

1. Let V be a vector space. Consider linearly independent vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ in a subspace H of V and vectors $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_q$ that span H . Show that there is a basis of H that consists of all the \vec{v}_i and some of the \vec{w}_j . Hint: Use the Spanning Set Theorem 5 in section 4.3.

Consider the ordered set $S = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_{p+q}\}$, where $\vec{u}_i = \vec{v}_i$, if $1 \leq i \leq p$, and $\vec{u}_{p+j} = \vec{w}_j$, $1 \leq j \leq q$.

If the set $\{\vec{u}_1, \dots, \vec{u}_{p+q}\}$ is not linearly independent, then one \vec{u}_k is a linear combination of the preceding vectors $\vec{u}_1, \dots, \vec{u}_{k-1}$, for some $k > p$ (since $\vec{u}_1, \dots, \vec{u}_p$ is linearly independent). In that case we call \vec{u}_k a redundant vector and $H = \text{Span } S = \text{Span } (S \setminus \{\vec{u}_k\})$. Repeating

since S contains $\{\vec{v}_1, \dots, \vec{v}_p\}$

by the Spanning Set Theorem

the process with $S \setminus \{\vec{u}_k\}$ until all redundant vectors were discarded we arrive at a linearly independent set $\{\vec{u}_1, \dots, \vec{u}_p, \vec{u}_{i_1}, \dots, \vec{u}_{i_m}\}$, with $p < i_t \leq p+q$

which spans H . It is thus a basis for H of the desired property, since $\vec{u}_{i_t} = \vec{w}_{(i_t - p)}$.

2. Let G and H be subspaces of a vector space V .

(a) The intersection $G \cap H$ is the subset of V consisting of vectors that belong to both G and H . Show that $G \cap H$ is a subspace of V .

- (1) $G \cap H$ contains $\vec{0}$, since both G and H do being subspaces.
- (2) Let \vec{u}, \vec{v} be vectors in $G \cap H$, Then $\vec{u} + \vec{v}$ belong to G , since G is a subspace, and to H , for the same reason, hence to $G \cap H$.
- (3) Let \vec{u} be a vector in $G \cap H$, and c a scalar. Then $c\vec{u}$ belong to G , since G is a subspace, and to H , for the same reason, hence to $G \cap H$.

(b) The sum $G + H$ is the subset of V consisting of sums of vectors $\vec{g} + \vec{h}$, where \vec{g} belongs to G and \vec{h} belongs to H . Show that $G + H$ is a subspace of V .

- (1) $\vec{0} = \vec{0} + \vec{0}$, and $\vec{0}$ belongs to G and to H . Hence $\vec{0}$ belongs to $G + H$.
- (2) Let \vec{u}, \vec{v} be vectors in $G + H$. Then $\vec{u} = \vec{g}_1 + \vec{h}_1$ and $\vec{v} = \vec{g}_2 + \vec{h}_2$, for \vec{g}_i in G and \vec{h}_i in H , $i=1,2$. So $\vec{u} + \vec{v} = (\vec{g}_1 + \vec{g}_2) + (\vec{h}_1 + \vec{h}_2)$ and $\vec{g}_1 + \vec{g}_2$ belongs to G , since G is a subspace, and $\vec{h}_1 + \vec{h}_2$ belongs to H for the same reason. Hence $\vec{u} + \vec{v}$ belongs to $G + H$.
- (3) Let $\vec{u} = \vec{g} + \vec{h}$ be a vector in $G + H$, with \vec{g} in G and \vec{h} in H , and let c be a scalar. Then $c\vec{g}$ belongs to G , $c\vec{h}$ belongs to H , since G and H are subspaces. Thus $c\vec{u} = c\vec{g} + c\vec{h}$ belongs to $G + H$.

(c) Let $\{v_1, \dots, v_p\}$ be a linearly independent subset of V and k an integer satisfying $1 \leq k < p$. Show that $\underbrace{\text{span}\{v_1, v_2, \dots, v_k\}}_G \cap \underbrace{\text{span}\{v_{k+1}, \dots, v_{p-1}, v_p\}}_H$ is the zero subspace of V .

We already know that $G \cap H$ is a subspace, by Part (b).

Suppose \vec{v} is in $G \cap H$. Then $\vec{v} = c_1 \vec{v}_1 + \dots + c_k \vec{v}_k$ and

$$\vec{v} = c_{k+1} \vec{v}_{k+1} + \dots + c_p \vec{v}_p. \text{ So } \vec{0} = \vec{v} - \vec{v} = c_1 \vec{v}_1 + \dots + c_k \vec{v}_k - c_{k+1} \vec{v}_{k+1} - \dots - c_p \vec{v}_p$$

Hence, $c_i = 0$, for $1 \leq i \leq p$, since $\{v_1, \dots, v_p\}$ is linearly independent. So $\vec{v} = \vec{0}$.

x_2, x_4 free

(d) Let $A = \begin{pmatrix} 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$. Find a basis for $\text{Null}(A)$, $\text{Col}(A)$, $\text{Null}(A) \cap \text{Col}(A)$, and $\text{Null}(A) + \text{Col}(A)$.

Null(A): $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_4 \\ -x_4 \\ x_4 \end{pmatrix} = x_2 \underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}}_{v_1} + x_4 \underbrace{\begin{pmatrix} 0 \\ 1 \\ -1 \\ 1 \end{pmatrix}}_{v_2}$

$\{v_1, v_2\}$ is a basis for $\text{Null}(A)$.

The pivot columns (2nd and third) of A are a basis for $\text{Col}(A)$, namely $\left\{ \underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}}_{v_1}, \underbrace{\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}}_{v_3} \right\}$

Null(A) \cap Col(A): If \vec{v} is in $\text{Null}(A) \cap \text{Col}(A)$, then $\vec{v} = a_1 v_1 + a_2 v_2$ and $\vec{v} = b_1 v_1 + b_3 v_3$.

So $\vec{0} = (a_1 - b_1) \vec{v}_1 + a_2 \vec{v}_2 + b_3 \vec{v}_3$. But $\underbrace{\{v_1, v_2, v_3\}}_{\text{the set}}$ is linearly independent. So $a_1 = b_1$, $a_2 = 0$, and $b_3 = 0$, and so $\vec{v} = a_1 v_1$ belongs to $\text{span}\{v_1\}$. So $\{v_1\}$ is a basis for $\text{Null}(A) \cap \text{Col}(A)$.

Null(A) + Col(A): Let $\vec{v} = \vec{u} + \vec{w}$, where \vec{u} is in $\text{Null}(A)$ and \vec{w} is in $\text{Col}(A)$. Then $\vec{u} = a_1 v_1 + a_2 v_2$ and $\vec{w} = b_1 v_1 + b_3 v_3$. So $\vec{v} = (a_1 + b_1) v_1 + a_2 v_2 + b_3 v_3$. So \vec{v} belongs to $\text{span}\{v_1, v_2, v_3\}$. Conversely, if \vec{v} belongs to $\text{span}\{v_1, v_2, v_3\}$ then $\vec{v} = (c_1 v_1 + c_2 v_2) + c_3 v_3$, with $(c_1 v_1 + c_2 v_2)$ in $\text{Null}(A)$ and $c_3 v_3$ in $\text{Col}(A)$. So \vec{v} is in $\text{Null}(A) + \text{Col}(A)$. Thus, $\text{Null}(A) + \text{Col}(A) = \text{span}\{v_1, v_2, v_3\}$. Since $\{v_1, v_2, v_3\}$ is linearly independent, it is a basis for $\text{Null}(A) + \text{Col}(A)$.

3. Let G and H be finite dimensional subspaces of a vector space V . Show that

$$(†) \quad \dim(G) + \dim(H) = \dim(G \cap H) + \dim(G + H).$$

Hint: Let $\vec{v}_1, \dots, \vec{v}_m$ be a basis of $G \cap H$. Using problem 1 extend it to a basis $\vec{v}_1, \dots, \vec{v}_m, \vec{g}_1, \dots, \vec{g}_p$ of G and a basis $\vec{v}_1, \dots, \vec{v}_m, \vec{h}_1, \dots, \vec{h}_q$ of H . Show that

$$(*) \quad \vec{v}_1, \dots, \vec{v}_m, \vec{g}_1, \dots, \vec{g}_p, \vec{h}_1, \dots, \vec{h}_q$$

is a basis of $G + H$. Hint: For the proof of linear independence, assume that $a_1\vec{v}_1 + \dots + a_m\vec{v}_m + b_1\vec{g}_1 + \dots + b_p\vec{g}_p + c_1\vec{h}_1 + \dots + c_q\vec{h}_q \stackrel{(**)}{=} 0$. Show first that $c_1\vec{h}_1 + \dots + c_q\vec{h}_q$ belongs to $G \cap H$ and use it to prove that $b_j = 0, 1 \leq j \leq p$.

If $(*)$ is a basis for $G+H$, then $\dim(G+H) = m+p+q$
 $\dim(G) = m+p$
 $\dim(H) = m+q$
 $\dim(G \cap H) = m$, so Eq (†) holds.

Proof that the set $(*)$ is linearly independent:

Assume $(**)$. Then $c_1\vec{h}_1 + \dots + c_q\vec{h}_q$ both belongs to H and equal to $-(a_1\vec{v}_1 + \dots + a_m\vec{v}_m + b_1\vec{g}_1 + \dots + b_p\vec{g}_p)$ which belongs to G . Hence, $c_1\vec{h}_1 + \dots + c_q\vec{h}_q$ belongs to $G \cap H$ and is thus a linear comb $d_1\vec{v}_1 + \dots + d_m\vec{v}_m$ of its basis. So,

$$\vec{0} = \text{left hand side of } (***) = (a_1 + d_1)\vec{v}_1 + \dots + (a_m + d_m)\vec{v}_m + b_1\vec{g}_1 + \dots + b_p\vec{g}_p.$$

Hence, $b_i = 0$, for $1 \leq i \leq p$. Interchanging the roles of G and H we get that $c_i = 0$, for $1 \leq i \leq q$.

Hence, $\vec{0} = a_1\vec{v}_1 + \dots + a_m\vec{v}_m$. So $a_i = 0$, for $0 \leq i \leq m$.

Since $\{\vec{v}_1, \dots, \vec{v}_m\}$ is linearly independent.

Proof that $(*)$ spans: Let $v \in G+H$. Then $v = g+h$, where g is in G and h is in H . So $g = \sum_{i=1}^m a_i \vec{v}_i + \sum_{i=1}^p b_i \vec{g}_i$ and $h = \sum_{i=1}^m c_i \vec{v}_i + \sum_{i=1}^q d_i \vec{h}_i$.

Thus $v = \sum_{i=1}^m (a_i + c_i) \vec{v}_i + \sum_{i=1}^p b_i \vec{g}_i + \sum_{i=1}^q d_i \vec{h}_i$ is a linear

combination of the vectors in $(*)$.



4. If G and H are subspaces of \mathbb{R}^{10} , with $\dim(G) = 6$ and $\dim(H) = 7$, what are the possible dimensions of $G \cap H$? Hint: Use problem 3.

$$\underbrace{\dim(G) + \dim(H)}_{\substack{\parallel \\ 6 \quad 7 \\ \underbrace{\hspace{2cm}} \\ 13}} = \dim(G \cap H) + \underbrace{\dim(G+H)}_{\substack{\wedge \\ \dim(\mathbb{R}^{10}) = 10}}$$

So $\dim(G \cap H) \geq 13 - 10 = 3$.

$G \cap H$ is a subspace of G , so $\dim(G \cap H) \leq 6$.
 We get that $3 \leq \dim(G \cap H) \leq 6$. We show next that all four possibilities are possible:

Let $\{e_1, \dots, e_{10}\}$ be the standard basis of \mathbb{R}^{10} ,

and let $H = \text{Span}\{e_1, \dots, e_7\}$.

If $G = \text{Span}\{e_1, \dots, e_6\}$ then $G \cap H = G$ and $\dim(G \cap H) = 6$.

If $G = \text{Span}\{e_1, e_2, e_3, e_4, e_5, e_8\}$, then $G \cap H = \text{Span}\{e_1, e_2, e_3, e_4, e_5\}$
 and $\dim(G \cap H) = 5$.

If $G = \text{Span}\{e_1, e_2, e_3, e_4, e_8, e_9\}$, then $G \cap H = \text{Span}\{e_1, e_2, e_3, e_4\}$
 and $\dim(G \cap H) = 4$.

If $G = \text{Span}\{e_1, e_2, e_3, e_8, e_9, e_{10}\}$, then
 $G \cap H = \text{Span}\{e_1, e_2, e_3\}$ and $\dim(G \cap H) = 3$.

Q.E.D

5 Let $T: V \rightarrow W$ be a linear transformation, $\mathcal{B} = \{v_1, \dots, v_n\}$ a basis for V , and $\mathcal{C} = \{w_1, \dots, w_m\}$ a basis for W . Let $[\]_{\mathcal{C}}: W \rightarrow \mathbb{R}^m$ be the linear coordinate transformation of Theorem 8 in Section 4.4 of our textbook. Let $S: \mathbb{R}^n \rightarrow V$ be

the linear transformation sending the vector $\begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$ to $c_1v_1 + c_2v_2 + \dots + c_nv_n$.

Note that S is the inverse of $[\]_{\mathcal{B}}$.

(a) By definition, the composite linear transformation $[\]_{\mathcal{C}} \circ T \circ S: \mathbb{R}^n \rightarrow \mathbb{R}^m$ maps \vec{x} to $[T(S(\vec{x}))]_{\mathcal{C}}$. It fits in the diagram:

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \uparrow S & & \downarrow [\]_{\mathcal{C}} \\ \mathbb{R}^n & \xrightarrow{[\]_{\mathcal{C}} \circ T \circ S} & \mathbb{R}^m \end{array}$$

the standard matrix of $[\]_{\mathcal{C}} \circ T \circ S: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is the $m \times n$ matrix

$$A = ([T(v_1)]_{\mathcal{C}} [T(v_2)]_{\mathcal{C}} \dots [T(v_n)]_{\mathcal{C}}),$$

which j -th column is $[T(v_j)]_{\mathcal{C}}$. Hint: Compute A column by column. Note: The matrix A is considered in Theorem 15 of Section 4.7 of our textbook only in the special case where $V = W$. When $V = W$ and $\mathcal{B} = \mathcal{C}$ we will call A the \mathcal{B} -matrix of T .

Write $A = (\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n)$ where \vec{a}_j is the j -th column of A . We know that $A\vec{x} = [T(S(\vec{x}))]_{\mathcal{C}}$, for every \vec{x} in \mathbb{R}^n , by definition of A . Let \vec{e}_j be the j -th column of I , the $n \times n$ identity matrix.

$$\vec{a}_j = A\vec{e}_j = [T(S(\vec{e}_j))]_{\mathcal{C}} = [T(\underbrace{\vec{e}_j}_{\vec{v}_j})]_{\mathcal{C}},$$

- (b) Show that the coordinate linear transformation $[\]_B$ maps $\ker(T)$ onto $\text{Null}(A)$. In other words, show that if $T(v) = 0$, then $[v]_B$ belongs to $\text{Null}(A)$ and if $A\vec{x} = \vec{0}$, then $\vec{x} = [v]_B$, for some vector v in $\ker(T)$. Conclude that $\dim(\ker(T)) = \dim(\text{Null}(A))$.

The equation $A\vec{x} = [T(S(\vec{x}))]_e$ for all \vec{x} in \mathbb{R}^n implies that $A[\vec{v}]_B \stackrel{(+)}{=} [T(\vec{v})]_e$, for all \vec{v} in V .
Indeed, take $\vec{x} = [\vec{v}]_B$ and use the fact that $S([\vec{v}]_B) = \vec{v}$.

If \vec{v} is in $\ker(T)$, then $T(\vec{v}) = \vec{0}$, so $[T(\vec{v})]_e = \vec{0}$, so $A[\vec{v}]_B = \vec{0}$, by equation (+), so $[\vec{v}]_B$ is in $\text{Null}(A)$.

Let $\vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix}$ be in $\text{Null}(A)$, and set $\vec{v} = x_1\vec{v}_1 + \dots + x_m\vec{v}_m$, so that $[\vec{v}]_B = \vec{x}$.

Then $[T(\vec{v})]_e \stackrel{\text{by (+)}}{=} A[\vec{v}]_B = A\vec{x} = \vec{0}$. Hence, the e -coordinate vector of $T(\vec{v})$ is zero. So $T(\vec{v}) = \vec{0}$. So \vec{v} is in $\ker(T)$ and $\vec{x} = [\vec{v}]_B$. Hence $[\]_B$ maps $\ker(T)$ ONTO $\text{Null}(A)$.

Let $F: \ker(T) \rightarrow \text{Null}(A)$ be given by $F(\vec{v}) = [\vec{v}]_B$. Then F is a linear transformation, since $[\]_B$ is, F is one-to-one, since $[\]_B$ is, and F is onto, as was shown above.

So F translates every linear algebra statement on $\ker(T)$ to one on $\text{Null}(A)$ (see the paragraph in Sec 4.4 before Example 5 in the text). In particular, F maps a linearly independent set to a linearly independent set.

Furthermore, F maps a set that spans $\ker(T)$ to a set that spans $\text{Null}(A)$. So if $\{u_1, u_2\}$ is a basis for $\ker(T)$, then $\{[u_1]_B, [u_2]_B\}$ is a basis for $\text{Null}(A)$. Thus $\dim(\ker(T)) = \dim(\text{Null}(A)) = 2$.

$$\begin{array}{ccc}
 V & \xrightarrow{T} & W \supset \text{Im}(T) \\
 \downarrow []_B & & \downarrow []_C \\
 \mathbb{R}^m & \xrightarrow{A} & \mathbb{R}^m \supset \text{Col}(A)
 \end{array}$$

(c) Show that $[]_C$ maps the image $\text{Im}(T)$ onto $\text{Col}(A)$. Conclude that $\dim(\text{Im}(T)) = \dim(\text{Col}(A))$.

Let \vec{w} be a vector in $\text{Im}(T) = \{T(\vec{v}) \text{ such that } \vec{v} \text{ is in } V\}$.

Then $\vec{w} = T(\vec{v})$ for some \vec{v} in V . So

$$[\vec{w}]_C = [T(\vec{v})]_C = A [\vec{v}]_B. \text{ Now } A\vec{x} \text{ is in } \text{Col}(A) \text{ for}$$

every \vec{x} in \mathbb{R}^m . Hence $[\vec{w}]_C$ is in $\text{Col}(A)$.

Conversely, let \vec{y} be a vector in $\text{Col}(A)$, $\vec{y} = \sum_{j=1}^m x_j \vec{a}_j$

Then $\vec{y} = A\vec{x}$, for $\vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix}$ in \mathbb{R}^m . So

$$\vec{y} = A \left[\sum_{j=1}^m x_j \vec{v}_j \right]_B = [T(\sum_{j=1}^m x_j \vec{v}_j)]_C, \text{ so}$$

$$\vec{y} = [\vec{w}]_C \text{ where } \vec{w} = T\left(\sum_{j=1}^m x_j \vec{v}_j\right) \text{ is in } \text{Im}(T),$$

Hence $[]_C$ maps $\text{Im}(T)$ onto $\text{Col}(A)$.

Let $F: \text{Im}(T) \rightarrow \text{Col}(A)$ be given by $F([\vec{y}]) = \vec{y}$.

Then F is a one-to-one and onto linear transformation.

Hence, $\dim \text{Im}(T) = \dim \text{Col}(A)$, by the argument in part b.

(d) Generalize the Rank-Nullity Theorem by proving the following equality $\dim(\text{Im}(T)) + \dim(\ker(T)) = \dim(V)$.

$$\begin{array}{ccc}
 \underbrace{\hspace{10em}} & & \underbrace{\hspace{10em}} \\
 \boxed{\text{Part c}} // & & \boxed{\text{Part b}} \\
 \dim(\text{Col}(A)) & & \dim(\text{Null}(A))
 \end{array}$$

$$\begin{aligned}
 \dim(\text{Im}(T)) + \dim(\ker(T)) &= \dim(\text{Col}(A)) + \dim(\text{Null}(A)) \stackrel{\uparrow}{=} \\
 &= m = \dim(V).
 \end{aligned}$$

by the Rank-Nullity Theorem

6

Let $M_{2 \times 2}$ be the vector space of 2×2 matrices (with the usual scalar multiplication and addition of matrices). Consider the following basis of $M_{2 \times 2}$.

$$B = \left\{ \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}_{E_{11}}, \underbrace{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}_{E_{12}}, \underbrace{\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}}_{E_{21}}, \underbrace{\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}}_{E_{22}} \right\}.$$

Let $C = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$. Let $T: M_{2 \times 2} \rightarrow M_{2 \times 2}$ be given by $T(B) = BC - CB$.

(a) Show that T is a linear transformation. (1) Let B, M be 2×2 matrices

$$\begin{aligned} T(B+M) &= (B+M)C - C(B+M) = (BC - CB) + (MC - CM) = \\ &= T(B) + T(M). \end{aligned}$$

(2) Let λ be a scalar and B a 2×2 matrix. Then

$$T(\lambda B) = (\lambda B)C - C(\lambda B) = \lambda[BC - CB] = \lambda T(B).$$

(b) Compute the B -matrix of T (as in Problem 8, but with $V = W = M_{2 \times 2}$ and take C to be equal to the specific basis B given above).

$M_{2 \times 2} \xrightarrow{T} M_{2 \times 2}$
 $\downarrow []_B \quad \downarrow []_B$
 $\mathbb{R}^4 \xrightarrow{\text{mult by } A} \mathbb{R}^4$
 We will show that
 $A = \begin{pmatrix} 0 & 1 & -1 & 0 \\ 1 & 1 & 0 & -1 \\ -1 & 0 & -1 & 1 \\ 0 & -1 & 1 & 0 \end{pmatrix}$
 is the standard matrix of T .

Part 8a

$$\vec{a}_1 = [T(E_{11})]_B = \left[\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} C - C \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right]_B = \left[\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} \right]_B = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}$$

$$\vec{a}_2 = [T(E_{12})]_B = \left[\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} C - C \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right]_B = \left[\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \right]_B = \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix}$$

$$\vec{a}_3 = [T(E_{21})]_B = \left[\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} C - C \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right]_B = \left[\begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 2 & 0 \end{pmatrix} \right]_B = \begin{pmatrix} -1 \\ 0 \\ -1 \\ 1 \end{pmatrix}$$

$$\vec{a}_4 = [T(E_{22})]_B = \left[\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} C - C \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right]_B = \left[\begin{pmatrix} 0 & 0 \\ 1 & 2 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \right]_B = \begin{pmatrix} 0 \\ -1 \\ 1 \\ 0 \end{pmatrix}$$

Interchange R_1 and R_2

(c) Use part 8b to find a basis for $\ker(T)$. (It should consist of 2×2 matrices, not vectors in \mathbb{R}^4). x_3, x_4 are free

$$A \sim \begin{pmatrix} 1 & 1 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ -1 & 0 & -1 & 1 \\ 0 & -1 & 1 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Add R_2 to R_4 Add $-R_2$ to R_3
Add R_1 to R_3 Add $-R_2$ to R_1

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -x_3 + x_4 \\ x_3 \\ x_3 \\ x_4 \end{pmatrix} = x_3 \begin{pmatrix} -1 \\ 1 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

v_1 basis v_2 for $\text{Null}(A)$.

$$v_1 = \left[\begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix} \right]_{\mathcal{B}}, \quad v_2 = \left[\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right]_{\mathcal{B}}.$$

So $\{C-2I, I\}$ is a basis for $\ker(T)$.

(d) Use part 8c to find a basis of $\text{Im}(T)$.

Basis for $\text{Col}(A)$: The two pivot columns of A are a basis, \vec{a}_1 and \vec{a}_2 .

$$\vec{a}_1 = \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} = \left[\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right]_{\mathcal{B}}, \quad \vec{a}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ -1 \end{pmatrix} = \left[\begin{pmatrix} 1 & 1 \\ 0 & -1 \end{pmatrix} \right]_{\mathcal{B}}$$

So, $\left\{ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 0 & -1 \end{pmatrix} \right\}$ is a basis for $\text{Im}(T)$.

" " " " " "

$T(E_{11})$ $T(E_{12})$