

MODULAR FORMS AND ELLIPTIC CURVES OVER THE CUBIC FIELD OF DISCRIMINANT -23

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ABSTRACT. Let F be the cubic field of discriminant -23 and let $\mathcal{O} \subset F$ be its ring of integers. By explicitly computing cohomology of congruence subgroups of $\mathrm{GL}_2(\mathcal{O})$, we computationally investigate modularity of elliptic curves over F .

1. INTRODUCTION

1.1. Let F be a number field with ring of integers \mathcal{O} , and let E be an elliptic curve defined over F . According to a general contemporary philosophy with roots in the work of Taniyama, Shimura, and Weil, the curve E should be *modular*. There are many different perspectives about what this might mean, but at the very least one expects there exists a cuspidal automorphic form f on GL_2 that is a Hecke eigenform with integral Hecke eigenvalues, and such that these eigenvalues are closely related to the number of points on E over various finite fields. In particular, suppose \mathfrak{n} is the conductor of E . Then one expects f also to have conductor \mathfrak{n} , and that there should be an identification of partial L -functions $L^S(s, f) = L^S(s, E)$, where S is a fixed finite set of primes including all those dividing \mathfrak{n} . This identification is done through matching of Euler factors at good primes: if \mathfrak{p} is prime to \mathfrak{n} , then one wants

$$(1) \quad |E(\mathbb{F}_{\mathfrak{p}})| = \mathrm{Norm}(\mathfrak{p}) + 1 - a_{\mathfrak{p}},$$

where $\mathbb{F}_{\mathfrak{p}} = \mathcal{O}/\mathfrak{p}$ is the residue field and $a_{\mathfrak{p}} \in \mathbb{Z}$ is the \mathfrak{p} th Hecke eigenvalue. This idea has been computationally investigated by a variety of authors, including Cremona and his students for F complex quadratic [7, 9, 10, 21]; Socrates–Whitehouse and Dembélé for F real quadratic [11, 23]; and the current authors, in joint work with F. Hajir, for F the CM field of fifth roots of unity [15].

In this paper, we continue this computational work and study the modularity of elliptic curves when F is the complex cubic field of discriminant -23 . This field has signature $(1, 1)$ and is thus not Galois (its Galois closure is the Hilbert class field of $\mathbb{Q}(\sqrt{-23})$).

The overall program is similar to that of [15]. Namely, instead of explicitly working with automorphic forms, we work with the cohomology of the congruence subgroups $\Gamma_0(\mathfrak{n}) \subset \mathrm{GL}_2(\mathcal{O})$. By Franke’s proof of Borel’s conjecture [13], one knows that this cohomology is built from certain automorphic forms, and that there is a

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subspace of *cuspidal cohomology* that corresponds to certain cuspidal automorphic forms. This cohomology can be computed using topological tools; in particular the first step is carrying out a version of explicit reduction theory due to Koecher [20]. This reduction theory is one generalization of Voronoi's theory of perfect quadratic forms [24] to a much broader setting that includes quadratic forms over both number fields of arbitrary signature and the quaternions. To the best of our knowledge, this is the first time Koecher's work has been used for such computations. Since we expect that these techniques will be useful for later researchers, we take some time to explain Koecher's work.

The second step is computing the cohomology and its decomposition under the action of the Hecke operators. Computing the cohomology is straightforward, since the reduction theory provides us with an explicit cell complex with an action by $\Gamma_0(\mathfrak{n})$. Computing the Hecke operators, however, is much more involved. Our technique is to use the *sharply complex* and a variant of an algorithm described by the first-named author for subgroups of $\mathrm{SL}_4(\mathbb{Z})$ [17], and later developed by both of us in [15, 18] for subgroups of $\mathrm{GL}_2(\mathcal{O})$, where F is real quadratic and totally complex quartic. Although these settings seem to have little to do with each other, they share the feature that the highest cohomological degree where the cusp forms can contribute is exactly one less than the virtual cohomological dimension. Thus although the symmetric spaces and underlying fields are completely different, computing the Hecke operators reduces to a similar combinatorial problem. The technique we use is closely related to that of modular symbols [4, 22], although the combinatorics are more complicated since we need to work with a different cohomology group. As in the papers [15, 17, 18], we do not have a proof that our technique of computing Hecke operators works, but the technique has always been successful in practice.

With the first two steps completed, we find ourselves with a list of Hecke eigen-classes, some of which apparently correspond to cuspforms, and further some of which have eigenvalues that are rational integers. The final step is to compile a list of elliptic curves over F of small conductors. This is done in the obvious way: we enumerate curves by searching over a box of Weierstrass equations and throwing out duplicates.

After all three steps are done, we arrive at a list of cohomology classes and a list of elliptic curves. We found complete agreement between these lists. In particular:

- For each elliptic curve E with norm conductor within the range of our cohomology computations, we found a cuspidal cohomology class with rational Hecke eigenvalues that matched the point counts for E as in (1), for every Hecke operator that we checked.
- For each cuspidal cohomology class with rational Hecke eigenvalues, we found a corresponding elliptic curve whose point counts matched every eigenvalue we computed.

We now give a guide to the contents of the paper. In §§2,3 we recall Koecher's work on positivity domains, and explain how one can find explicit fundamental domains for GL_n over number fields acting on spaces of quadratic forms. In §4 we compute the Koecher polyhedron for the case under consideration, namely $\mathrm{GL}_2(\mathcal{O})$ where \mathcal{O} is the ring of integers in the cubic field of discriminant -23 . Next, §5 explains the complexes we use to compute the cohomology of subgroups of $\mathrm{GL}_2(\mathcal{O})$ and the Hecke action. After this, in §6 we give a brief overview of how we compute

the action of the Hecke operators, following [15, 18]. The following two sections §§7,8 give more details about what is done differently in the current paper from the techniques in [15, 18]. Finally, in §9 we present our computational data.

2. POSITIVITY DOMAINS

In this section we review Koecher’s study of positivity domains [20], which generalizes Voronoi’s reduction theory for positive definite quadratic forms [24].

Let V be a finite dimensional vector space over \mathbb{R} . Let $\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{R}$ be a positive definite symmetric bilinear form. The form determines a norm $|\cdot|$ on V in the usual way by $|v| = \sqrt{\langle v, v \rangle}$, and we give V the metric topology. For any subset $C \subset V$, let \overline{C} be the closure, let $\text{Int}(C)$ be the relative interior, and let $\partial C = \overline{C} \setminus \text{Int}(C)$ be the boundary.

Definition 2.1. A subset $C \subset V$ is called a *positivity domain* if the following hold:

- C is open and nonempty.
- $\langle x, y \rangle > 0$ for all $x, y \in C$.
- For each $x \in V \setminus C$ there is a nonzero $y \in \overline{C}$ such that $\langle x, y \rangle \leq 0$.

One can show that a positivity domain C is a convex cone in V . In other words, if $y \in C$ then $\lambda y \in C$ for all $\lambda > 0$, and if $y, y' \in C$ then $y + y' \in C$. Furthermore, C contains no line.

Let $D \subset \overline{C} \setminus \{0\}$ be a nonempty discrete subset. For $y \in C$, let

$$\mu(y) = \inf_{d \in D} \{\langle d, y \rangle\}.$$

Koecher proves that $\mu(y) > 0$ and that the infimum is achieved only on a finite set of points, which we denote $M(y)$:

$$M(y) = \{d \in D \mid \langle d, y \rangle = \mu(y)\}.$$

We call $M(y)$ the set of *minimal vectors* for y .

Definition 2.2. A point $y \in C$ is called *perfect* if the linear span of its minimal vectors $M(y)$ is all of V .

Note that the set $M(y)$, as well as the notion of perfection of a point in C , depend on the choice of the set D . If y is perfect, then so is λy for $\lambda > 0$, and clearly $M(\lambda y) = M(y)$. We let $\Phi = \Phi(D)$ be the set of all perfect points y with $\mu(y) = 1$.

Example 2.3. We consider the classical case of this construction. Let V be the space of symmetric $n \times n$ matrices over \mathbb{R} , let $\langle a, b \rangle = \text{Tr}(ab)$, and let $C \subset V$ be the cone of positive definite matrices. Let $D \subset V$ be the set of points of the form vv^t for $v \in \mathbb{Z}^n$, where we regard elements of \mathbb{Z}^n as column vectors. Then if $y \in C$, $d = vv^t \in D$, the quantity $\langle d, y \rangle$ is easily seen to be the value $Q_y(v) = v^t y v$, in other words the value of the positive definite quadratic form Q_y determined by y on the integral vector v . Koecher’s notion of perfect coincides with Voronoi’s notion of a perfect quadratic form: a positive definite quadratic form is perfect if it can be recovered from the knowledge of its nonzero minimum and the set of vectors on which the minimum is attained.

Returning now to the general setting, Voronoi used perfect quadratic forms to provide an explicit reduction theory for the cone of positive definite quadratic forms,

and we want the same for our positivity domain C . Unfortunately not all sets D will accomplish this. Thus we have the following definition:

Definition 2.4. A nonempty discrete subset $D \subset \overline{C} \setminus \{0\}$ is said to be *admissible* if for any sequence $\{y_i\}$ converging to a point in ∂C , we have $\lim \mu(y_i) = 0$.

Note that the set D from Example 2.3 is admissible. Suppose $\{y_i\} \rightarrow y \in \partial C$. The real quadratic form Q_y associated to y is degenerate, and thus there is a nonzero subspace $W \subset \mathbb{R}^n$ such that Q_y restricted to W vanishes. Since there exist integral vectors arbitrarily close to W , we have $\lim \mu(y_i) = 0$.

Koecher proved that if D is admissible, then $\Phi(D)$ is a discrete subset of C , and provides a polyhedral decomposition of C . To explain what we mean, we must recall some notions from convex geometry (a convenient reference is [14, Chapter 1]). Recall that a *polyhedral cone* in a real vector space V is a subset σ of the form

$$\sigma = \sigma(v_1, \dots, v_p) = \left\{ \sum_{i=1}^p \lambda_i v_i \mid \lambda_i \geq 0 \right\},$$

where v_1, \dots, v_p is a fixed set of vectors. We say that the v_1, \dots, v_p *span* σ . The dimension of σ is the dimension of its linear span; if the dimension of σ is n , then we call σ an *n-cone*. If σ is spanned by a linearly independent subset, then σ is called *simplicial*.

Now given any $y \in \Phi(D)$, let $\sigma(y)$ be the cone

$$\sigma(y) = \left\{ \sum \lambda_d d \mid \lambda_d \geq 0, d \in M(y) \right\}.$$

Koecher calls $\sigma(y)$ the *perfect pyramid* of y . We remark that typically $\sigma(y)$ is not a simplicial cone.

Let Σ be the set of perfect pyramids and all their proper faces, as y ranges over all points in $\Phi(D)$. Koecher proves that for admissible D , the perfect pyramids have the following properties:

- (i) Any compact subset of C meets only finitely many perfect pyramids.
- (ii) Two different perfect pyramids have no interior point in common.
- (iii) Given any perfect pyramid σ , there are only finitely many perfect pyramids σ' such that $\sigma \cap \sigma'$ contains a point of C (which, by item (ii), must lie on the boundaries of σ, σ').
- (iv) The intersection of any two perfect pyramids is a common face of each.
- (v) Let $\sigma(y)$ be a perfect pyramid and F a codimension one face of $\sigma(y)$. If F meets C , then there is another perfect pyramid $\sigma(y')$ such that $\sigma(y) \cap \sigma(y') = F$.
- (vi) We have $\bigcup_{\sigma \in \Sigma} \sigma \cap C = C$.

In item (v), if a facet F of a perfect pyramid is contained in ∂C , we say that F is a *dead end*. In item (iii), the pyramid σ' is called a *neighbor* of σ . Property (iv), together with the definition of Σ , implies that Σ is a *fan* [14, §1.4].

Definition 2.5. We call Σ the *Koecher fan*, and the cones in Σ the *Koecher cones*.

Now we bring groups into the picture. Let $G \subset \mathrm{GL}(V)$ be the group of automorphisms of C . Let $\Gamma \subset G$ be a discrete subgroup such that $\Gamma D = D$. Koecher proves that if D is admissible, then Γ acts properly discontinuously on C [20, §5.4]. Moreover, the Koecher fan gives an explicit reduction theory for Γ in the following sense:

- (O1) There are finitely many Γ -orbits in Σ .
- (O2) Every $y \in C$ is contained in a unique cone in Σ .
- (O3) Given any cone $\sigma \in \Sigma$ with $\sigma \cap C \neq \emptyset$, the group $\{\gamma \in \Gamma \mid \gamma\sigma = \sigma\}$ is finite.

Choose representatives $\sigma_1, \dots, \sigma_n$ of the orbits of Γ in Σ , and let

$$\Omega = \bigcup \sigma_i \cap C.$$

One would hope that Ω is a fundamental domain for the action of Γ on C , but unfortunately the properties (O1)–(O3) do not imply this. However Ω is close to a fundamental domain: each of the σ_i has at worst a finite stabilizer subgroup in Γ . If one wishes to refine Ω to an exact reduction domain, as Koecher does, one must account for these finite stabilizers, for instance by passing to the barycentric subdivision of the perfect pyramids and then taking an appropriate union of the resulting cones. For our purposes this is not necessary, since explicit knowledge of Ω and these stabilizers suffices for cohomology computations (cf. [1, §4]).

We conclude this section by presenting another viewpoint on the perfect pyramids and the Koecher fan. This perspective does not appear in [20], but instead is motivated by the theory of cores and co-cores in [3, Chapter II].

Definition 2.6. Let D be an admissible set in \bar{C} . The *Koecher polyhedron* Π is the convex hull in \bar{C} of D .

The connection between Π and Σ is given by the following proposition:

Proposition 2.7. *Assume that no perfect pyramid in Σ has a dead end. Then the nonzero cones in the fan Σ are the cones on the faces of Π .*

Proof. Because Π is a convex polyhedron, it suffices to see that the perfect pyramids are the cones on the facets (maximal proper faces) of Π . So let y be a perfect form with minimal vectors d_1, \dots, d_n and with perfect pyramid $\sigma(y)$. The equation $\langle x, y \rangle = 1$ defines a hyperplane in V that is a supporting hyperplane for Π (all other $d \in D$ satisfy $\langle d, y \rangle > 1$, and Π is the convex hull of D). Since the d_i span V , it follows that the convex hull of the d_i is a facet of Π . Thus $\sigma(y)$ gives rise to a facet F of Π , and $\sigma(y)$ is the cone on F . Since we assume no perfect pyramids have dead ends, property (v) on page 4 implies that the facets of Π meeting F in a codimension one face correspond to perfect forms by a similar argument. Thus the facets of Π are in bijection with the perfect pyramids. \square

3. QUADRATIC FORMS OVER NUMBER FIELDS AND REDUCTION THEORY

In this section we specialize the results of §2 to the setting of primary concern to us. This recapitulates [20, §9].

Let F be a number field of degree $d = r + 2s$ with r real embeddings and s conjugate pairs of complex embeddings. For each pair of complex conjugate embeddings, choose and fix one. We can then identify the infinite places of F with its real embeddings and our choice of complex embeddings.

For each infinite place v of F , let V_v be the real vector space of $n \times n$ real symmetric (respectively, of complex Hermitian) matrices $\text{Sym}_n(\mathbb{R})$ (resp., $\text{Herm}_n(\mathbb{C})$) if v is real (resp., complex). Let C_v be the corresponding cone of positive definite (resp., positive Hermitian) forms. Put $V = \prod_v V_v$ and $C = \prod_v C_v$, where the products

are taken over the infinite places of F . We equip V with the inner product

$$(2) \quad \langle x, y \rangle = \sum_v c_v \operatorname{Tr}(x_v y_v),$$

where the sum is again taken over the infinite places of F , and c_v equals 1 if v is real and equals 2 if v is complex.

The group $G = \operatorname{GL}_n(\mathbb{R})^r \times \operatorname{GL}_n(\mathbb{C})^s$ acts on V by

$$(g \cdot y)_v = \begin{cases} g_v y_v g_v^t & v \text{ real,} \\ g_v y_v \bar{g}_v^t & v \text{ complex.} \end{cases}$$

This action preserves C , and exhibits G as the full automorphism group of C . Moreover, if \mathbf{G} is the reductive group $\operatorname{Res}_{F/\mathbb{Q}} \operatorname{GL}_n$, then we can identify the group of real points $\mathbf{G}(\mathbb{R})$ with G . In fact, we can identify the quotient $C/\mathbb{R}_{>0}$ of C by homotheties with the symmetric space $X = G/KA_G$, where $K \subset G$ is the maximal compact subgroup and A_G is the split component (the connected component of a maximal \mathbb{Q} -split torus in the center of \mathbf{G}). Indeed, let X_n (respectively Y_n) be the symmetric space of noncompact type $\operatorname{SL}_n(\mathbb{R})/\operatorname{SO}(n)$ (resp. $\operatorname{SL}_n(\mathbb{C})/\operatorname{SU}(n)$). Then we have

$$X \simeq (X_n)^r \times (Y_n)^s \times Z,$$

where Z is a euclidean symmetric space of dimension $r + s - 1$.¹ Now we also have isomorphisms

$$(3) \quad \operatorname{Sym}_n(\mathbb{R})/\mathbb{R}_{>0} \xrightarrow{\simeq} X_n, \quad \operatorname{Herm}_n(\mathbb{C})/\mathbb{R}_{>0} \xrightarrow{\simeq} Y_n.$$

The identification $C/\mathbb{R}_{>0} \simeq X$ then follows, once one rewrites (3) as $\operatorname{Sym}_n(\mathbb{R}) \simeq X_n \times \mathbb{R}_{>0}$ and $\operatorname{Herm}_n(\mathbb{C}) \simeq Y_n \times \mathbb{R}_{>0}$.

Now we construct an admissible subset D of \bar{C} . Let \mathcal{O} be the ring of integers of F . The nonzero (column) vectors $\mathcal{O}^n \setminus \{0\}$ determine points in V via

$$(4) \quad q: x \mapsto (x_v x_v^*).$$

Here $*$ denotes transpose if v is real, and conjugate transpose if v is complex. We have $q(x) \in \bar{C}$ for all $x \in \mathcal{O}^n$, and by analogy with Voronoi's construction it is natural to consider the set D obtained by applying q to the nonzero points. Indeed, we have the following basic result of Koecher (cf. [20, Lemma 11]):

Proposition 3.1. *The set*

$$D = \{q(x) \mid x \in \mathcal{O}^n \setminus \{0\}\}$$

is admissible.

The group $\Gamma = \operatorname{GL}_n(\mathcal{O})$ acts on C and takes D into itself. Thus we can find the Koecher fan Σ . After passing to the symmetric space X , we obtain a decomposition of X into cells with Γ -action that can then be used to compute the cohomology of Γ and its finite-index subgroups as in [1, 15] and other places.

Remark. One can think of the cone C as being the space of real-valued positive quadratic forms over F in n -variables. Specifically, if $A \in C$ is a tuple (A_v) , then A determines a quadratic form Q_A on F^n by

$$Q_A(x) = \sum_v c_v x_v^* A_v x_v,$$

¹In terms of the associated discrete groups, this flat factor Z accounts for the difference between $\operatorname{SL}_n(\mathcal{O})$ and $\operatorname{GL}_n(\mathcal{O})$; the former is infinite index in the latter.

where c_v is defined in (2) and $*$ is defined as in (4). However, not every quadratic form of interest comes from a matrix A that is the image of a matrix from F under the embeddings. For instance, in general the perfect forms will not come from matrices over F in this way.

4. THE KOECHER POLYHEDRON AND FAN FOR THE FIELD OF DISCRIMINANT -23

From now on, we set $n = 2$ and consider a particular mixed signature cubic field, namely $F = \mathbb{Q}[x]/(f(x))$, where $f(x) = x^3 - x^2 + 1$. If we choose a root t of f , then the field F has ring of integers $\mathcal{O} = \mathbb{Z}[t]$, discriminant -23 , and class number one. We remark that much of what we do can be extended to other mixed signature cubic fields, but for this investigation we focus on F to honor its special place in the menagerie of complex cubics.²

Since F has signature $(1, 1)$, the space of forms V is the product

$$V = \text{Sym}_2(\mathbb{R}) \times \text{Herm}_2(\mathbb{C}).$$

The quotient $X = C/\mathbb{R}_{>0}$ is 6-dimensional.

We now present representatives for the $\Gamma = \text{GL}_2(\mathcal{O})$ orbits of perfect forms. These were computed using the algorithm in [16], which is a recasting of Voronoi's original algorithm to the setting of self-adjoint homogeneous cones. In particular, the algorithm begins with an initial perfect form and then identifies the neighbors of the corresponding perfect pyramid. To find the initial perfect form, we computed a large enough part of the Koecher polyhedron Π (Definition 2.6) to identify a facet.

In our computation, we found that there are nine Γ -orbits of perfect forms, which thus give rise to nine Γ -orbits of perfect pyramids. Seven of these orbits consist of simplicial cones (each with seven spanning vectors); the remaining two classes of cones are spanned by eight and nine vectors.

Theorem 4.1. *A perfect binary form over F has minimal vectors that are $\text{GL}_2(\mathcal{O})$ -conjugate to exactly one of the following sets (each vector d in these lists is a*

²For instance, it appears first in lists of cubic fields ordered by the absolute value of their discriminants. It appears often in algebraic number theory courses since its Galois closure is the Hilbert class field of $\mathbb{Q}(\sqrt{-23})$.

representative of a pair $\pm d$ of minimal vectors):

$$\begin{aligned}
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 - t \\ t^2 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2 + 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2 + 1 \end{bmatrix}, \begin{bmatrix} t^2 - t \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix}, \begin{bmatrix} t^2 - t \\ t^2 \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 \\ 1 \end{bmatrix}, \begin{bmatrix} -t^2 + 1 \\ -t^2 \end{bmatrix}, \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2 + 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 - t \\ t^2 \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2 + 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} t^2 - t \\ 0 \end{bmatrix}, \begin{bmatrix} t^2 - t \\ t^2 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix}, \begin{bmatrix} t^2 \\ t^2 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} t^2 - t \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -t \end{bmatrix}, \begin{bmatrix} t \\ t^2 \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 - t \\ t^2 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} t^2 \\ t \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2 + 1 \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 \\ t^2 - t \end{bmatrix}, \begin{bmatrix} 1 \\ t^2 - t \end{bmatrix}, \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ t^2 \end{bmatrix}, \begin{bmatrix} t^2 - t \\ -t \end{bmatrix} \right\}, \\
& \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} t^2 - t \\ -t \end{bmatrix}, \begin{bmatrix} -t^2 \\ -t^2 + t \end{bmatrix}, \begin{bmatrix} t^2 - t \\ t^2 - t \end{bmatrix} \right\}.
\end{aligned}$$

Using the data in Theorem 4.1, we can compute the complete combinatorial structure of the fan Σ . In particular we can enumerate the $\mathrm{GL}_2(\mathcal{O})$ -orbits of the lower-dimensional cones of Σ . The results are given in Table 3. For later purposes, we record the following facts about Σ , which represents the information we need for our purposes. Propositions 4.2 and 4.3 are proved by direct computation.

Proposition 4.2.

- (i) *All cones up to dimension 6 in the Koecher fan are simplicial.*
- (ii) *All 1-cones lie in the boundary ∂C .*
- (iii) *One of the two orbits of 2-cones lies in ∂C ; a representative has spanning vectors*

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} t \\ 0 \end{bmatrix} \right\}.$$

The other orbit, with representative spanned by

$$(5) \quad \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}.$$

meets C .

(iv) *There are ten orbits of 3-cones, represented by*

$$\begin{aligned} & \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2 + 1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} t-1 \\ -t+1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} t \\ 1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 - t + 1 \\ t - 1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -t+1 \\ -t^2+t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2 \\ t^2 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -t^2+t \\ t^2-t+1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}. \end{aligned}$$

All 3-cones meet the interior of C .

(v) *There are thirty-one orbits of 4-cones. Representatives have spanning vectors given by the following list (each pair in this list should be supplemented by the spanning vectors of the cone (5)).*

$$\begin{aligned} & \left\{ \begin{bmatrix} 1 \\ -t^2 + 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t+1 \\ -t^2+t \end{bmatrix}, \begin{bmatrix} t^2-t+1 \\ t-1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} -t \\ -t \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2+1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} t^2 \\ t^2 \end{bmatrix}, \begin{bmatrix} t \\ 1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ t^2-t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} t^2-t \\ t^2 \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2+1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} 0 \\ -t \end{bmatrix}, \begin{bmatrix} t-1 \\ t^2-t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -1 \\ -t+1 \end{bmatrix}, \begin{bmatrix} -t^2+t \\ t^2-t+1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} t^2-t \\ t^2 \end{bmatrix}, \begin{bmatrix} -t \\ -t \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} -1 \\ t^2-t \end{bmatrix}, \begin{bmatrix} t-1 \\ t^2-t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} -t^2+t \\ t^2-t+1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -t+1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} -1 \\ t^2-t \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} t^2-t \\ -t^2+t \end{bmatrix}, \begin{bmatrix} -t+1 \\ t-1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -t^2+1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} t^2 \\ -t^2+1 \end{bmatrix}, \begin{bmatrix} t \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} -t+1 \\ t-1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} t^2-t \\ -t^2+t \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} t^2-t \\ -1 \end{bmatrix}, \begin{bmatrix} -t+1 \\ -t^2+t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2-t \\ t^2 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ t^2 \end{bmatrix}, \begin{bmatrix} t \\ -t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ t^2 \end{bmatrix}, \begin{bmatrix} t^2 \\ -t^2+1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} -t^2+t \\ t^2-t+1 \end{bmatrix}, \begin{bmatrix} -t+1 \\ -t^2+t \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t^2 \\ t^2-t \end{bmatrix}, \begin{bmatrix} -t^2+t \\ -t+1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t^2+1 \\ 1 \end{bmatrix}, \begin{bmatrix} -t \\ -t^2+1 \end{bmatrix} \right\}, \\ & \left\{ \begin{bmatrix} 1 \\ t^2 \end{bmatrix}, \begin{bmatrix} -t^2+1 \\ 1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} t^2 \\ 1 \end{bmatrix}, \begin{bmatrix} t^2-t \\ t^2 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} -t \\ 0 \end{bmatrix}, \begin{bmatrix} t \\ 1 \end{bmatrix} \right\}, \left\{ \begin{bmatrix} t^2-t \\ -t^2+t \end{bmatrix}, \begin{bmatrix} t^2 \\ -t^2+t \end{bmatrix} \right\}. \end{aligned}$$

Proposition 4.3. *Let γ and δ denote the matrices*

$$\gamma = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \delta = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}.$$

- (i) *The 2-cone that meets C has stabilizer of order 8, isomorphic to D_4 generated by γ and δ .*
- (ii) *The stabilizers of the 3-cones are given in Table 1.*
- (iii) *The stabilizers of the 4-cones are given in Table 2.*

Remark. A consequence of the computations in this section is that the Koecher fan has no dead ends, in the sense of item (v) on page 4. Thus the cones in the Koecher fan are in bijection with the cones on the faces of the Koecher polyhedron, as in Proposition 2.7. We expect this is always true for GL_n over number fields

when D is constructed as in Proposition 3.1. We do not know if this is true for general admissible sets D , although we expect not, since dead ends do occur in other generalizations of Voronoi's theory [12, §3].

5. COHOMOLOGY, THE KOECHER COMPLEX, AND THE SHARPLY COMPLEX

We now turn to the cohomology spaces $H^*(\Gamma; \mathbb{C})$, where $\Gamma \subset \mathrm{GL}_2(\mathcal{O})$ is now a congruence subgroup. This is isomorphic to $H^*(\Gamma \backslash X; \mathbb{C})$. Since X is 6-dimensional, we have $H^i(\Gamma; \mathbb{C}) = 0$ unless $0 \leq i \leq 6$. Since \mathbf{G} mod its radical has \mathbb{Q} -rank 1, by the Borel–Serre vanishing theorem [5] we have $H^i(\Gamma; \mathbb{C}) = 0$ if $i = 6$. Thus the cohomological dimension ν of any Γ is 5. One can show that the *cuspidal cohomology* (the part of the cohomology corresponding to cuspidal automorphic forms) only occurs in degrees 2, 3, 4, and general results imply that we only need to compute one of these groups. Thus we focus on $H^4(\Gamma; \mathbb{C})$; as we shall see this is the easiest group for us to compute.

We now describe the techniques we use to compute cohomology and the action of the Hecke operators. Similar techniques were used in [1, 15]. For more details about the complexes we use (in the setting of GL_n/\mathbb{Q}), see [2].

Let \mathcal{T} be the Tits building for GL_n/F . Thus \mathcal{T} is a simplicial complex with k -simplices given by the proper flags in F^n of length $(k+1)$. By the Solomon–Tits theorem, \mathcal{T} has the homotopy type of a bouquet of $(n-2)$ -spheres, and in particular has reduced homology concentrated in dimension $n-2$. One can construct classes in $\tilde{H}_{n-2}(\mathcal{T})$ by taking the fundamental classes of apartments: one chooses a basis $E = \{v_1, \dots, v_n\}$ of F^n and considers all the possible flags that can be constructed from E by taking spans of permutations of subsets. By appropriately choosing signs one obtains a class $\langle v_1, \dots, v_n \rangle \in \tilde{H}_{n-2}(\mathcal{T})$. It is known that such classes span the homology. We have an action of $\mathbf{G}(\mathbb{Q})$, and by definition, the *Steinberg module* St_n is the $\mathbf{G}(\mathbb{Q})$ -module $\tilde{H}_{n-2}(\mathcal{T})$.

According to the Borel–Serre duality theorem [5], for any arithmetic subgroup $\Gamma \subset \mathbf{G}(\mathbb{Q})$ we have

$$H^{\nu-k}(\Gamma; \mathbb{C}) \xrightarrow{\sim} H_k(\Gamma; \mathrm{St}_n \otimes \mathbb{C}).$$

Thus to compute the cohomology of Γ , we need to take a resolution of the Steinberg module. We work with two different complexes; each has features that help us deal with the two sides of our computational problem, namely computing H^* as well as the action of the Hecke operators. The first, the Koecher complex, comes from the geometry of the Koecher polyhedron. It has the advantage that it is finite mod Γ , but it does not admit an action of the Hecke operators. On the other hand the second, the sharply complex, does admit a Hecke action, but unfortunately it is not finite mod Γ .

Recall that Σ is the fan of Koecher cones in the closed cone \overline{C} . After we mod out by homotheties, the nonzero cones in Σ determine cells in the quotient $\overline{X} = (\overline{C} \setminus \{0\})/\mathbb{R}_{>0}$. We let K_* be the oriented chain complex on these cells, and let ∂K_* be the subcomplex generated by the cells contained entirely in the boundary $\partial X = \overline{X} \setminus X$. The *Koecher complex* \mathcal{K}_* is the quotient complex $K_*/\partial K_*$. We can construct a map

$$(6) \quad \mathcal{K}_1 \longrightarrow \mathrm{St}_2$$

as follows. Let $\{e_1, e_2\}$ be the standard basis of F^2 . By (iii) of Proposition 4.2, nontrivial generators of \mathcal{K}_1 correspond to the images of the oriented 2-cones in the

$\mathrm{GL}_2(\mathcal{O})$ -orbit of the cone spanned by $q(e_1), q(e_2)$. Orient this cone by taking the spanning points in this order, and then map it to the class of the corresponding apartment. This leads to a diagram

$$\mathcal{K}_* \longrightarrow \mathrm{St}_2,$$

which gives the desired resolution.

We now turn to the sharbly complex. Recall that for any $x \in \mathcal{O}^2 \setminus \{0\}$, we have constructed a point $q(x) \in \overline{C}$ (see (4)). Write $x \sim y$ if $q(x)$ and $q(y)$ determine the same point in \overline{X} . Let $\mathcal{S}_k, k \geq 0$, be the Γ -module A_k/C_k , where A_k is the set of formal \mathbb{C} -linear sums of symbols $\mathbf{u} = [x_1, \dots, x_{k+2}]$, where each x_i is in $\mathcal{O}^2 \setminus \{0\}$, and C_k is the submodule generated by

- (i) $[x_{\sigma(1)}, \dots, x_{\sigma(k+2)}] - \mathrm{sgn}(\sigma)[x_1, \dots, x_{k+2}]$,
- (ii) $[x, x_2, \dots, x_{k+2}] - [y, y_2, \dots, y_{k+2}]$ if $x \sim y$, and
- (iii) \mathbf{u} if x_1, \dots, x_{k+2} are contained in a hyperplane (we say \mathbf{u} is *degenerate*).

We define a boundary map $\partial: \mathcal{S}_{k+1} \rightarrow \mathcal{S}_k$ by

$$(7) \quad \partial[x_1, \dots, x_{k+2}] = \sum_{i=1}^{k+2} (-1)^i [x_1, \dots, \hat{x}_i, \dots, x_{k+2}],$$

where \hat{x}_i means omit x_i . The resulting complex \mathcal{S}_* is called the *sharbly complex*. We have a map $\mathcal{S}_0 \rightarrow \mathrm{St}_2$ analogous to (6), and the sharbly complex provides a resolution of St_2 .

Recall that all Koecher cones of dimension ≤ 6 are simplicial (Proposition 4.2, (i)). Thus one can identify \mathcal{K}_i with a subgroup of \mathcal{S}_i for $i \leq 5$. This identification is compatible with the boundary maps, so we can think of \mathcal{K}_* as being a subcomplex of \mathcal{S}_* in these degrees. Since our main focus is computing H^4 , we will work exclusively with Koecher/sharbly chains in degrees 0, 1, 2, and therefore we regard the corresponding Koecher chains as living in the sharbly complex. Propositions 4.2–4.3 give all the information we need for computing H^4 .

To compute the Hecke operators, one proceeds as follows. First one computes the cohomology group $H^4(\Gamma \backslash X)$ using the relevant part of \mathcal{K}_* . Let ξ be a cycle representing a class in H^4 . We write ξ as a finitely supported 1-sharbly cycle $\xi = \sum n(\mathbf{u})\mathbf{u}$, where “cycle” means that the boundary vanishes modulo the action of Γ . We can compute the Hecke operator T in the sharbly complex as

$$(8) \quad T(\xi) = \sum n(\mathbf{u}) \sum_g g \cdot \mathbf{u},$$

where the inner sum is taken over a finite subset of $\mathbf{G}(\mathbb{Q})$. The right hand side of (8) will usually be a 1-sharbly cycle that does not come from the Koecher complex, and thus cannot obviously be written in terms of a fixed basis of H^4 . Therefore one needs an algorithm to move $T(\xi)$ back to a sum of cycles coming from \mathcal{K}_* . How this is done is described in the next section.

Remark. Since \mathcal{K}_* is not the chain complex of a simplicial complex, one cannot directly regard it as a subcomplex of \mathcal{S}_* . However, it is possible to canonically refine \mathcal{K}_* to a complex $\tilde{\mathcal{K}}_*$ that does sit naturally inside the sharbly complex: one simply considers the simplicial complex on all simplices that arise by subdividing the cells in \mathcal{K}_* without adding new vertices. One must also add new relations that encode when an original Koecher cell is a union of simplices. Since we do not need this construction in our paper, we omit the details.

6. REDUCTION ALGORITHM

In this section we describe how Hecke images $T(\xi)$ as in (8) are rewritten as a sum of sharply cycles supported on Koecher cones. The main ideas and steps already appear in [18], which studied the case of a $\mathrm{GL}_2(\mathcal{O})$, where \mathcal{O} is the ring of integers of a real quadratic field. Here we focus on the differences between that case and the current. We begin with some definitions.

Given a point $q(x)$, $x \in \mathcal{O}^2 \setminus \{0\}$, let $R(x)$ be the unique point $y \in \mathcal{O}^2 \setminus \{0\}$ such that $y \sim x$ and y is closest to the origin along the ray $\mathbb{R}_{\geq 0}q(x)$. We call $R(x)$ the *spanning point* of x ; for any sharply $\mathbf{u} = [x_1, \dots, x_n]$ we can speak of its set of spanning points. Any sharply $\mathbf{u} = [x_1, \dots, x_n]$ determines a closed cone $\sigma(\mathbf{u})$ in \bar{C} . We call a sharply $\mathbf{u} = [x_1, \dots, x_n]$ *reduced* if its spanning points are a subset of the spanning points of some fixed Koecher cone; similarly we call a sharply cycle reduced if each sharply in its support is reduced. Note that \mathbf{u} reduced does not mean that $\sigma(\mathbf{u})$ is the face of some perfect pyramid, and thus a reduced sharply cycle need not come from a Koecher cycle. However, it is clear that there are only finitely many reduced sharply cycles modulo Γ . Moreover, it is not difficult to write a reduced sharply cycle in terms of Koecher cycles directly, so our main challenge is to rewrite $T(\xi)$ in terms of reduced sharply cycles.

We now introduce notions of size and reduction level help us gauge how close a sharply cycle is to being reduced. For any 0-sharply $\mathbf{u} = [x_1, x_2]$, define the *size* of \mathbf{u} by $\mathrm{Size}(\mathbf{u}) = |\mathrm{Norm}(\det(R(x_1), R(x_2)))|$. We extend this to general sharplies by first defining the size of $\mathbf{u} = [x_1, \dots, x_n]$ to be the maximum of the size of the sub 0-sharplies $[x_i, x_j]$, and then to chains $\xi = \sum n(\mathbf{u})\mathbf{u}$ by taking the maximum size found over the support of ξ .

We now focus on 0- and 1-sharplies. Given a 1-sharply $\mathbf{u} = [x_1, x_2, x_3]$, we call its sub 0-sharplies *edges*, and define the *reduction level* of \mathbf{u} to be the number of edges that are not reduced. According to Proposition 4.2 the only $\mathrm{GL}_2(\mathcal{O})$ -class of reduced 0-sharply is $[e_1, e_2]$, and all we can often detect nonzero reduction level by computing sizes, but we remark that there are subtleties: for instance, there exist nonreduced 1-sharplies of reduction level zero. Similar phenomena occur in [15, 18], and reflect the infinite order units in \mathcal{O} .

There are also edges with size 0 that are not reduced. More precisely, looking at the edges of the standard 1-sharplies, we see that $[x, cx]$ is reduced only if the coordinates of x generate the ideal \mathcal{O} and $c \in \{\pm t, \pm t^{-1}\} = \{\pm \epsilon, \pm \epsilon^{-1}\}$, where $\epsilon = -t$ is a generator of $\mathcal{O}^\times \bmod \text{torsion}$. Such 0-sharplies are of course degenerate and are eliminated in the defining relations of \mathcal{S}_* , but when one wants to write a 1-sharply cycle in terms of reduced cycles they must be considered. Again, this is not surprising since the same phenomena appear in [15, 18]. However, if a 1-sharply contains an edge of the $[x, \pm x]$, then the 1-sharply is degenerate and is thrown away.

We now turn to the reduction algorithm. The overall structure proceeds as described in [18], and we refer to there for more details. For each 1-sharply \mathbf{u} in the support of a Hecke image, we Γ -equivariantly choose a collection of *reducing points* for the nonreduced edges of \mathbf{u} (see [18, §3.3]). These points, together with the original spanning points of \mathbf{u} , are assembled into a new 1-sharply chain ξ' , following the cases described in [18, §3.5]. The process is repeated until the 1-sharply chain is reduced.

In the current work, there are two new features to this algorithm:

- (i) The case of reduction level 0 is handled slightly differently than in [15, 18].³
- (ii) A new technique is used to choose reducing points Γ -equivariantly.

For item (i) see the next section; item (ii) is discussed in §8.

7. REDUCTION LEVEL 0

We consider 1-sharblies with all edges reduced, but that are not themselves reduced. According to Proposition 4.2, there are two $\mathrm{GL}_2(\mathcal{O})$ -orbits of 2-cones. One is degenerate, and the other corresponds to a 0-sharply of size 1. It follows that the 1-sharblies with all edges reduced must have edges of determinant 0 or ϵ^k , where ϵ is an infinite generator of the unit group \mathcal{O}^\times , and $k \in \mathbb{Z}$ has large absolute value. More precisely, write

$$\mathcal{O}^\times \simeq \langle -1 \rangle \times \langle \epsilon \rangle.$$

Then up to $\mathrm{GL}_2(\mathcal{O})$ -equivalence, we need only consider 1-sharblies with spanning points e_1, e_2 , and $v = \begin{bmatrix} a \\ b \end{bmatrix}$, where

- $a = (-1)^{f_a} \epsilon^{n_a}$ and $b = (-1)^{f_b} \epsilon^{n_b}$,
- at least one of $|n_a|, |n_b|$ is strictly greater than 1, and
- both n_a, n_b are non-zero.

We now describe how to write $[e_1, e_2, v]$ in terms of reduced 1-sharblies. We do this by replacing $[e_1, e_2, v]$ by a sum of 1-sharblies that are $\mathrm{GL}_2(\mathcal{O})$ -equivalent to 3-cones listed in Proposition 4.2. First introduce new vertices $v_a = \begin{bmatrix} a \\ 0 \end{bmatrix}$, $v_b = \begin{bmatrix} 0 \\ b \end{bmatrix}$ and edges $[v_a, v]$, $[v_a, e_1]$, $[v_a, e_2]$, $[v_b, v_a]$, $[v_b, v]$, and $[v_b, e_2]$ (cf. the left of Figure 1.)

Now we treat each region A_i separately, depending on a variety of cases. Given $z = (-1)^f \epsilon^n \in \mathcal{O}^\times$, let $\mathcal{I}(z) \subset \mathcal{O}^\times$ denote the list

$$\mathcal{I}(z) = [z_0, z_1, z_2, \dots, z_{|n|}],$$

where $z_i = (-1)^f \epsilon^i$ if $n \geq 0$, and $z_i = (-1)^f \epsilon^{-i}$ if $n < 0$. For example, if $z = -\epsilon^3$, then $\mathcal{I}(z)$ is the list $[-1, -\epsilon, -\epsilon^2, -\epsilon^3]$.

By construction, the region A_0 is already reduced. In fact, we have

$$[v, v_a, v_b] = \gamma \cdot [e_1 + e_2, e_1, e_2],$$

where $\gamma = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \in \mathrm{GL}_2(\mathcal{O})$.

For the regions A_1, A_2 , along the edge $[v_a, e_1]$ we introduce vertices

$$\varepsilon_a = \left\{ \begin{bmatrix} z \\ 0 \end{bmatrix} \mid z \in \mathcal{I}(a) \right\}$$

Note that $\#\mathcal{I}(a) \geq 2$. If $\#\mathcal{I}(a) = 2$, then no new vertices are added. Otherwise, let ε_a^0 be ε_a with the first and last vector removed. Construct edges

$$\begin{aligned} & \{[w, v] \mid w \in \varepsilon_a^0\}, \quad \{[w, e_2] \mid w \in \varepsilon_a^0\}, \quad \text{and} \\ & \{[(\varepsilon_a)_i, (\varepsilon_a)_{i+1}] \mid i = 1, \dots, \#\varepsilon_a - 1\}. \end{aligned}$$

In A_1 this creates the 1-sharblies $[v, (\varepsilon_a)_i, (\varepsilon_a)_{i+1}]$. These are reduced. Indeed, if $n_a \geq 0$, then

$$[v, (\varepsilon_a)_i, (\varepsilon_a)_{i+1}] = \gamma \cdot [e_1, e_2, \epsilon e_2],$$

³We also remark that for reduction level 1, only the second case of [18, §3.5 (III)] is needed.

where $\gamma = \begin{bmatrix} 0 & b^{-1} \\ \epsilon^{-i} & ab^{-1}\epsilon^{-i} \end{bmatrix} \in \mathrm{GL}_2(\mathcal{O})$. If $n_a < 0$, then

$$[v, (\varepsilon_a)_i, (\varepsilon_a)_{i+1}] = \gamma \cdot [e_1, e_2, \epsilon^{-1}e_2],$$

where $\gamma = \begin{bmatrix} 0 & b^{-1} \\ \epsilon^i & ab^{-1}\epsilon^i \end{bmatrix} \in \mathrm{GL}_2(\mathcal{O})$. A similar argument applies to the new 1-sharblies in A_2 , which are $[e_2, (\varepsilon_a)_{i+1}, (\varepsilon_a)_i]$; thus they are also reduced.

The regions A_3, A_4 are handled in the same manner. Along the edge $[e_2, v_b]$ we introduce the vertices

$$\varepsilon_b = \left\{ \begin{bmatrix} 0 \\ z \end{bmatrix} \mid z \in \mathcal{I}(b) \right\}.$$

As before $\#\mathcal{I}(b) \geq 2$, and we put ε_b^0 to be ε_b with the first and last vector removed. Add edges

$$\begin{aligned} & \{[w, v] \mid w \in \varepsilon_b^0\}, \quad \{[w, v_a] \mid w \in \varepsilon_b^0\}, \quad \text{and} \\ & \{[(\varepsilon_b)_i, (\varepsilon_b)_{i+1}] \mid i = 1, \dots, \#\varepsilon_b - 1\}. \end{aligned}$$

The 1-sharblies added in region A_3 are $[v_a, (\varepsilon_b)_i, (\varepsilon_b)_{i+1}]$; those added in region A_4 are $[v, (\varepsilon_b)_{i+1}, (\varepsilon_b)_i]$. Both types are reduced as above. The result, after completing all steps in this section, is the chain of 1-sharblies depicted in the right of Figure 1.

8. NORMAL FORMS

An important aspect of the reduction algorithm is choosing reducing points Γ -equivariantly. This means the following. Suppose that \mathbf{u} and \mathbf{u}' are two 1-sharblies that appear in a 1-sharply cycle $\xi \bmod \Gamma$ with coefficient 1, and that an edge $[x_1, x_2]$ of \mathbf{u} cancels an edge $[x'_1, x'_2]$ of \mathbf{u}' when $\partial\xi$ is taken mod Γ ; that is, there exists some $g \in \mathrm{GL}_2(\mathcal{O})$ such that $g \cdot [x_1, x_2] = -[x'_1, x'_2]$. Suppose further that these two edges are not reduced. Then when executing the reduction algorithm we begin by choosing reducing points w, w' for them, and we require that $g \cdot w = w'$. If this Γ -equivariance is not respected, then the output of the algorithm will not be a cycle mod Γ .

In [18, §§3.2–3.4], we presented a technique to do this. First we encode a 1-sharply cycle mod Γ as a collection of 1-sharblies with extra data attached to their edges, called *lift matrices*. These are 2×2 matrices over \mathcal{O} such that if two edges are $\mathrm{GL}_2(\mathcal{O})$ -equivalent, then their lift matrices are in the same $\mathrm{GL}_2(\mathcal{O})$ -orbit. Then when computing a reducing point for an edge, we first compute a unique representative of the $\mathrm{GL}_2(\mathcal{O})$ -orbit of its lift matrix. This representative is then fed into the reducing point algorithm.

Thus we must explain how to compute a normal form for any lift matrix. We use the technique of pseudo-matrices and their associated Hermite normal form [8].

Definition 8.1. A *pseudo-matrix* is a pair (I, A) , where $A = (a_{j,l})$ is an $m \times r$ matrix with entries in F , and $I = (\mathfrak{a}_i)$ is a sequence of fractional ideals called *coefficient ideals*.

Definition 8.2. A pseudo-matrix (I, A) is in *Hermite normal form* if there are $s \leq m$, $1 \leq i_1 < \dots < i_s$ such that for $1 \leq l < i_j$, we have $a_{j,l} = 0$, $a_{j,i_j} = 1$, and $a_{j,l}$ is reduced modulo $\mathfrak{a}_j \mathfrak{a}_l^{-1}$, and $a_{j,l} = 0$ for $j > s$.

We specialize to our case $m = k = 2$. For a matrix A , let A_i denote the i th row. For a matrix $A \in \text{Mat}_2(\mathcal{O})$, let M_A denote the \mathcal{O} -module generated by $\{A_1, A_2\}$. A pseudo-matrix consists of a triple $[I_1, I_2, A]$, where $I_i \subseteq \mathcal{O}$ are ideals, and $A \in \text{Mat}_2(\mathcal{O})$. For a pseudo-matrix $\mathcal{A} = [I_1, I_2, A]$, let $M_{\mathcal{A}}$ denote the \mathcal{O} -module

$$M_{\mathcal{A}} = \{a_1 A_1 + a_2 A_2 \mid a_i \in I_i\}.$$

Thus if $A \in \text{Mat}_2(\mathcal{O})$ and $\mathcal{A} = [\mathcal{O}, \mathcal{O}, A]$, then $M_A = M_{\mathcal{A}}$.

Given a pseudo-matrix $\mathcal{A} = [I_1, I_2, A]$, Magma's `HermiteForm` function returns a pair \mathcal{H}, T , where \mathcal{H} is pseudo-matrix $[J_1, J_2, H]$ in Hermite normal form, and $T \in \text{GL}_2(F)$ satisfies

$$M_{\mathcal{H}} = M_{\mathcal{A}} \quad \text{and} \quad H = T A.$$

Note that while A and H have entries in \mathcal{O} , the entries of T lie in F in general. Note, however, that $J_i \cdot T_i \subseteq \mathcal{O}^2$ for $i = 1, 2$. Since F is class number one, we can pick generators $g_i \in \mathcal{O}$ such that $J_i = g_i \mathcal{O}$. Then $g_i T_i \in \mathcal{O}^2$, and thus $\tilde{T} = \begin{bmatrix} g_1 T_1 \\ g_2 T_2 \end{bmatrix} \in \text{GL}_2(\mathcal{O})$. Let $\tilde{H} = \begin{bmatrix} g_1 H_1 \\ g_2 H_2 \end{bmatrix}$. If \mathcal{A} comes from a matrix A so that $\mathcal{A} = [\mathcal{O}, \mathcal{O}, A]$, then we have $\tilde{H} = \tilde{T} A$.

If we wish to use the theory of Hermite normal forms to produce normal forms for matrices using the remark above, we need a section to the map

$$\mathcal{O} \rightarrow \mathcal{O}/\mathcal{O}^\times.$$

Let $a \in \mathcal{O}$ be the element for which we wish to produce a representative modulo units. First construct the ideal $\mathfrak{a} = a\mathcal{O}$. Then compute a \mathbb{Z} -basis for \mathfrak{a} , and compute the Hermite normal form (over \mathbb{Z}) of the matrix of this basis. This will produce a sequence $L \subset \mathcal{O}$ which generates \mathfrak{a} . In Magma, we create another ideal \mathfrak{b} generated by L . Note that

- (i) $\mathfrak{b} = \mathfrak{a}$.
- (ii) The generators \mathfrak{b} only depend on the ideal \mathfrak{a} , not the original choice of generator a .

Since F is class number one, Magma will produce a generator a_0 for \mathfrak{b} , which only depends on the generators L . This a_0 is the representative for a modulo units.

This procedure, combined with Hermite normal form for pseudo matrices and the remark above allow us to, given $A \in \text{Mat}_2(\mathcal{O})$, output a Hermite normal form \tilde{H} and transformation matrix \tilde{T} such that

- (i) $\tilde{H} = \tilde{T} A$.
- (ii) If $A' = gA$ for some $g \in \text{GL}_2(\mathcal{O})$, then $\tilde{H}' = \tilde{H}$.

This completes the computation of normal forms, but there is still one implementation detail of interest. Recall that we really only need the normal form to ensure all reducing points are chosen Γ -equivariantly. A key step in computing a reducing point is computing the cone containing the barycenter of the line through $q(v_1)$ and $q(v_2)$, where v_i are the columns of the lift matrix (cf. [18, §3.3]). By abuse of notation, we will call this the cone containing the lift matrix.

It turns out that for a typical lift matrix A arising in our computations, the cone containing A is much closer to the ‘‘standard’’ cones (i.e., cones appearing as faces of the perfect pyramids from Theorem 4.1) than the cone containing the Hermite normal form \tilde{H} . This means that if we use Hermite normal form as the input to

our code that computes reducing points, then our code will waste considerable time trying to compute the cone containing \tilde{H} .

We address this issue as follows by caching normal forms as we compute them. Given a matrix $A \in \text{Mat}_2(\mathcal{O})$, we compute the pseudo matrix Hermite normal form \mathcal{H} . If \mathcal{H} shows up on our master list, we return the associated normal form A_0 . If \mathcal{H} is not on the master list, we set $A_0 = A$ to be the normal form associated to \mathcal{H} . In practice we go ahead and compute the reducing point for A as well before adding the data to the master list.

9. COMPUTATIONAL RESULTS

We conclude by presenting our computational results, from both the cohomology and elliptic curve sides. The techniques are very similar to that of [15], so we will be brief. As before our programs were implemented in Magma [6]. We remark that, as in [15], to avoid floating-point precision problems we did not use the complex numbers \mathbb{C} as coefficients for H^4 , but instead computed cohomology with coefficients in the large finite field \mathbb{F}_{12379} . We expect that the Betti numbers we report coincide with those one would compute for the group cohomology with \mathbb{C} -coefficients.

As in [15], we began by computing the dimension of H^4 for a large range of level. To determine if $H_{\text{cusp}}^4 \neq 0$, we experimentally determined the dimensions of the subspace H_{Eis}^4 spanned by *Eisenstein cohomology classes* [19]. Such classes are closely related to Eisenstein series. In particular the eigenvalue of $T_{\mathfrak{q}}$ on these classes equals $\text{Norm}(\mathfrak{q}) + 1$. We expect that for a given level \mathfrak{n} , the dimension of the Eisenstein cohomology space depends only on the factorization type of \mathfrak{n} . Thus initially we used some Hecke operators applied to cohomology spaces of small level norm to compute the expected Eisenstein dimension for small levels with different factorization types. The result can be found in Table 4. After compiling this table, we were able to predict which levels had cohomology in excess of the Eisenstein subspace, and thus gave candidates for cuspidal classes.

Next we computed the Hecke operators. Our primary focus was to find eigenclasses with rational eigenvalues, and in fact this was almost always the case: for all levels except level norm $529 = 23^2$, the Hecke eigenvalues were rational. Altogether we computed the cohomology at 308 different levels, which includes all ideals with level norm ≤ 835 .

We now turn to the elliptic curve side. We compiled a list of elliptic curves over F of small norm conductor simply by searching over a box of Weierstrass equations. More precisely, for a positive integer B , let

$$S_B = \{c_0 + c_1t + c_2t^2 \mid |c_i| \leq B, 0 \leq i \leq 2\},$$

be a boxed grid of size $(2B+1)^3$ inside the lattice of algebraic integers in F , centered at the origin. We considered equations of the form

$$E : y^2 + a_1xy + a_3 = x^3 + a_2x^2 + a_4x + a_6, \text{ with } a_1, a_2, a_3, a_4, a_6 \in S_B.$$

and took $B = 2$. For each non-zero discriminant ≤ 10000000 , we kept those of norm conductor ≤ 20000 to arrive at a list of elliptic curves of small norm conductor. This consisted of 26445 curves lying in 1518 isomorphism classes. Of course with such a naive method we have no way of knowing whether or not we have found all isomorphism—or even isogeny—classes of curves up to some bound. Nevertheless,

this enables us to obtain a list of curves of various conductors, which must then be reconciled with the cohomology data.

Finally we compare the two sides. In every case, we found perfect agreement:

- (i) In all cases where an eigenspace was one-dimensional with rational Hecke eigenvalues, we found an elliptic curve over F whose point counts over finite fields agreed with our Hecke data, at least within the range where we were able to compute both sides. There were 44 levels where this occurred; the curves are given in Table 5. Generators for the conductors of these curves are given in Table 6.
- (ii) For no level/conductor of norm ≤ 835 did we find a curve over F that was not accounted for by a Hecke eigenclass, or a Hecke eigenclass that could not be matched to a curve.
- (iii) In 10 levels we encountered a two-dimensional eigenspace on which the Hecke operators acted by rational scalar matrices. These were “old” cohomology classes and can be accounted for by cohomology classes at lower levels. Table 7 records the data.
- (iv) At norm level $529 = 23^2$, we found a two-dimensional cuspidal subspace where the eigenvalues live in $\mathbb{Q}(\sqrt{5})$. The eigenvalues of this cohomology class match those of the weight two newform of level 23.

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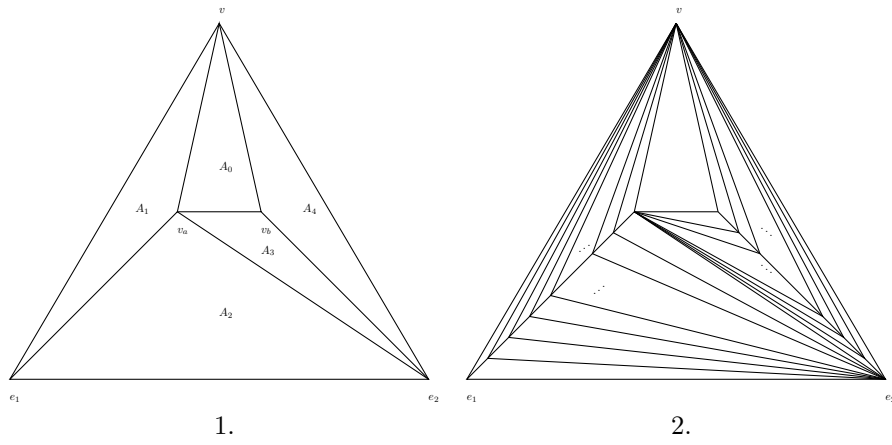


FIGURE 1. Reduction of Type-0 1-sharply.

Order	Group	Generators
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \gamma\delta$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} 1 & -t^2 + 1 \\ 0 & -1 \end{bmatrix}$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \gamma$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \gamma$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} -1 & 0 \\ t & 1 \end{bmatrix}$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \gamma$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
12	D_6	$\begin{bmatrix} 1 & 1 \\ -1 & 0 \end{bmatrix}, \gamma$

TABLE 1. The stabilizer groups of the 3-cones in the Koecher fan Σ . See Proposition 4.3 for notation.

Order	Group	Generators
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} 1 & -t^2 + 1 \\ 0 & -1 \end{bmatrix}$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
8	D_4	$\gamma\delta, \begin{bmatrix} 0 & -t^2 + t \\ -t & 0 \end{bmatrix}$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} -1 & t^2 - t \\ 0 & 1 \end{bmatrix}$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} 1 & 1 \\ 0 & -1 \end{bmatrix}$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \gamma$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} -t & t^2 \\ -t & t \end{bmatrix}$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
2	$\mathbb{Z}/2\mathbb{Z}$	$-I$
4	$\mathbb{Z}/4\mathbb{Z}$	$\begin{bmatrix} t^2 & 1 \\ -t^2 + t & -t^2 \end{bmatrix}$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} -1 & 0 \\ t & 1 \end{bmatrix}$
4	$\mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z}$	$-I, \begin{bmatrix} t^2 - t & -t^2 + t \\ t^2 & -t^2 + t \end{bmatrix}$

TABLE 2. The stabilizer groups of the 4-cones in the Koecher fan Σ . See Proposition 4.3 for notation.

k	1	2	3	4	5	6	7
N_k	1	2	10	31	47	35	9

TABLE 3. The number N_k of $\mathrm{GL}_2(\mathcal{O})$ -orbits of cones of dimension k in the Koecher fan Σ .

Factorization of \mathfrak{n}	\mathfrak{p}	\mathfrak{p}^2	$\mathfrak{p}\mathfrak{q}$	\mathfrak{p}^3	$\mathfrak{p}\mathfrak{q}^2$	$\mathfrak{p}\mathfrak{q}\mathfrak{r}$
$\dim H_{\mathrm{Eis}}^4(\Gamma_0(\mathfrak{n}))$	3	5	7	7	11	15

TABLE 4. Expected dimension of Eisenstein cohomology $H_{\mathrm{Eis}}^4(\Gamma_0(\mathfrak{n}))$ in terms of the prime factorization of \mathfrak{n} . Prime ideals are denoted by $\mathfrak{p}, \mathfrak{q}, \mathfrak{r}$.

Norm(n)	a_1	a_2	a_3	a_4	a_6
89	$t - 1$	$-t^2 - 1$	$t^2 - t$	t^2	0
107	0	$-t$	$-t - 1$	$-t^2 - t$	0
115	$-t^2 + t - 1$	$-t^2 + 1$	$t - 1$	-1	$-t^2$
136	$-t^2$	-1	$-t^2 + 1$	$t + 1$	0
161	$t^2 - t - 1$	$-t^2 + t - 1$	$t^2 - t + 1$	$t^2 - t$	$t - 1$
167	$t^2 + 1$	$t + 1$	$t^2 + t - 1$	$-t^2 - t + 1$	$-t^2 + t + 1$
185	t	$-t^2 + t + 1$	$t + 1$	0	0
223	1	t^2	$t^2 + t - 1$	$-t^2 + t - 1$	1
253	-1	$-t^2 - t$	$-t^2 - t$	$-t^2 - t$	0
259	0	1	$-t^2 - t - 1$	$t^2 - t + 1$	$-t^2 - t + 1$
275	$-t^2 + t$	t	$t^2 - t$	0	0
289	-1	$t^2 - t$	t	1	0
293	$t^2 - 1$	$-t + 1$	$t^2 - t + 1$	0	0
344	$t - 1$	$-t^2 - t$	$-t^2 + t + 1$	$t^2 - 1$	0
359	$-t^2 + 1$	$t + 1$	$t^2 + 1$	$t^2 - t$	$-t + 1$
385	$-t^2$	$-t^2 - t - 1$	$-t^2 - 1$	$t^2 + t$	$-t^2 + 1$
392	$-t^2 + 1$	$-t^2 + t + 1$	$-t + 1$	$t^2 - 1$	t
440	$-t^2 + 1$	$-t^2 - t + 1$	$-t^2$	$-t$	0
449	$-t^2$	1	$-t^2 + t + 1$	$t + 1$	0
475	0	$-t$	$t^2 + t$	$t^2 - t + 1$	$-t^2 + 1$
503	$-t^2 + t$	$-t^2 + t + 1$	$-t^2 + t$	$-t^2 + t$	0
505	$t^2 - t$	$t^2 - t + 1$	$t^2 + t$	$t^2 - t + 1$	$-t^2 + 1$
505	$t^2 - t - 1$	$t^2 - 1$	0	$t - 1$	0
512	0	$t^2 + 1$	0	t^2	0
553	t	1	t	0	0
593	t	$-t - 1$	t^2	$-t^2 + t + 1$	0
595	$-t^2 + t - 1$	$-t^2 + t + 1$	$-t^2 + t + 1$	$-t^2 + t + 1$	0
625	t	$-t - 1$	$t^2 + 1$	1	$-t^2$
649	$-t^2 - t - 1$	$-t$	0	$-t^2 + t - 1$	0
665	$-t$	$-t^2 + 1$	$-t^2 + t$	$-t^2 + t$	0
685	$t^2 - 1$	$-t^2 + t$	$-t^2 + 1$	$-t - 1$	t^2
712	$2t^2 - t - 1$	$-t^2 - 2t + 2$	$t + 2$	$2t^2 + 2t$	$-2t^2 - t$
719	$-t^2 + t$	$-t^2 + t - 1$	-1	0	0
719	$t^2 - t - 1$	$-t^2 + t - 1$	0	$t^2 - t$	0
721	$-t^2 + t + 1$	$-t^2 + t - 1$	$t^2 + 1$	$-t - 1$	$-t + 1$
727	1	$t^2 + t - 1$	$t^2 - t$	-1	0
773	$2t^2 - 1$	$2t + 1$	$2t^2 + 2t$	$-t^2 + 2t + 1$	$-2t^2 - t$
805	$-t^2 - 2t + 2$	$-2t^2 + 2t$	$t^2 - t - 1$	$-2t^2 + t + 2$	$-2t^2 - t$
808	$-t - 2$	0	$2t^2 - t - 2$	$-2t^2 + 2t + 2$	$-2t^2 - t$
809	$-t^2 + t - 1$	$t^2 - 1$	$t^2 + 1$	$t^2 - t$	$-t^2$
809	$t^2 - 1$	$t^2 + t - 1$	$t^2 - t$	$t^2 - t$	0
817	$-t^2 + t$	$-t^2$	$t^2 - t + 1$	-1	0
829	0	$-t^2$	$t^2 - t - 1$	0	0

TABLE 5. Equations for elliptic curves over F . Here t is a root of $x^3 - x^2 + 1$.

$N(\mathfrak{n})$	generator	$N(\mathfrak{n})$	generator	$N(\mathfrak{n})$	generator	$N(\mathfrak{n})$	generator
89	$4t^2 - t - 5$	107	$-5t^2 + 3t$	115	$-2t^2 - 2t - 3$	136	$6t^2 - 2t - 2$
161	$-5t^2 + 5t + 4$	167	$-5t^2 + 3t - 3$	185	$-t^2 - 5t + 4$	223	$6t^2 - 5t - 2$
253	$7t^2 - 5t - 5$	259	$4t^2 - 7t - 1$	275	$8t^2 - 2t - 3$	289	$3t^2 - 7t - 2$
293	$-5t^2 - 2t - 2$	344	$6t^2 - 2t - 8$	359	$7t^2 - 6t - 2$	385	$-6t^2 + 7t + 5$
392	$-8t^2 + 6t + 6$	440	$8t^2 + 2t - 6$	449	$t^2 - 8t$	475	$-4t^2 - 7t$
503	$t^2 - t - 8$	505	$-2t^2 - 7t + 2$	505	$-8t + 1$	512	8
553	$9t^2 - 4t - 2$	593	$8t^2 - t - 9$	595	$11t^2 - 4t - 6$	625	$8t^2 + 3t + 1$
649	$8t^2 + t - 8$	665	$9t^2 + t - 8$	685	$-7t^2 + 5t - 7$	712	$6t^2 - 10t - 8$
719	$t^2 - t - 9$	719	$11t^2 - 4t - 5$	721	$8t^2 - 9$	727	$10t^2 - 7t - 7$
773	$-3t^2 + 12t - 5$	805	$3t^2 - 6t - 10$	808	$-6t^2 - 2t - 4$	809	$9t^2 - 9t - 1$
817	$-t^2 - 7t - 8$	829	$6t^2 - t - 10$				

TABLE 6. Generators for ideals arising as conductors of elliptic curves. Here t is a root of $x^3 - x^2 + 1$. The two curves labelled 809 in Table 5 share the level of norm 809 in this table. The curves labelled 505 and 719 have different conductors, as indicated by the levels in this table.

$N(\mathfrak{n})$	generator	Norm of original level
445	$2t^2 - 5t - 8$	89
535	$-7t^2 + 8t + 2$	107
575	$-9t^2 + t + 9$	115
623	$10t^2 + 2t - 7$	89
680	$-6t - 8$	136
712	$6t^2 - 10t - 8$	89
749	$-8t^2 + t - 2$	107
805	$-t^2 + 10t + 4$	161
805	$3t^2 - 6t - 10$	115
835	$-10t^2 + 8t - 1$	167

TABLE 7. “Old” cohomology classes. In every instance the eigenspace was two-dimensional, with the Hecke operators acting by scalar matrices. The eigenvalues originally occur at the levels in the third column. Here t is a root of $x^3 - x^2 + 1$.