

Homework 4.2

Stat 605, Fall 2018

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Due Thursday, October 4

In class, I mentioned that by making an analogy with inner products of vectors in \mathbb{R}^3 one might interpret $\rho(X, Y)$ as the cosine of the angle between $X - \mathbb{E}X$ and $Y - \mathbb{E}Y$. Therefore, one might say that correlation measures the degree to which the deviations of X and Y from their expectations point in the same direction. The following problem is intended to clarify a subtly different statement about correlation: Correlation measures the strength of the linear relationship between two random variables.

Problem 1 (1+2+2 points). *Let $X, Y : (\Omega, \mathcal{F}, \mathbb{P}) \rightarrow (\mathbb{R}, \mathcal{B})$ be random variables.*

1. *Write down an L^2 -orthonormal basis for $\text{span}\{Y, \mathbf{1}\}$. Here, $\mathbf{1}$ denotes the constant random variable with value 1. Note that $\text{span}\{Y, \mathbf{1}\}$ is the set of all linear functions $\alpha Y + \beta$ of Y .*
2. *Write down a formula for the orthogonal projection of X onto $\text{span}\{Y, \mathbf{1}\}$. Try to make the correlation $\rho(X, Y)$ appear in this formula.*
3. *Define*

$$d(X, \text{span}\{Y, \mathbf{1}\}) = \min_{Z \in \text{span}\{Y, \mathbf{1}\}} \|X - Z\|_2.$$

Derive a formula expressing $d(X, \text{span}\{Y, \mathbf{1}\})$ in terms of $\rho(X, Y)$ and $\text{var}(X)$. Note: When statisticians say things about R^2 values and the proportion of the variation in X explained by a linear regression on Y , they are using a version of this formula.

Recall that for $X : (\Omega, \mathcal{F}, \mathbb{P}) \rightarrow (U, \mathcal{S})$ a random variable, we define the σ -algebra generated by X to be

$$\sigma(X) = \{X^{-1}(B); B \in \mathcal{S}\}$$

(I believe that this definition first appeared in our discussion of independent random variables.) The σ -algebra $\sigma(X)$ is sometimes called the information contained in X . To see why, work out the following problem.

Problem 2 (2+4 points). For \mathcal{G} a σ -algebra on Ω , we call a map $H : \Omega \rightarrow \mathbb{R}$ \mathcal{G} -measurable if $H^{-1}(B) \in \mathcal{G}$ for all $B \in \mathcal{B}$. We say that a function $H : \Omega \rightarrow \mathbb{R}$ is \mathcal{G} -simple if it is a \mathcal{G} -measurable simple function.

1. Show that the set of all \mathcal{G} -measurable maps is the smallest class containing the simple functions and closed under pointwise limits. Note: Most of the work here has been done in class.
2. Show that Y is $\sigma(X)$ -measurable if and only if $Y = f(X)$ for some measurable $f : (\mathbb{R}, \mathcal{B}) \rightarrow (\mathbb{R}, \mathcal{B})$. In particular, if two random variables contain the same information, then they are functions of each other.

We will see that many properties of a random variable depend only on the information which it contains. For example, $X \perp\!\!\!\perp Y$ implies that $X' \perp\!\!\!\perp Y'$ for any $\sigma(X)$ -measurable X' and $\sigma(Y)$ -measurable Y' . Later, we will see that the conditional expectation $\mathbb{E}[X|Y]$ depends only on X and the information contained in Y .

The results in this problem may possibly be useful below.

Problem 3 (1+1+1 points). A random variable X is said to be a Bernoulli trial with probability of success p if X takes only the values $\{0, 1\}$ and $\mathbb{P}[X = 1] = p$. Let $\{X_i\}_{i=1}^{\infty}$ be independent Bernoulli trials, and define

$$T = \inf\{m : X_m = 1\}.$$

The distribution of T is called the geometric distribution. Since T takes values in the countable set \mathbb{N} , this distribution is characterized by the probability mass function $f_T : \mathbb{N} \rightarrow \mathbb{R}$ by

$$f_T(t) = \mathbb{P}[T = t].$$

1. Find a formula expressing $f_T(t)$ in terms of p and t .
2. Compute $\mathbb{E}[T]$.
3. Compute $\text{var}(T)$.

This next problem is extra credit. If you like, you can use the result below even if you do not turn in a proof. It is helpful to introduce some new terminology here: We say that the functions $f, g : \mathbb{R} \rightarrow \mathbb{R}$ are asymptotic in the limit as x tends to c if

$$\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = 1.$$

Here, c may be a real number or it may be infinity. When f is asymptotic to g in some limit, we write $f \sim g$. It is important to note that this definition is really only interesting when either f and g both tend to zero in the limit or both tend to infinity in the limit. Otherwise, at least if both limits exist, f is asymptotic to g if and only if the limits are equal.

Problem 4 (1 points). Show that $n \sum_{m=1}^n m^{-1} \sim n \log n$ as $n \rightarrow \infty$.

Problem 5 (1 point). Let $\{Y_n\}$ be a sequence of random variables and v_n a sequence of real numbers so that $\text{var}(Y_n)/v_n^2 \rightarrow 0$ as $n \rightarrow \infty$. Show that

$$\frac{Y_n - \mathbb{E}Y_n}{v_n} \xrightarrow{\text{P}} 0.$$

Problem 6 (5 points). Let $\{X_i\}_{i=1}^\infty$ be independent random variables, each having the uniform distribution on the finite set $\{1, 2, \dots, n\}$. Let

$$\tau_k^n = \inf\{m : \#\{X_1, \dots, X_m\} = k\}$$

be the least index m for which the sequence X_1, \dots, X_m takes k distinct values. (Here, we use $\#S$ to denote the cardinality of the set S .) To make this more concrete, let us suppose that you like watching birds and that you will stop only once you have seen every bird on a list of n birds. If we assume that the birds are observed with equal probability and that the observations are independent, then τ_n^n is a good model for the total number of observations that you will make before stopping. Prove that

$$\frac{\tau_n^n}{n \log n} \xrightarrow{\text{P}} 1.$$

Hint: Use the results of the previous three problems.