

5.3. Diagonalization of square matrices

- Diagonal matrices are "the simplest" ones: they behave as n numbers acting in n directions.

- Diagonalization of A means A is presented as PDP^{-1} for some diagonal matrix D .

- Matrix A can be diagonalized iff there is a basis consisting of A eigenvectors v_1, \dots, v_n . Then $P = [v_1 \dots v_n]$ the matrix whose columns are the eigenvectors v_1, \dots, v_n . Also, $D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$ where $Av_i = \lambda_i v_i$.

Procedure:

- Find all eigenvalues.
- For each eigenvalue λ find a basis B_λ of the eigenspace V_λ .
- If the size of B_λ is the multiplicity m_λ of λ , then the union of all B_λ for all λ is a basis B of eigenvectors.

§5.3 Diagonalization:

A diagonalization of a matrix A is a matrix D which is diagonal and an invertible matrix P, such that $A = P D P^{-1}$.

P -conjugate of D
 A, D similar.
 claim:

A: Motivation: calculation of powers

example $A = \begin{bmatrix} 1 & 2 \\ -4 & 1 \end{bmatrix}$

$A = P D P^{-1}$

for $D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}$ & $P = \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix}$

Q. $A^{1000} = \overbrace{A \cdot A \cdot \dots \cdot A}^{1000} = ?$ (n times)

$A^n = (P D P^{-1})^n = \underbrace{P D P^{-1} \cdot P D P^{-1} \cdot \dots \cdot P D P^{-1}}_n = P \cdot \underbrace{D \cdot \dots \cdot D}_n \cdot P^{-1} = P (D^n) P^{-1}$

$D^n = D^{1000} = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}^{1000} = \begin{bmatrix} 5^{1000} & 0 \\ 0 & 3^{1000} \end{bmatrix}$

Rule

$\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} = \begin{bmatrix} a^2 & 0 \\ 0 & b^2 \end{bmatrix}$

diagonal entries get multiplied!

$A^{1000} = \underbrace{\begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix}}_P \cdot \underbrace{\begin{bmatrix} 5^{1000} & 0 \\ 0 & 3^{1000} \end{bmatrix}}_{D^{1000}} \cdot \underbrace{\begin{bmatrix} 2 & 1 \\ -1 & 1 \end{bmatrix}}_{P^{-1}}$

Calculation of powers! easy!

A2. Powers of matrices represent repeated processes:

A matrix A describes a lin. transform $T(x) = Ax$

In applications: T is a description of some process. Then $T^n = \underbrace{T \cdots T}_n T$ describes the process repeated

n times. Here $T^n(x) = A^n x$.

of interest is how this behaves for large n . } iteration of a process

A3. Ex. Dynamical systems:

Consider an ecological system in woods:

x = # squirrels

y = # wolves

$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x' \\ y' \end{pmatrix} = \left\{ \begin{array}{l} \text{the same but} \\ \text{one year later!} \end{array} \right.$

Then $T^n \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \#S \\ \#W \end{pmatrix}$ (population) after n years.

- population after a long time:
- stable state: does not change much
- catastrophy: $\left\{ \begin{array}{l} \text{die out} \\ \text{explode} \end{array} \right\} =$

A4. Conclusion: • A diagonalization of a matrix A means presenting A as PDP^{-1} for some matrix P and a diagonal matrix D .

- This is useful because calculations with D are much simpler!

B. Which matrices A can be diagonalized?

TL;DR A can be diagonalized if \mathbb{R}^n has a basis $\mathcal{B} = \{b_1, \dots, b_n\}$ of eigenvectors of A , i.e., $Ab_i = \lambda_i b_i$ for some λ_i .

(b) Then we can choose D as $D = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{bmatrix}$
and $P = P_{\mathcal{B}} = [b_1 \dots b_n]$ columns in \mathcal{B} .

Proof. $Ab_i = \lambda_i b_i$ and also

Claim (*) $PDP^{-1}b_i = \lambda_i b_i$ (as we will see!).

Then $A = PDP^{-1}$:

(*) $\left\{ \begin{array}{l} A \text{ and } B = PDP^{-1} \text{ act the same on some basis } \mathcal{B}, \\ \text{they must be the same matrices!} \end{array} \right. \quad \text{i.e. } A = B (= PDP^{-1})$

Proof: Matrices A, B act the same on all of (*) linear combinations of vectors b_i

- These are all vectors! (since \mathcal{B} is a basis)
- In particular $Ab_i = Bb_i$.
- However, these are the i^{th} column A_i and B_i of A & B .
- So, $A_i = B_i$ hence $A = B$!

So, it suffices to check that

$$P D P^{-1} b_i = \lambda_i b_i.$$

However, $P e_i =$ i^{th} column of $P = b_i$.
hence $P^{-1} b_i = e_i$. $\begin{matrix} \downarrow \\ P^{-1} \end{matrix}$

Therefore:

$$P D P^{-1} b_i = P D e_i$$

and since $D e_i =$ i^{th} column of $D =$

For a diagonal D , e_i 's are eigenvectors!

$$= \lambda_i e_i$$

we have:

$$\begin{aligned} P D P^{-1} b_i &= P D e_i = P \lambda_i e_i = \\ &= \lambda_i P e_i = \lambda_i b_i \end{aligned}$$

□

C. For which A is there a basis of eigenvectors?

T2. If an $n \times n$ matrix A has

n different eigenvalues $\lambda_1, \dots, \lambda_n$ then
 A can be diagonalized! (because it has a basis of eigenvectors)

Pf. Let v_i be an eigenvector for A ,
with eigenvalue λ_i , so $A v_i = \lambda_i v_i$.

Then v_1, \dots, v_n are independent. !!!

But then this is a basis (since
we have n independent vectors in \mathbb{R}^n !).

Now we know diagonalization by T1. □

Di Example 5:

$$A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix}$$

We want to

Diagonalize!

Find a basis of eigenvectors

Factor it into linear

We will find a basis of eigenvectors & diagonalize.

Step 1. Calculate

$$\det(A - \lambda I) =$$

$$= \lambda^3 - 3\lambda^2 + 4$$

terms:

$$= -(\lambda - 1)(\lambda + 2)^2$$

So, eigenvalues are $\lambda_1 = 1, \lambda_2 = \lambda_3 = -2$

Step 2. Find eigenvectors for eigenvalues:

$$v_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$v_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

for $\lambda_1 = 1$

for $\lambda_2 = -2$

for $\lambda_3 = -2$

Remark: Here, the three eigenvalues $\lambda_1, \lambda_2, \lambda_3$ were not all different but we were lucky and we still

found 3 independent eigenvectors!

then it is a basis of \mathbb{R}^3

Step 3.

$$P = [v_1 \ v_2 \ v_3] =$$

$$\begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

use TI:

$$D = \begin{bmatrix} 1 & & \\ & -2 & \\ & & 2 \end{bmatrix}$$

eigenvalues of A

and

$$A = P D P^{-1}$$

by TI. ! \square

$$E2. A = \begin{bmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{bmatrix}$$

$$\det(A - \lambda I) = -(\lambda - 1)(\lambda + 2)^2$$

- V_1 for $\lambda = \lambda_1 = 1$ has basis $v_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$
- V_2 for $\lambda = \lambda_2 = \lambda_3 = -2$ has basis $v_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$

There are only two independent eigenvectors. So no eigenvector basis.
 So: A can not be diagonalized!

□

$$E3. A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \text{ eigenvalues:}$$

(triangular!) $\lambda_1 = 1, \lambda_2 = 1$.

Eigenvectors $v = \begin{bmatrix} x \\ y \end{bmatrix}$ satisfies $Av = 1 \cdot v$

$$\text{i.e. } Av = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x+y \\ y \end{bmatrix}$$

$$v = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\text{So: } Av = v \text{ means: } \begin{bmatrix} x+y \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\text{i.e. } x = 0$$

$$\text{So: } v = \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ y \end{bmatrix} = y \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\mathbb{R}^2 \supseteq V_1 = \lambda v \in V; Av = v = \mathbb{R} \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

So, no basis of eigenvectors.

So, A does not diagonalize.

□

E. Criterion for diagonalizability:

T3. Let A be $n \times n$ matrix

with distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_p$
which appear with multiplicities m_1, m_2, \dots, m_p
 $\left[\text{So, } m_1 + m_2 + \dots + m_p = n \right] \equiv n = \deg(\det(A - \lambda I))$

$$(a) \quad \underline{\dim \{V_{\lambda_i}\}} \leq \underline{m_i}$$

dimension of λ -eigenspace is \leq
multiplicity of λ .

(b) A is diagonalizable iff
all these inequalities are equalities.

[For each eigenvalue λ any basis of
 V_{λ} has the number of elements
the same as multiplicity of λ]

(c) Then, we choose bases B_1 for V_{λ_1} ,
 B_2 for V_{λ_2} etc, and together they
form a basis of \mathbb{R}^n : $\boxed{B_1, B_2, \dots, B_p}$.

This is a basis consisting of
eigenvectors of A so:

$$A = P D P^{-1}, \quad A_{\mathcal{B}} = P, \quad D = \begin{bmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_2 & \\ & & & \ddots \\ & & & & \lambda_p \end{bmatrix}$$

$\left. \begin{array}{l} \text{ } \\ \text{ } \\ \text{ } \\ \text{ } \end{array} \right\} m_i \text{ times}$
 $\left. \begin{array}{l} \text{ } \\ \text{ } \\ \text{ } \\ \text{ } \end{array} \right\} m_j \text{ times}$

