Homework 8

Math 651 Fall 2019

Due Friday, November 22, 2019

Consider Newton's equations

$$x' = v$$
, and
 $v' = -\nabla V(x)$

for some potential energy $V : \mathbb{R}^d \to \mathbb{R}$. (Here, $x : [0, \infty) \to \mathbb{R}^d$, $v : [0, \infty) \to \mathbb{R}^d$.) Newton's equations model the motion of the planets, the vibrations of molecules, and many other phenomena. The simplest example of a system governed by Newton's equations is the harmonic oscillator

$$\begin{cases} x' = v, \text{ and} \\ v' = -x, \end{cases}$$

for which the potential energy is

$$V(x) = \frac{1}{2}x^2.$$

Problem 1 (2+2+2 points).

1. Let x and v solve Newton's equations with potential energy V. Define the Hamiltonian

$$H(x,v) = \frac{1}{2}|v|^2 + V(x).$$

Show that H(x(t), v(t)) = H(x(0), v(0)) for all t > 0. This property is of extreme importance in physics: it is called conservation of energy.

Hint: What is $\frac{d}{dt}H(x(t),v(t))$ when x and v solve Newton's equations?

2. Use Euler's method to solve the initial value problem for the harmonic oscillator with $x_0 = 1$ and $v_0 = 0$. Compute the numerical solution up to time T = 30 using the time step $\Delta t = 0.02$. Plot the numerical solution (x_n, v_n) as a curve in the xv plane. You should see a spiral. Plot the Hamiltonian as a function of time for the numerical solution. Observe that the Hamiltonian is not conserved for Euler's method!

3. Define the Störmer–Verlet Method

$$v_{n+\frac{1}{2}} = v_n - \frac{1}{2}\Delta t \nabla V(x_n)$$

$$x_{n+1} = x_n + \Delta t v_{n+\frac{1}{2}}$$

$$v_{n+1} = v_{n+\frac{1}{2}} - \frac{1}{2}\Delta t \nabla V(x_{n+1}).$$

Observe that Störmer-Verlet is similar to Euler's Method, except that the update of the variable v is split into two pieces. Use Störmer-Verlet to solve the initial value problem for the harmonic oscillator with $x_0 = 1$ and $v_0 = 0$. Compute the numerical solution up to time T = 30 using the time step $\Delta t = 0.02$. Make the same plots as for Euler's method. Observe that the Hamiltonian is nearly conserved.

Remark 1. The Störmer–Verlet Method is a *symplectic integrator*. Symplectic integrators preserve certain geometric properties of Newton's equations. In general, for symplectic integrators, the Hamiltonian is not exactly constant over trajectories, but one can show that a slightly perturbed version of the Hamiltonian is very nearly constant. No such property holds for Euler's method.

Problem 2 (3 points). Recall that the trapezoidal rule is the numerical integrator defined by

$$x_{n+1}=x_n+\frac{\Delta t}{2}(f(x_n,n\Delta t)+f(x_{n+1},(n+1)\Delta t))).$$

Find the linear stability domain of the trapezoidal rule.

Problem 3 (2+2+4+2 points). Recall that the implicit Euler method is the numerical integrator defined by

$$x_{n+1} = x_n + \Delta t f(x_{n+1}, (n+1)\Delta t).$$

Assume that the right-hand-side $f : \mathbb{R}^n \times [0, \infty) \to \mathbb{R}^n$ of the initial value problem is globally Lipschitz with constant L. That is,

$$||f(x,t) - f(y,t)|| \le L||x - y||$$

for all $x, y \in \mathbb{R}^n$. Let T > 0. Assume that $\Delta tL \leq \frac{1}{2}$.

1. Prove that the implicit Euler method is consistent of order one. That is, show that for any $t \in [0, T - \Delta t]$,

$$\|x(t + \Delta t) - x(t) - \Delta t f(x(t + \Delta t), t + \Delta t)\| \le C \Delta t^2,$$

where x(t) is the exact solution of the IVP and C is some constant that may depend on x(t) but that does not depend on Δt . You may assume without comment that x(t) is twice continuously differentiable. 2. To assist in your proof of stability below, show that whenever $\Delta tL \leq \frac{1}{2}$, we have

$$\frac{1}{1 - \Delta tL} \le \exp\left(2L\Delta t\right)$$

3. Prove that the implicit Euler method is stable. To be more precise, suppose that y_n solves

$$y_{n+1} = y_n + \Delta t f(y_{n+1}, (n+1)\Delta t) + G_n,$$

where $||G_n|| \leq \varepsilon$. Show that

$$\max_{n=0,\dots,\left\lfloor\frac{T}{\Delta t}\right\rfloor} \|y_n - x_n\| \le \frac{\varepsilon}{\Delta tL} \exp\left(2LT\right).$$

4. Prove that the implicit Euler method is convergent of order one. That is, show

$$\max_{n=0,\dots,\left\lfloor\frac{T}{\Delta t}\right\rfloor} \|x_n - x(n\Delta t)\| \le D\Delta t \exp\left(2LT\right)$$

for some constant D that may depend on the exact solution x(t) of the IVP but that does not depend on Δt .

Problem 4 (5 points). Let $f \in C([0,1])$, and let $u \in C^2([0,1])$ be a solution of the boundary value problem

$$\begin{cases} u''(x) = f(x) & \text{for } x \in (0,1), \\ u(0) = 0, \\ u(1) = 0. \end{cases}$$

 $Show \ that$

$$\|u\|_{\infty} \le \frac{1}{8} \|f\|_{\infty}.$$

Hint: Mimic the argument for the discrete analogue of this result. Use the comparison function

$$\phi(x) := \frac{1}{2} \left(x - \frac{1}{2} \right)^2.$$

Problem 5 (2+1+2 points). Define the forwards finite difference operator $D_{\Delta x}: \mathbb{R}^{N-1} \to \mathbb{R}^{N-1}$ by

$$(Dv)_i = \frac{v_{i+1} - v_i}{\Delta x}$$
 for $i = 1, \dots, N - 1$.

When i = N - 1 above, we set $v_N = 0$. Recall that we adopted a similar convention in defining the discrete Laplacian Δ_{Δ_x} .

1. Define the backwards difference

$$(D_{\Delta x}^{-}v)_{i} := \frac{v_{i} - v_{i-1}}{\Delta x} \text{ for } i = 1, \dots, N-1,$$

where again we take $v_0 = 0$. Show that $-D_{\Delta x}^{t} = D_{\Delta x}^{-}$.

Hint: The right way to do this is to show $\langle D_{\Delta x}u, v \rangle = -\langle u, D_{\Delta x}^-v \rangle$ for all $u, v \in \mathbb{R}^{N-1}$. You don't ever have to explicitly write the difference operator as a matrix, and that makes everything easier.

- 2. What does the above have to do with integration by parts?
- 3. Show that $\Delta_{\Delta x} = -D_{\Delta x}^{t}D_{\Delta x}$.

Hint: Again, the right way is to show that $\langle \Delta_{\Delta x} u, v \rangle = -\langle D_{\Delta x} u, D_{\Delta x} v \rangle$. You shouldn't ever have to explicitly write down and multiply matrices.

The problem above will be continued next week—you'll see the point eventually.