

Name: _____

1. (15 points) a) Show that the row **reduced** echelon form of the augmented matrix of the system

$$x_1 + x_2 + x_3 + 2x_4 + 3x_5 = 4$$

$$x_2 - x_3 + x_4 + x_5 = 4$$

$$2x_1 + 4x_3 + 3x_4 + 5x_5 = 2$$

is $\begin{pmatrix} 1 & 0 & 2 & 0 & 1 & -2 \\ 0 & 1 & -1 & 0 & 0 & 2 \\ 0 & 0 & 0 & 1 & 1 & 2 \end{pmatrix}$. Use at most five elementary operations. Show all your work. Clearly write in words each elementary row operation you used.

- b) Find the general solution for the system.

2. (20 points) You are given that the row reduced echelon form of the matrix

$$A = \begin{pmatrix} 1 & 0 & 2 & 0 & 1 & 0 \\ 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & 1 & -1 & 2 & 0 & 4 \\ 1 & 0 & 2 & -1 & 2 & 0 \end{pmatrix} \text{ is } B = \begin{pmatrix} 1 & 0 & 2 & 0 & 0 & -2 \\ 0 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{pmatrix}. \text{ You do **not** need to verify this statement.}$$

(a) Write the general solutions of the system $A\vec{x} = \vec{0}$ in parametric form $\vec{x} = (\text{first free variable})\vec{v}_1 + (\text{second free variable})\vec{v}_2 + \dots$

(b) Let $T : \mathbb{R}^6 \rightarrow \mathbb{R}^4$ be the linear transformations given by $T(\vec{x}) = A\vec{x}$. Find a basis for the kernel $\ker(T)$. In other words, find a linearly independent set of vectors in $\ker(T)$, which spans $\ker(T)$. Explain why the set you found is linearly independent, and why it spans $\ker(T)$.

(c) For each vector in the basis you found in part 2b, write down a corresponding linear relation among the columns of the original matrix A (use the notation a_i for the i -th column). Then use each of these relations to find a redundant vector among the columns of A (i.e., a column vector \vec{a}_i , which is a linear combination of the preceding columns $\vec{a}_1, \dots, \vec{a}_{i-1}$).

(d) Is the image of T equal to the whole of \mathbb{R}^4 ? Justify your answer.

3. (a) (7 points) Let A, B, C be $n \times n$ matrices, with A invertible, which satisfy the equation $A(C + I_n)A^{-1} = B$, where I_n is the $n \times n$ identity matrix. Express C in terms of A and B . Show all your work.

- (b) (8 points) Let A be an $n \times n$ matrix satisfying $A^3 + 5A^2 + 2A - I_n = 0$, where 0 is the $n \times n$ matrix all of which entries are zero. Show that A is invertible and express A^{-1} in terms of A .

Hint: Rewrite the equation as $A^3 + 5A^2 + 2AI_n - I_n = 0$.

4. (15 points) Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ be a linear transformation with standard matrix

A. Assume that there exists a unique vector \vec{x} in \mathbb{R}^3 , such that $T(\vec{x}) = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix}$.

Carefully **justify** your answers to the following questions.

- (a) The rank of A is: ____.

- (b) Describe geometrically the kernel of T .

(c) Is it true that the equation $A\vec{x} = \vec{y}$ has a unique solution \vec{x} , for every vector \vec{y} in \mathbb{R}^4 ? Justify!

5. (a) (8 points) Find the inverse of the matrix $A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 0 \\ 1 & 2 & 4 \end{pmatrix}$.

(b) (7 points) Find the set of all matrices B , satisfying the matrix equation $BA = \begin{pmatrix} 1 & 0 & -1 \\ 1 & 1 & 1 \end{pmatrix}$.

6. (20 points) Let L_θ be the line in \mathbb{R}^2 through the origin and the unit vector $\vec{u} = \begin{pmatrix} \cos(\theta) \\ \sin(\theta) \end{pmatrix}$. Recall that the reflection $Ref_{L_\theta} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ of the plane about the line L_θ is given by the formula $Ref_{L_\theta}(\vec{x}) = 2(\vec{u} \cdot \vec{x})\vec{u} - \vec{x}$.

(a) Use the algebraic properties of the dot product to show that Ref_{L_θ} is a linear transformation. In other words, verify the following identities, for any two vectors \vec{v}, \vec{w} and for every scalar k .

i. $Ref_{L_\theta}(\vec{v} + \vec{w}) = Ref_{L_\theta}(\vec{v}) + Ref_{L_\theta}(\vec{w})$.

ii. $Ref_{L_\theta}(k\vec{v}) = kRef_{L_\theta}(\vec{v})$.

(b) Use the above formula for $Ref_{L_\theta}(\vec{x})$ to show that the standard matrix A of Ref_{L_θ} is $A = \begin{pmatrix} \cos(2\theta) & \sin(2\theta) \\ \sin(2\theta) & -\cos(2\theta) \end{pmatrix}$. Hint: Recall the identities:
 $\cos^2(\theta) + \sin^2(\theta) = 1$, $\cos(2\theta) = \cos^2(\theta) - \sin^2(\theta)$, $\sin(2\theta) = 2\cos(\theta)\sin(\theta)$.

- (c) Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the composition $T(\vec{x}) = Ref_{L_\phi}(Ref_{L_\theta}(\vec{x}))$, where L_ϕ is the line through the origin and $\vec{w} = \begin{pmatrix} \cos(\phi) \\ \sin(\phi) \end{pmatrix}$. Express the standard matrix C of T in terms of the standard matrices A of Ref_{L_θ} and B of Ref_{L_ϕ} : $C = \underline{\hspace{2cm}}$.

Use this expression to show the equality $C = \begin{pmatrix} \cos(2\phi - 2\theta) & -\sin(2\phi - 2\theta) \\ \sin(2\phi - 2\theta) & \cos(2\phi - 2\theta) \end{pmatrix}$.

Hint: Recall the identities $\cos(\alpha - \beta) = \cos(\alpha)\cos(\beta) + \sin(\alpha)\sin(\beta)$ and $\sin(\alpha - \beta) = \sin(\alpha)\cos(\beta) - \cos(\alpha)\sin(\beta)$.

- (d) The linear transformation T in part 6c is described more directly as the rotation of the plane about the origin an angle $\underline{\hspace{2cm}}$ counterclockwise. **Justify** your answer.