## 1 Quick Review of wave equation on $\mathbb{R}$.

### 1.1 An example and Causality

The wave equation on the entire real line $x \in \mathbb{R}$ corresponds to a string of infinite length $h$
The wave equation then describes the dynamics of the amplitude $u(x, t)$ of the point at position $x$ on the string at time $t$, has the following form

$$
u_{t t}=c^{2} u_{x x},
$$

or

$$
\begin{equation*}
u_{t t}-c^{2} u_{x x}=0 \tag{1.1}
\end{equation*}
$$

The wave equation is hyperbolic. One can then rewrite this equation as

$$
\begin{equation*}
u_{\xi_{\eta}}=0 . \tag{1.2}
\end{equation*}
$$

To see this we pass to the characteristic variables as follows: let

$$
\left\{\begin{array}{l}
\xi=x+c t  \tag{1.3}\\
\eta=x-c t
\end{array}\right.
$$

To see that (1.2) is equivalent to (1.1), let us compute the partial derivatives of $u$ with respect to $x$ and $t$ in the new variables using the chain rule.

$$
\begin{aligned}
& u_{t}=c u_{\xi}-c u_{\eta}, \\
& u_{x}=u_{\xi}+u_{\eta} .
\end{aligned}
$$

We can differentiate the above first order partial derivatives with respect to $t$, respectively $x$ using the chain rule again, to get

$$
\begin{aligned}
& u_{t t}=c^{2} u_{\xi \xi}-2 c^{2} u_{\xi \eta}+c^{2} u_{\eta \eta}, \\
& u_{x x}=u_{\xi \xi}+2 u_{\xi \eta}+u_{\eta \eta} .
\end{aligned}
$$

[^0]Substituting these expressions into the left hand side of equation (??), we see that

$$
u_{t t}-c^{2} u_{x x}=c^{2} u_{\xi \xi}-2 c^{2} u_{\xi \eta}+c^{2} u_{\eta \eta}-c^{2}\left(u_{\xi \xi}+2 u_{\xi \eta}+u_{\eta \eta}\right)=-4 c^{2} u_{\xi \eta}=0,
$$

which is equivalent to (1.2).
Equation (1.2) can be treated as a pair of successive ODEs. Integrating first with respect to the variable $\eta$, and then with respect to $\xi$, we arrive at the solution

$$
u(\xi, \eta)=f(\xi)+g(\eta)
$$

Recalling the definition of the characteristic variables (1.3), we can switch back to the original variables $(x, t)$, and obtain the general solution

$$
\begin{equation*}
u(x, t)=f(x+c t)+g(x-c t) . \tag{1.4}
\end{equation*}
$$

Another way to solve equation (1.1) is to realize that the second order linear operator of the wave equation factors into two first order operators

$$
\mathcal{L}=\partial_{t}^{2}-c^{2} \partial_{x}^{2}=\left(\partial_{t}-c \partial_{x}\right)\left(\partial_{t}+c \partial_{x}\right) .
$$

Hence, the wave equation can be thought of as a pair of transport (advection) equations

$$
\begin{align*}
& \left(\partial_{t}-c \partial_{x}\right) v=0  \tag{1.5}\\
& \left(\partial_{t}+c \partial_{x}\right) u=v \tag{1.6}
\end{align*}
$$

It is no coincidence, of course, that

$$
\begin{equation*}
x+c t=\text { constant } \tag{1.7}
\end{equation*}
$$

and

$$
\begin{equation*}
x-c t=\text { constant }, \tag{1.8}
\end{equation*}
$$

are the characteristic lines for the transport equations (1.5), and (1.6) respectively, hence our choice of the characteristic coordinates (1.3). We also see that for each point in the $x t$ plane there are two distinct characteristic lines, each belonging to one of the two families (1.7) and (1.8), that pass through the point. This is illustrated in Figure 1.1 below.


Figure 1.1: Characteristic lines for the wave equation with $c=0.6$.

### 1.2 Initial value problem

Along with the wave equation (1.1), we next consider some initial conditions, to single out a particular physical solution from the general solution (1.4). The equation is of second order in time $t$, so values must be specified both for the initial dispalcement $u(x, 0)$, and the initial velocity $u_{t}(x, 0)$. We study the following initial value problem, or IVP

$$
\begin{cases}u_{t t}-c^{2} u_{x x}=0 & \text { for }-\infty<x<+\infty  \tag{1.9}\\ u(x, 0)=\phi(x), & u_{t}(x, 0)=\psi(x)\end{cases}
$$

where $\phi$ and $\psi$ are arbitrary functions of single variable, and together are called the initial data of the IVP. The solution to this problem is easily found from the general solution (1.4). All we need to do is find $f$ and $g$ from the initial conditions of the IVP (1.9). To check the first initial condition, set $t=0$ in (1.4),

$$
\begin{equation*}
u(x, 0)=\phi(x)=f(x)+g(x) . \tag{1.10}
\end{equation*}
$$

To check the second initial condition, we differentiate with respect to $t$, and set $t=0$

$$
\begin{equation*}
u_{t}(x, 0)=\psi(x)=c f^{\prime}(x)-c g^{\prime}(x) . \tag{1.11}
\end{equation*}
$$

Equations (1.10) and (1.11) can be treated as a system of two equations for $f$ and $g$. To solve this system, we first integrate both sides of (1.11) from 0 to $x$ to get rid of the derivatives on $f$ and $g$ (alternatively we could
differentiate 1.10) instead), and rewrite the equations as

$$
\begin{aligned}
& f(x)+g(x)=\phi(x), \\
& f(x)-g(x)=\frac{1}{c} \int_{0}^{x} \psi(s) d s+f(0)-g(0) .
\end{aligned}
$$

We can solve this system by adding the equations to eliminate $g$, snd subtracting them to eliminate $f$. This leads to the solution

$$
\begin{aligned}
& f(x)=\frac{1}{2} \phi(x)+\frac{1}{2 c} \int_{0}^{x} \psi(s) d s+\frac{1}{2}[f(0)-g(0)], \\
& g(x)=\frac{1}{2} \phi(x)-\frac{1}{2 c} \int_{0}^{x} \psi(s) d s-\frac{1}{2}[f(0)-g(0)] .
\end{aligned}
$$

Finally, substituting these expressions for $f$ and $g$ back into the solution (1.4), we obtain the solution of the IVP (1.9)

$$
u(x, t)=\frac{1}{2} \phi(x+c t)+\frac{1}{2 c} \int_{0}^{x+c t} \psi(s) d s+\frac{1}{2} \phi(x-c t)-\frac{1}{2 c} \int_{0}^{x-c t} \psi(s) d s .
$$

Combining the integrals using additivity, and the fact that flipping the integration limits changes the sign of the integral, we arrive at the following form for the solution

$$
\begin{equation*}
u(x, t)=\frac{1}{2}[\phi(x+c t)+\phi(x-c t)]+\frac{1}{2 c} \int_{x-c t}^{x+c t} \psi(s) d s \tag{1.12}
\end{equation*}
$$

This is called the d'Alambert's formula for the solution to the IVP (1.9). It implies that as long as $\phi$ is twice continuously differentiable $\left(\phi \in C^{2}\right)$, and $\psi$ is continuously differentiable $\left.\left(\psi \in C^{1}\right), 1.12\right)$ gives a solution to the IVP. We will also consider examples with discontinuous initial data, which after plugging into 1.12 produce weak solutions. This notion will be made precise in later lectures.

Example 1.1. Solve the initial value problem (1.9) with the initial data

$$
\phi(x) \equiv 0, \quad \psi(x)=\sin x .
$$

Substituting $\phi$ and $\psi$ into d'Alambert's formula, we obtain the solution

$$
u(x, t)=\frac{1}{2 c} \int_{x-c t}^{x+c t} \sin s d s=\frac{1}{2 c}(-\cos (x+c t)+\cos (x-c t)) .
$$

Using the trigonometric identities for the cosine of a sum and difference of two angles, we can simplify the above to get

$$
u(x, t)=\frac{1}{c} \sin x \sin (c t) .
$$

You should verify that this indeed solves the wave equation and satisfies the given initial conditions.

### 1.3 An Example

When solving the transport equation, we saw that the initial values simply travel to the right, when the speed is positive (they propagate along the characteristics 1.8) ; or to the left (they propagate along the characteristics (1.7)), when the speed is negative. Since the wave equation is made up of two of these type of equations, we expect similar behavior for the solutions of the IVP (1.9) as well. To see this, let us consider the following example with simplified initial data.

Example 1.2. Find the solution of IVP (1.9), with the initial data

$$
\begin{align*}
& \phi(x)=\left\{\begin{array}{rr}
h, & |x| \leq a, \\
0, & |x|>a,
\end{array}\right.  \tag{1.13}\\
& \psi(x) \equiv 0 .
\end{align*}
$$

This data corresponds to an initial disturbance of the string centered at $x=0$ of height $h$, and zero initial velocity. Notice that $\phi(x)$ is not continuous, let alone twice differentiable, though one can still substitute it into d'Alambert's solution (1.12) and get a function $u$, which will be a weak solution of the wave equation.

Since $\psi(x) \equiv 0$, only the first term in (1.12) is nonzero. We compute this term using the particular $\phi(x)$ in (1.13). First notice that

$$
\phi(x+c t)= \begin{cases}h, & |x+c t| \leq a  \tag{1.14}\\ 0, & |x+c t|>a\end{cases}
$$

and

$$
\phi(x-c t)= \begin{cases}h, & |x-c t| \leq a  \tag{1.15}\\ 0, & |x-c t|>a\end{cases}
$$

Hence, the solution

$$
u(x, t)=\frac{1}{2}[\phi(x+c t)+\phi(x-c t)]
$$

is piecewise defined in 4 different regions in the xt half-plane (we consider only positive time $t \geq 0$ ), which correspond to pairings of the intervals in the expressions 1.14) and 1.15). These regions are

$$
\begin{array}{cll}
I: & \{|x+c t| \leq a,|x-c t| \leq a\}, & u(x, t)=h \\
I I: & \{|x+c t| \leq a,|x-c t|>a\}, & u(x, t)=\frac{h}{2}  \tag{1.16}\\
I I I: & \{|x+c t|>a,|x-c t| \leq a\}, & u(x, t)=\frac{h}{2} \\
I V: & \{|x+c t|>a,|x-c t|>a\}, & u(x, t)=0
\end{array}
$$

The regions are depicted in Figure 1.2. Notice that $|x+c t| \leq a$ is equivalent to

$$
-a \leq x+c t \leq a, \quad \text { or } \quad-\frac{1}{c}(x+a) \leq t \leq-\frac{1}{c}(x-a) .
$$

Similarly for the other inequalities.


Figure 1.2: Regions where $u$ has different values.

Using the values for the solution in (1.16), we can draw the graph of $u$ at different times, some of which are depicted in Figures 1.3 1.6.

We see that the initial box-like disturbance centered at $x=0$ splits into two disturbances of half the size, which travel in opposite directions with speed $c$.

The graphs hint that the initial disturbance will not be felt at a point $x$ on the string (for $|x|>a$ ) before the time $t=\frac{1}{c}| | x|-a|$. We will shortly see that this is a general property for the wave equation. In this particular case a box-like disturbance appears at the time $t=\frac{1}{c}| | x|-a|$, and lasts exactly $t=\frac{2 a}{c}$ units of time, after which
it completely moves along. In general, the initial velocity may slow down the speed, and subsequently make the disturbance "last" longer, however, the speed cannot exceed c.


Figure 1.3: The solution at $t=0$.


Figure 1.5: The solution at $t=a / c$.


Figure 1.4: The solution for $0<t<a / c$.


Figure 1.6: The solution for $t>a / c$.

### 1.4 Causality

The value of the solution to the IVP (1.9) at a point $\left(x_{0}, t_{0}\right)$ can be found from d'Alambert's formula 1.12 )

$$
\begin{equation*}
u\left(x_{0}, t_{0}\right)=\frac{1}{2}\left[\phi\left(x_{0}+c t_{0}\right)+\phi\left(x_{0}-c t_{0}\right)\right]+\frac{1}{2 c} \int_{x_{0}-c t_{0}}^{x_{0}+c t_{0}} \psi(s) d s \tag{1.17}
\end{equation*}
$$

We can see that this value depends on the values of $\phi$ at only two points on the $x$ axis, $x_{0}+c t_{0}$, and $x_{0}-c t_{0}$, and the values of $\psi$ only on the interval $\left[x_{0}-c t_{0}, x_{0}+c t_{0}\right]$. For this reason the interval $\left[x_{0}-c t_{0}, x_{0}+c t_{0}\right]$ is called interval of dependence for the point $\left(x_{0}, t_{0}\right)$. The triangular region with vertices at $x_{0}-c t_{0}$ and $x_{0}+c t_{0}$ on the $x$ axis and the vertex $\left(x_{0}, t_{0}\right)$ is called the domain of dependence, or the past history of the point $\left(x_{0}, t_{0}\right)$, as depicted in Figure 1.7. The sides of this triangle are segments of characteristic lines passing through the point $\left(x_{0}, t_{0}\right)$. Thus, we see that the initial data travels along the characteristics to give the values at later times. In the previous example of the box wave, we saw that the jump discontinuities travel along the characteristic lines as well.


Figure 1.7: Domain of dependence for $\left(x_{0}, t_{0}\right)$.


Figure 1.8: Domain of influence of $x_{0}$.

An inverse notion to the domain of dependence is the notion of domain of influence of the point $x_{0}$ on the $x$ axis. This is the region in the $x t$ plane consisting of all the points, whose domain of dependence contains the point $x_{0}$. The region has an upside-down triangular shape, with the sides being the characteristic lines emanating from the point $x_{0}$, as shown in Figure 1.8. This also means that the value of the initial data at the point $x_{0}$ effects the values of the solution $u$ at all the points in the domain of influence. Notice that at a fixed time $t_{0}$, only the points satisfying $x_{0}-c t_{0} \leq x \leq x_{0}+c t_{0}$ are influenced by the point $x_{0}$ on the $x$ axis.

Example 1.3 (The hammer blow). Analyze the solution to the IVP (1.9) with the following initial data

$$
\begin{align*}
& \phi(x) \equiv 0, \\
& \psi(x)= \begin{cases}h, & |x| \leq a, \\
0, & |x|>a .\end{cases} \tag{1.18}
\end{align*}
$$

From d'Alambert's formula 1.12, we obtain the following solution

$$
\begin{equation*}
u(x, t)=\frac{1}{2 c} \int_{x-c t}^{x+c t} \psi(s) d s \tag{1.19}
\end{equation*}
$$

Similar to the previous example of the box wave, there are several regions in the xt plane, in which $u$ has different values. Indeed, since the initial velocity $\psi(x)$ is nonzero only in the interval $[-a, a]$, the integral in (1.19) must be computed differently according to how the intervals $[-a, a]$ and $[x-c t, x+c t]$ intersect. This corresponds to the cases when $\psi$ is zero on the entire integration interval in (1.19), on a part of it, or is nonzero on the entire
integration interval. These different cases are:

$$
\begin{array}{rll}
\text { I: } & \{x-c t<x+c t<-a<a\}, & u(x, t)=0 \\
\text { II: } & \{x-c t<-a<x+c t<a\}, & u(t, x)=\frac{1}{2 c} \int_{-a}^{x+c t} h d s=h \frac{x+c t+a}{2 c} \\
\text { III: } & \{x-c t<-a<a<x+c t\}, & u(t, x)=\frac{1}{2 c} \int_{-a}^{a} h d s=h \frac{a}{c}  \tag{1.20}\\
\text { IV: } & \{-a<x-c t<x+c t<a\}, & u(t, x)=\frac{1}{2 c} \int_{x-c t}^{x+c t} h d s=h t \\
\text { V: } & \{-a<x-c t<a<x+c t\}, & u(t, x)=\frac{1}{2 c} \int_{x-c t}^{a} h d s=h \frac{a-(x-c t)}{2 c} \\
\text { VI: } & \{-a<a<x-c t<x+c t\}, & u(x, t)=0
\end{array}
$$

The regions are depicted in Figure 1.9 below. Notice that to find the value of the solution at a point $\left(x_{0}, t_{0}\right)$, one simply needs to trace the point back to the $x$ axis along the characteristic lines, and determine how the interval of dependence intersects the segment $[-a, a]$.


Figure 1.9: Regions where $u$ has different values.

### 1.5 Conclusion

The wave equation, being a constant coefficient second order PDE of hyperbolic type, posseses two families of characteristic lines, which correspond to constant values of respective characteristic variables. Using these variables the equation can be treated as a pair of successive ODEs, integrating which leads to the general solution. This general solution was used to arrive at d'Alambert's solution (1.12) for the IVP on the whole line. Unfortunately this simple derivation relies on having two families of characteristics and does not work for the heat and Laplace's equations.

Exploring a few examples of initial data, we established causality between the initial data and the values of the solution at later times. In particular, we saw that the initial values travel with speeds bounded by the wave speed $c$, and that the discontinuities of the initial data travel along the characteristic lines.


[^0]:    ${ }^{1}$ Although physically unrealistic, as we will see later, when considering the dynamics of a portion of the string away from the endpoints, the boundary conditions have no effect for some (nonzero) finite time. Due to this, one can neglect the endpoints, and make the assumption that the string is infinite.

