required. Next we rewrite the initial polynomial as

$$\begin{aligned} f &= g_{N-1} + t^Nq_N \\ &= g_{N-1} + t^N + t^{N+1}q_{N+1}. \end{aligned}$$

And we know  $g_{N-1} + t^N$ , has degree less than  $N + 1$ , so the theorem holds in this case.

**Case 4:**  $h_{N-1}(1) = 1$ ,  $p_N = 1$ . That is, the  $N$ -th term of the trajectory is odd and  $q_N$  is even. Let  $q_N = tq_{N+1}$ . Then the next term is

$$\begin{aligned} f_{N+1} &= \frac{m [h_{N-1} + m^{s(N)} q_N] + 1}{t} \\ &= \frac{mh_{N-1} + 1}{t} + m^{s(N+1)} q_{N+1}. \end{aligned}$$

Let  $h_N = (mh_{N-1} + 1)/t$ . This has degree  $< 2s(N + 1)$  as required. Lastly, we rewrite the initial polynomial:

$$\begin{aligned} f &= g_{N-1} + t^N q_N \\ &= g_{N-1} + t^{N+1} q_{N+1}. \end{aligned}$$

The theorem is satisfied because  $\deg g_{N-1} < N + 1$ .

## 1.2 Gambler's Ruin

In the paper, we describe how the problem of determining the probability that a polynomial  $f \in \mathbb{F}_2[t]$  will have finite stopping time can be formulated as a version of the well-known “gambler’s ruin” problem. We prove the following lemma.

**Lemma 1.2.** *For  $k = 0, \dots, N-1$ , let  $X_k$  be IID uniform Bernoulli variables and let  $P_d$  be defined*

$$P_d = P \left( \exists N > 0 : \sum_{k=0}^{N-1} X_k < \frac{1}{d} N \right).$$

*Then  $P_1 = P_2 = 1$ , and for  $d > 2$ ,  $P_d$  is the unique real root of the polynomial  $g_d(z) = z^d - 2z + 1$  lying inside the unit disk.*

Here we present some additional details of the proof that were left out of the paper to save space.

### 1.2.1 Solving a linear recurrence

For  $d > 2$ , let  $\lambda_1, \lambda_2, \dots, \lambda_d$  be the  $d$  distinct complex roots of the polynomial  $g_d(z) = z^d - 2z + 1$ . In the paper, we write the probability of ruin in this case as

$$P_d = \lim_{W \rightarrow \infty} P_{d,W} = \lim_{W \rightarrow \infty} (c_1 + c_2 + \dots + c_d),$$

where  $c_j$  are the solutions of the following linear system:

$$\begin{bmatrix} \lambda_1^{-1} & \lambda_2^{-1} & \lambda_3^{-1} & \cdots & \lambda_d^{-1} \\ \lambda_1^W & \lambda_2^W & \lambda_3^W & \cdots & \lambda_d^W \\ \lambda_1^{W+1} & \lambda_2^{W+1} & \lambda_3^{W+1} & \cdots & \lambda_d^{W+1} \\ \vdots & \vdots & \vdots & & \vdots \\ \lambda_1^{W+d-1} & \lambda_2^{W+d-1} & \lambda_3^{W+d-1} & \cdots & \lambda_d^{W+d-1} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ \vdots \\ c_d \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}.$$

This system can be solved analytically using Cramer's rule. Let  $A$  be the  $d \times d$  matrix above and let  $b$  be the column vector on the right-hand side of the system. Using Cramer's rule, we write

$$U_0 = \sum_{i=1}^d c_i = \frac{\sum_{i=1}^d \det A_i}{\sum_{i=1}^d \lambda_i^{-1} A_{1,i}} \quad (1)$$

where  $A_i$  is the matrix formed by replacing the  $i$ -th column of  $A$  with  $b$ , and  $A_{i,j}$  is the  $i, j$  cofactor of  $A$ .

Because  $b$  in this case is just the first standard basis vector,  $\det A_i = A_{1,i}$  for each  $1 \leq i \leq d$ . We compute  $A_{1,1}$  as an example; the others follow the exact same pattern.

$$\begin{aligned} \det A_1 &= \det \begin{bmatrix} 1 & \lambda_2^{-1} & \lambda_3^{-1} & \cdots & \lambda_d^{-1} \\ 0 & \lambda_2^W & \lambda_3^W & \cdots & \lambda_d^W \\ 0 & \lambda_2^{W+1} & \lambda_3^{W+1} & \cdots & \lambda_d^{W+1} \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & \lambda_2^{W+d-1} & \lambda_3^{W+d-1} & \cdots & \lambda_d^{W+d-1} \end{bmatrix} \\ &= \det \begin{bmatrix} \lambda_2^W & \lambda_3^W & \cdots & \lambda_d^W \\ \lambda_2^{W+1} & \lambda_3^{W+1} & \cdots & \lambda_d^{W+1} \\ \vdots & \vdots & & \vdots \\ \lambda_2^{W+d-1} & \lambda_3^{W+d-1} & \cdots & \lambda_d^{W+d-1} \end{bmatrix} \\ &= \prod_{j=2}^d \lambda_j^W \det \begin{bmatrix} 1 & 1 & \cdots & 1 \\ \lambda_2 & \lambda_3 & \cdots & \lambda_d \\ \vdots & \vdots & & \vdots \\ \lambda_2^{d-1} & \lambda_3^{d-1} & \cdots & \lambda_d^{d-1} \end{bmatrix}. \end{aligned}$$

The matrix in the last row above is a Vandermonde matrix with parameters  $\lambda_2, \lambda_3, \dots, \lambda_d$ , so its determinant is  $\prod_{2 \leq j < k \leq d} (\lambda_k - \lambda_j)$ . More generally, for any  $1 \leq i \leq d$ , let  $B_i$  be the determinant of the  $(d-1) \times (d-1)$

Vandermonde matrix with parameters  $\lambda_1, \dots, \lambda_{i-1}, \lambda_{i+1}, \dots, \lambda_d$ . Then

$$B_i = \prod_{\substack{1 \leq j < k \leq d \\ j, k \neq i}} (\lambda_k - \lambda_j)$$

And since  $\prod_{j=1}^d \lambda_j = 1$ , we can write

$$\begin{aligned} \det A_i &= (-1)^{1+i} \prod_{\substack{1 \leq j \leq d \\ j \neq i}} \lambda_j^W B_i \\ &= (-1)^{1+i} \lambda_i^{-W} B_i. \end{aligned}$$

We can now rewrite equation (1) as follows:

$$U_0 = \frac{\sum_{i=1}^d (-1)^{1+i} \lambda_i^{-W} B_i}{\sum_{i=1}^d (-1)^{1+i} \lambda_i^{-W-1} B_i}.$$

This makes it clear that if there exists a root  $\lambda_1$  of  $g_d(z)$  with minimal absolute value, then  $\lim_{W \rightarrow \infty} U_0 = \lambda_1$ .

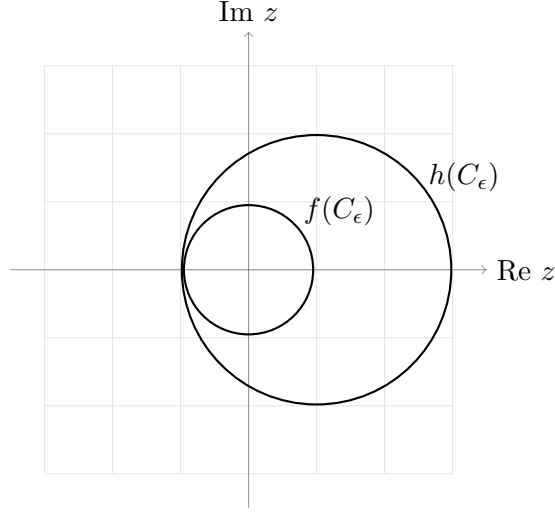
### 1.2.2 The roots of $g_d(z)$

Here we provide a fully detailed proof that for  $d > 2$ ,  $g_d(z) = z^d - 2z + 1$  has a unique root inside the unit disk, and that this root is real and positive. Using Descartes' rule of signs, we determine that there are two positive real roots of  $g_d(z)$ , one of which is  $z = 1$ . Since  $g'_d(1) = d - 2 > 0$ , we know that  $g_d(1 - \epsilon) < 0$  for small positive epsilon. On the other hand,  $g_d(1/2) = (1/2)^d > 0$ , so the other real root must lie in the interval  $(1/2, 1)$ .

Next, we use Rouché's theorem to prove that there is only one root within the unit circle. Let  $f(z) = z^d$  and let  $h(z) = -2z + 1$ . For small positive  $\epsilon$ , consider the circle  $C_\epsilon = \{z \in \mathbb{C} : |z| = 1 - \epsilon\}$ . The function  $f$  maps  $C_\epsilon$  to a smaller circle  $|z| = (1 - \epsilon)^d$ . Define  $m_f(\epsilon) = (1 - \epsilon)^d$ . Then  $|f(z)| = m_f(\epsilon)$  for all  $z \in C_\epsilon$ . The other function  $h$  maps  $C_\epsilon$  to a circle of radius  $2(1 - \epsilon)$  centered at  $z = 1$ . The point on this circle closest to the origin is the point  $z = -1 + 2\epsilon$ , with magnitude  $|-1 + 2\epsilon| = 1 - 2\epsilon$ . Define  $m_h(\epsilon) = 1 - 2\epsilon$ . Then for all  $z \in C_\epsilon$ ,  $|h(z)| \geq m_h(\epsilon)$ . See Figure 1.

We claim that for small positive  $\epsilon$ ,  $m_h(\epsilon) > m_f(\epsilon)$  and therefore that  $|h(z)| > |f(z)|$  for all  $z \in C_\epsilon$ . Notice that  $m_h(0) = m_f(0) = 1$ . Calculating the derivatives of the two functions, we see that  $m'_h(0) = -2$  and  $m'_f(0) = -d$ . By continuity, since  $m'_h(0) > m'_f(0)$ ,  $m_h(\epsilon)$  must be greater than  $m_f(\epsilon)$  for small positive values of epsilon. Since  $|h(z)| > |f(z)|$  for all  $z \in C_\epsilon$ ,

Figure 1:



$g_d(z) = h(z) + f(z)$  must have the same number of roots within  $C_\epsilon$  as  $h(z)$ . The function  $h(z) = 1 - 2z$  has one root at  $z = 1/2$ . Therefore, for small positive  $\epsilon$ ,  $g_d(z)$  has a unique root inside the circle  $|z| = 1 - \epsilon$ , which must be the previously mentioned real root lying in the interval  $(1/2, 1)$ .

## 2 Terras' theorem in $R_r$

In the ring  $R_r = \mathbb{F}_2[x, t]/(x^2 + tx + r(t))$ , we once again formulate the probability that a randomly chosen polynomial has finite  $mx + 1$  stopping time as a version of the gambler's ruin problem. We prove the following lemma.

**Lemma 2.1.** *For  $d > 0$ , let  $P_d$  be defined*

$$P_d = P \left( \exists N > 0 : \sum_{k=0}^{N-1} X_k < \frac{N}{d} \right)$$

*where  $X_i$  are IID Bernoulli variables taking the value 1 with probability  $1/4$  and 0 otherwise. If  $d \leq 4$ , then  $P_d = 1$ . If  $d > 4$ , then  $P_d$  is the unique root of  $g_d(z) = z^d - 4z + 3$  inside the unit disk, which is real and lies in the interval  $(3/4, 1)$ .*

Here we present some additional details of the proof that were left out of the paper to save space.

## 2.1 Solving a recurrence relation

As in  $\mathbb{F}_2[t]$ , we first use a recurrence relation to solve the alternate version of the game which ends if the gambler reaches a value of  $\$W$ . We label  $U_k$  the probability of ruin under these conditions given a starting value of  $\$k$ . Clearly  $U_k = -1$  for all  $k < 0$  and  $U_k = 0$  for all  $k \geq W$ . For other values of  $k$ , we have the following linear recurrence relation.

$$U_k = \frac{3}{4}U_{k-1} + \frac{1}{4}U_{k+d-1}$$

Our goal is to find the value of  $U_0$ , representing the probability of ruin (depending on  $W$ ) starting from a value of 0. If we then take the limit of this quantity as  $W \rightarrow \infty$ , we will learn the actual probability of ruin in a game with no upper limit.

The auxiliary polynomial for the recurrence is  $g_d(z) = z^d - 4z + 3$ , which is separable as long as  $d \neq 4$ . When  $d = 4$  the root  $z = 1$  has multiplicity 2, so we handle this case first. In this case, the solutions to the recurrence equation will take the form  $U_k = c_1 + c_2k + c_3\lambda^k + c_4\bar{\lambda}^k$ . Since we know that  $U_{-1} = 1$  and  $U_W = U_{W+1} = U_{W+2} = 0$ , we can find the specific solution we need by solving the following linear system:

$$\begin{bmatrix} 1 & -1 & \lambda^{-1} & \bar{\lambda}^{-1} \\ 1 & W & \lambda^W & \bar{\lambda}^W \\ 1 & W+1 & \lambda^{W+1} & \bar{\lambda}^{W+1} \\ 1 & W+2 & \lambda^{W+2} & \bar{\lambda}^{W+2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$

The quantity we are seeking is then  $U_0 = c_1 + c_3 + c_4$ . We label the  $4 \times 4$  matrix above  $A$ . Using Cramer's rule, we write

$$\begin{aligned} U_0 &= c_1 + c_3 + c_4 \\ &= \frac{\det A_1}{\det A} + \frac{\det A_3}{\det A} + \frac{\det A_4}{\det A} \\ &= \frac{\det A_1 + \det A_3 + \det A_4}{\det A} \end{aligned}$$

where  $A_j$  is the determinant of  $A$  with the column  $j$  replaced by  $[1, 0, \dots, 0]$ . Next, we expand the determinant of  $A$  in terms of the cofactors.

$$\det A = A_{1,1} - A_{1,2} + \lambda^{-1}A_{1,3} + \bar{\lambda}^{-1}A_{1,4}.$$

For this linear system, because the right-hand vector  $b$  is just the first standard basis vector, the determinant of  $A$  with the  $j$ -th column replaced

by  $b$  is the same as the  $(1, j)$ -cofactor of  $A$ . That is,  $\det A_i = A_{1,i}$ . This allows us to write

$$U_0 = \frac{A_{1,1} + A_{1,3} + A_{1,4}}{A_{1,1} - A_{1,2} + \lambda^{-1}A_{1,3} + \bar{\lambda}^{-1}A_{1,4}}.$$

We argue that  $A_{1,1}$  dominates the other terms asymptotically as  $W \rightarrow \infty$ , and therefore that  $P_4 = \lim_{W \rightarrow \infty} U_0 = 1$ . We must express all four cofactors as functions of  $W$ .

$$\begin{aligned} A_{1,1} &= \begin{vmatrix} W & \lambda^W & \bar{\lambda}^W \\ W+1 & \lambda^{W+1} & \bar{\lambda}^{W+1} \\ W+2 & \lambda^{W+2} & \bar{\lambda}^{W+2} \end{vmatrix} = \lambda^W \bar{\lambda}^W \begin{vmatrix} W & 1 & 1 \\ W+1 & \lambda & \bar{\lambda} \\ W+2 & \lambda^2 & \bar{\lambda}^2 \end{vmatrix} \\ &= \lambda^W \bar{\lambda}^W \left( W \begin{vmatrix} \lambda & \bar{\lambda} \\ \lambda^2 & \bar{\lambda}^2 \end{vmatrix} - \begin{vmatrix} W+1 & \bar{\lambda} \\ W+2 & \bar{\lambda}^2 \end{vmatrix} + \begin{vmatrix} W+1 & \lambda \\ W+2 & \lambda^2 \end{vmatrix} \right) \\ &= \lambda^W \bar{\lambda}^W [W(\lambda \bar{\lambda}^2 - \lambda^2 \bar{\lambda}) - (W \bar{\lambda}^2 + \bar{\lambda}^2 - W \bar{\lambda} - 2 \bar{\lambda}) + (W \lambda^2 + \lambda^2 - W \lambda - 2 \lambda)] \\ &= \lambda^W \bar{\lambda}^W [W(\lambda \bar{\lambda}^2 - \lambda^2 \bar{\lambda} + \lambda^2 - \bar{\lambda}^2 + \bar{\lambda} - \lambda) + \lambda^2 - \bar{\lambda}^2 + 2 \bar{\lambda} - 2 \lambda] \\ &\text{Here we use the fact that } \lambda \text{ and } \bar{\lambda} \text{ are the roots of } x^2 + 2x + 3. \\ &= 3^W [W(3 \bar{\lambda} - 3 \lambda - 2 \lambda - 3 + 2 \bar{\lambda} + 3 + \bar{\lambda} - \lambda) - 2 \lambda - 3 + 2 \bar{\lambda} + 3 + 2 \bar{\lambda} - 2 \lambda] \\ &= 6(\bar{\lambda} - \lambda)W 3^W + 4(\bar{\lambda} - \lambda)3^W. \end{aligned}$$

$$\begin{aligned} A_{1,2} &= - \begin{vmatrix} 1 & \lambda^W & \bar{\lambda}^W \\ 1 & \lambda^{W+1} & \bar{\lambda}^{W+1} \\ 1 & \lambda^{W+2} & \bar{\lambda}^{W+2} \end{vmatrix} = -\lambda^W \bar{\lambda}^W \begin{vmatrix} 1 & 1 & 1 \\ 1 & \lambda & \bar{\lambda} \\ 1 & \lambda^2 & \bar{\lambda}^2 \end{vmatrix} \\ &= -3^W [(3 \bar{\lambda} - 3 \lambda) - (\bar{\lambda}^2 - \bar{\lambda}) + (\lambda^2 - \lambda)] \\ &= -3^W [3 \bar{\lambda} - 3 \lambda + 3 \bar{\lambda} + 3 - 3 \lambda - 3] \\ &= -6(\bar{\lambda} - \lambda)3^W. \end{aligned}$$

$$\begin{aligned} A_{1,3} &= \begin{vmatrix} 1 & W & \bar{\lambda}^W \\ 1 & W+1 & \bar{\lambda}^{W+1} \\ 1 & W+2 & \bar{\lambda}^{W+2} \end{vmatrix} = \bar{\lambda}^W \begin{vmatrix} 1 & W & 1 \\ 1 & W+1 & \bar{\lambda} \\ 1 & W+2 & \bar{\lambda}^2 \end{vmatrix} \\ &= \bar{\lambda}^W \left( \begin{vmatrix} W+1 & \bar{\lambda} \\ W+2 & \bar{\lambda}^2 \end{vmatrix} - W \begin{vmatrix} 1 & \bar{\lambda} \\ 1 & \bar{\lambda}^2 \end{vmatrix} + \begin{vmatrix} 1 & W+1 \\ 1 & W+2 \end{vmatrix} \right) \\ &= \bar{\lambda}^W [(W \bar{\lambda}^2 + \bar{\lambda}^2 - W \bar{\lambda} - 2 \bar{\lambda}) - W(\bar{\lambda}^2 - W \bar{\lambda}) + (W+2 - W-1)] \\ &= \bar{\lambda}^W (\bar{\lambda}^2 - 2 \bar{\lambda} + 1) \\ &= \bar{\lambda}^W (-4 \bar{\lambda} - 2). \end{aligned}$$



$$\begin{aligned}
A_{1,4} &= - \begin{vmatrix} 1 & W & \lambda^W \\ 1 & W+1 & \lambda^{W+1} \\ 1 & W+2 & \lambda^{W+2} \end{vmatrix} = -\lambda^W \begin{vmatrix} 1 & W & 1 \\ 1 & W+1 & \lambda \\ 1 & W+2 & \lambda^2 \end{vmatrix} \\
&= -\lambda^W \left( \begin{vmatrix} W+1 & \lambda \\ W+2 & \lambda^2 \end{vmatrix} - W \begin{vmatrix} 1 & \lambda \\ 1 & \lambda^2 \end{vmatrix} + \begin{vmatrix} 1 & W+1 \\ 1 & W+2 \end{vmatrix} \right) \\
&= -\lambda^W [(W\lambda^2 + \lambda^2 - W\lambda - 2\lambda) - W(\lambda^2 - W\lambda) + (W+2 - W-1)] \\
&= -\lambda^W (\lambda^2 - 2\lambda + 1) \\
&= -\lambda^W (-4\lambda - 2).
\end{aligned}$$

To summarize, the asymptotic growth rates of the cofactors are:

$$\begin{aligned}
A_{1,1} &\sim W 3^W \\
A_{1,2} &\sim 3^W \\
A_{1,3} &\sim \lambda^W \\
A_{1,4} &\sim \bar{\lambda}^W.
\end{aligned}$$

It is clear that  $A_{1,1}$  dominates the other cofactors as  $W \rightarrow \infty$ . Since the numerator and denominator have the same dominant term with the same coefficient, the probability of ruin in this case is

$$P_4 = \lim_{W \rightarrow \infty} P_{4,W} = 1.$$

For  $d \neq 4$  we have  $\gcd(f, f') = 1$ , so in this case the polynomial is separable. Therefore every solution must have the form  $U_k = c_1 \lambda_1^k + c_2 \lambda_2^k + \dots + c_d \lambda_d^k$ . The linear system we must solve is exactly the same as the one we found in  $\mathbb{F}_2[t]$ , except that the roots  $\lambda_i$  are now the roots of  $z^d - 4z + 3 = 0$ .

$$\begin{bmatrix} \lambda_1^{-1} & \lambda_2^{-1} & \lambda_3^{-1} & \dots & \lambda_d^{-1} \\ \lambda_1^W & \lambda_2^W & \lambda_3^W & \dots & \lambda_d^W \\ \lambda_1^{W+1} & \lambda_2^{W+1} & \lambda_3^{W+1} & \dots & \lambda_d^{W+1} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ \lambda_1^{W+d-1} & \lambda_2^{W+d-1} & \lambda_3^{W+d-1} & \dots & \lambda_d^{W+d-1} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ \vdots \\ c_d \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}.$$

We can solve this system in the same way, using Cramer's rule and Vandermonde determinants. The product of all the roots is still the constant term of  $g_d(z)$ , which in this case is  $\prod_{j=1}^d \lambda_j = 3$ . So  $\det A_i =$

$(-1)^{1+i}3^W\lambda_i^{-W}B_i$ , and the solution to the recurrence relation is

$$\begin{aligned} P_{d,W} = U_0 &= \sum_{j=1}^d c_j \\ &= \sum_{j=1}^d \frac{\det A_j}{\det A} \\ &= \frac{\sum_{j=1}^d (-1)^{1+j} 3^W \lambda_j^{-W} B_j}{\sum_{j=1}^d (-1)^{1+j} 3^W \lambda_j^{-W-1} B_j} \end{aligned}$$

where  $B_j$  are defined as Vandermonde determinants as before. Just as in  $\mathbb{F}_2[t]$ , if  $\lambda_1$  is a real root with strictly smaller absolute value than all of the others, then the limit of the above quantity is

$$P_d = \lim_{W \rightarrow \infty} U_0 = \lambda_1.$$

## 2.2 Roots of $g_d(z)$

We will now examine the polynomial  $g_d(z) = z^d - 4z + 3$  and show that when  $d \neq 4$ , such a root does in fact exist.

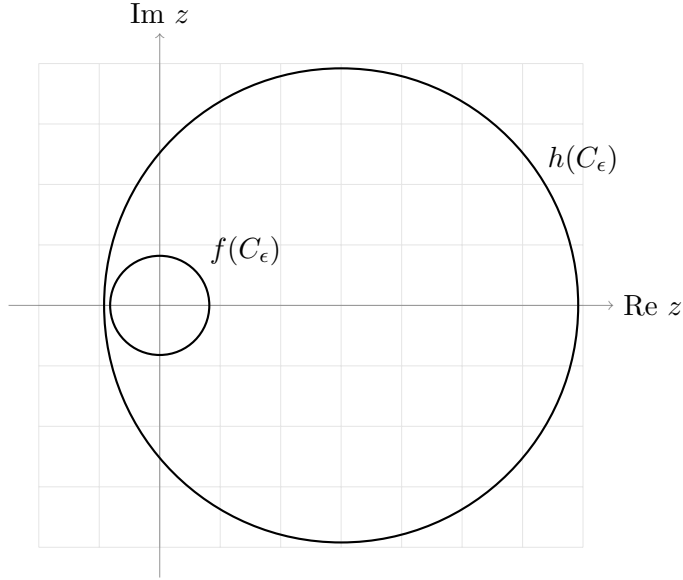
$d = 2$ : The polynomial  $g_2(z) = z^2 - 4z + 3$  has roots at  $z = 1$  and  $z = 3$ . Since  $z = 1$  is the root with the smallest magnitude, the probability of ruin is 1.

$d = 3$ : We write  $g_3(z) = z^3 - 4z + 3 = (z - 1)(z^2 + z - 3)$ . Using the quadratic formula, we find that the roots of  $z^2 + z - 3$  are  $z = -\frac{1}{2} \pm \frac{\sqrt{13}}{2}$ , both of which have magnitude  $> 1$ . Since  $z = 1$  is the root with the smallest magnitude, the probability of ruin is 1.

$d > 4$ : Using Descartes' rule of signs, we determine that there are two positive real roots of  $g_d(z)$ . We know that one of these is  $z = 1$ . Since  $g'_d(1) = d - 4 > 0$ , we know that  $g_d(1 - \epsilon) < 0$  for small positive epsilon. On the other hand,  $g_d(3/4) = (3/4)^d > 0$ . Therefore, the other real root must lie in the interval  $(3/4, 1)$ .

Next, we use Rouché's theorem to prove that there is only one root within the unit circle. Let  $f(z) = z^d$  and let  $h(z) = -4z + 3$ . For small positive  $\epsilon$ , consider the circle  $C_\epsilon = \{z \in \mathbb{C} : |z| = 1 - \epsilon\}$ . The function  $f$  maps  $C_\epsilon$  to a smaller circle  $|z| = (1 - \epsilon)^d$ . Define  $m_f(\epsilon) = (1 - \epsilon)^d$ . Then  $|f(z)| = m_f(\epsilon)$  for all  $z \in C_\epsilon$ .

The other function  $h$  maps  $C_\epsilon$  to a circle of radius  $4(1 - \epsilon)$  centered at  $z = 3$ . The point on this circle closest to the origin is the point  $z = -1 + 4\epsilon$ , with magnitude  $|-1 + 4\epsilon| = 1 - 4\epsilon$ . Define  $m_h(\epsilon) = 1 - 4\epsilon$ . Then for all  $z \in C_\epsilon$ ,  $|h(z)| \geq m_h(\epsilon)$ .



We claim that for small positive  $\epsilon$ ,  $m_h(\epsilon) > m_f(\epsilon)$  and therefore that  $|h(z)| > |f(z)|$  for all  $z \in C_\epsilon$ . Notice that  $m_h(0) = m_f(0) = 1$ . Calculating the derivatives of the two functions, we see that  $m'_h(0) = -4$  and  $m'_f(0) = -d$ . By continuity, since  $m'_h(0) > m'_f(0)$ ,  $m_h(\epsilon)$  must be greater than  $m_f(\epsilon)$  for small positive values of epsilon.

Since  $|h(z)| > |f(z)|$  for all  $z \in C_\epsilon$ ,  $g_d(z) = h(z) + f(z)$  must have the same number of roots within  $C_\epsilon$  as  $h(z)$ . The function  $h(z) = 3 - 4z$  has one root at  $z = 3/4$ . Therefore, for small positive  $\epsilon$ ,  $g_d(z)$  has a unique root inside the circle  $|z| = 1 - \epsilon$ , which must be the previously mentioned real root lying in the interval  $(3/4, 1)$ . Since this root has the smallest magnitude among roots of  $g_d(z)$ , the value of this root is the probability of ruin  $P_d$ .