

## Homework Set 2 - SOLUTIONS

1. *Orthogonality of complex exponentials:* Consider the complex exponential functions

$$\phi_n(x) = e^{-i\left(\frac{n\pi x}{L}\right)} \quad \text{for } -\infty < n < \infty.$$

Show that

$$\langle \phi_n(x), \phi_m(x) \rangle = \int_{-L}^L \phi_n(x) \overline{\phi_m(x)} dx = \begin{cases} 0 & \text{if } n \neq m \\ 2L & \text{if } n = m, \end{cases}$$

and thus the functions are mutually orthogonal.

**ANS:** First note that

$$\phi_n(x) = e^{-i\left(\frac{n\pi x}{L}\right)} = \cos\left(-\frac{n\pi x}{L}\right) + i \sin\left(-\frac{n\pi x}{L}\right) = \cos\left(\frac{n\pi x}{L}\right) - i \sin\left(\frac{n\pi x}{L}\right).$$

Thus,

$$\begin{aligned} \langle \phi_n(x), \phi_m(x) \rangle &= \int_{-L}^L \phi_n(x) \overline{\phi_m(x)} dx \\ &= \int_{-L}^L \left( \cos\left(\frac{n\pi x}{L}\right) - i \sin\left(\frac{n\pi x}{L}\right) \right) \left( \cos\left(\frac{m\pi x}{L}\right) + i \sin\left(\frac{m\pi x}{L}\right) \right) dx \\ &= \int_{-L}^L \cos\left(\frac{n\pi x}{L}\right) \cos\left(\frac{m\pi x}{L}\right) + \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx \\ &\quad + i \int_{-L}^L \cos\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) - \sin\left(\frac{n\pi x}{L}\right) \cos\left(\frac{m\pi x}{L}\right) dx \\ &= \begin{cases} (0+0) + i(0-0) & n \neq m \\ (L+L) + i(0-0) & n = m \end{cases} \\ &= \begin{cases} 0 & n \neq m \\ 2L & n = m \end{cases} \end{aligned}$$

due to the mutual orthogonality of Sines and Cosines over  $[-L, L]$ . This was shown in HW #1 when  $L = \pi$ . However, the argument in that solution follows for any  $L > 0$ .

2. Show that the second order centered finite difference approximation to  $u''(x_j)$ ,

$$D^2u_j = \frac{u_{j-1} - 2u_j + u_{j+1}}{h^2},$$

satisfies

$$u''(x_j) = D^2u_j + O(h^2),$$

using Taylor series approximations. Here  $u_j = u(x_j)$  and  $u_{j\pm 1} = u(x_{j\pm 1})$  where  $x_{j\pm 1} = x_j \pm h$ . Derive a concise formula for the  $O(h^2)$  error term.

**ANS:** We have the following Taylor expansions:

$$u_{j-1} = u(x_j) - u'(x_j)h + \frac{1}{2}u''(x_j)h^2 - \frac{1}{6}u'''(x_j)h^3 + \frac{1}{24}u^{(4)}(c_x^-)h^4 \quad \text{where } c_x^- \in (x_j - h, x_j)$$

$$u_j = u(x_j)$$

$$u_{j+1} = u(x_j) + u'(x_j)h + \frac{1}{2}u''(x_j)h^2 + \frac{1}{6}u'''(x_j)h^3 + \frac{1}{24}u^{(4)}(c_x^+)h^4 \quad \text{where } c_x^+ \in (x_j, x_j + h)$$

Forming the linear combination gives:  $au_{j-1} + bu_j + cu_{j+1} =$

$$(a + b + c)u_j + (-ah + ch)u'(x_j) + \frac{1}{2}(ah^2 + ch^2)u''(x_j) + \dots$$

Since we have three unknowns  $a$ ,  $b$ , and  $c$ , we choose them so that  $u''(x_j)$  is multiplied by 1, and  $u(x_j)$  and  $u'(x_j)$  are multiplied by 0. Thus  $a$ ,  $b$ , and  $c$  must satisfy

$$\begin{aligned} a + b + c &= 0 \\ -ah + ch &= 0 \Rightarrow a = c = \frac{1}{h^2}, b = -\frac{2}{h^2}. \\ (ah^2 + ch^2)/2 &= 1 \end{aligned}$$

Using these values gives us the approximation

$$u''(x_j) \approx \frac{u_{j-1} - 2u_j + u_{j+1}}{h^2}.$$

Since  $a = c$  the coefficient for the  $u'''(x_j)$  term is 0, and the error term is then given by

$$\frac{1}{24}h^4(au^{(4)}(c_x^-) + cu^{(4)}(c_x^+)) = \frac{1}{24}h^2(u^{(4)}(c_x^-) + u^{(4)}(c_x^+))$$

and assuming that  $u^{(4)}(x)$  is a continuous then  $u^{(4)}(c_x^-) + u^{(4)}(c_x^+) = 2u^{(4)}(c_x^*)$  where  $c_x^* \in (c_x^-, c_x^+)$  function. Then the error term can be written

$$\frac{1}{24}h^2(2u^{(4)}(c_x^*)) = \frac{h^2}{12}u^{(4)}(c_x^*) = O(h^2).$$

3. Find **by hand** the eigenvalues and eigenvectors of the following matrices

$$(a) \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \quad (b) \begin{bmatrix} 0 & 2 \\ 1 & 0 \end{bmatrix} \quad (c) \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \quad (d) \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

**ANS:** We first determine the eigenvalues from the roots of  $p_A(\lambda) = \det(A - \lambda I)$ , the characteristic polynomial, and then for each a corresponding non-zero eigenvector  $x$  which is a solution of the homogeneous system  $(A - \lambda I)x = 0$ .

$$(a) p_A(\lambda) = \det(A - \lambda I) = \det \begin{bmatrix} 2 - \lambda & 0 \\ 0 & 1 - \lambda \end{bmatrix} = (2 - \lambda)(1 - \lambda) = 0 \Rightarrow \lambda_1 = 2, \lambda_2 = 1.$$

For  $\lambda_1 = 2$  we have

$$\begin{bmatrix} 2 - 2 & 0 \\ 0 & 1 - 2 \end{bmatrix} x = \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix} x = 0 \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} c \\ 0 \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_1, \mathbf{x}_1) = (2, [\mathbf{1} \ 0]^T)$ . For  $\lambda_1 = 1$  we have

$$\begin{bmatrix} 2 - 1 & 0 \\ 0 & 1 - 1 \end{bmatrix} x = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} x = 0 \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} 0 \\ c \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_2, \mathbf{x}_2) = (1, [0 \ \mathbf{1}]^T)$ . Of course, for this matrix we can easily see that these are the eigenvalues and eigenvectors since it is diagonal.

$$(b) p_A(\lambda) = \det(A - \lambda I) = \det \begin{bmatrix} -\lambda & 2 \\ 1 & -\lambda \end{bmatrix} = \lambda^2 - 2 = 0 \Rightarrow \lambda_1 = \sqrt{2}, \lambda_2 = -\sqrt{2}. \text{ For}$$

$\lambda_1 = \sqrt{2}$  we have

$$\begin{bmatrix} -\sqrt{2} & 2 \\ 1 & -\sqrt{2} \end{bmatrix} x = \begin{bmatrix} -\sqrt{2} & 2 \\ 1 & -\sqrt{2} \end{bmatrix} x = 0 \Rightarrow x^{(1)} = \sqrt{2}x^{(2)} \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} c\sqrt{2} \\ c \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_1, \mathbf{x}_1) = (\sqrt{2}, [\sqrt{2} \ \mathbf{1}]^T)$ . For  $\lambda_2 = -\sqrt{2}$  we have

$$\begin{bmatrix} \sqrt{2} & 2 \\ 1 & \sqrt{2} \end{bmatrix} x = \begin{bmatrix} \sqrt{2} & 2 \\ 1 & \sqrt{2} \end{bmatrix} x = 0 \Rightarrow x^{(1)} = -\sqrt{2}x^{(2)} \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} -c\sqrt{2} \\ c \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_2, \mathbf{x}_2) = (-\sqrt{2}, [-\sqrt{2} \ \mathbf{1}]^T)$ .

$$(c) p_A(\lambda) = \det(A - \lambda I) = \det \begin{bmatrix} 2 - \lambda & -1 \\ -1 & 2 - \lambda \end{bmatrix} = (2 - \lambda)^2 - 1 = \lambda^2 - 4\lambda + 3 = (\lambda - 3)(\lambda - 1) = 0 \Rightarrow \lambda_1 = 1, \lambda_2 = 3. \text{ For } \lambda_1 = 1 \text{ we have}$$

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} x = 0 \Rightarrow x^{(1)} = x^{(2)} \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} c \\ c \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_1, \mathbf{x}_1) = (1, [\mathbf{1} \ \mathbf{1}]^T)$ . For  $\lambda_2 = 3$  we have

$$\begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} x = 0 \Rightarrow x^{(1)} = -x^{(2)} \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} -c \\ c \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_2, \mathbf{x}_2) = (3, [-1 \ \mathbf{1}]^T)$ .

(d)  $p_A(\lambda) = \det(A - \lambda I) = \det \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix} = \lambda^2 + 1 = 0 \Rightarrow \lambda_1 = i, \lambda_2 = -i$ . For  $\lambda_1 = i$  we have

$$\begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} x = 0 \Rightarrow x^{(1)} = ix^{(2)} \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} ic \\ c \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_1, \mathbf{x}_1) = (i, [\mathbf{i} \ 1]^T)$ . For  $\lambda_2 = -i$  we have

$$\begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix} x = 0 \Rightarrow x^{(1)} = -ix^{(2)} \Rightarrow x \in \text{span} \left\{ \begin{bmatrix} -ic \\ c \end{bmatrix} \right\} \text{ for any } c \neq 0.$$

Taking  $c = 1$ , we have the eigen-pair  $(\lambda_2, \mathbf{x}_2) = (-i, [-\mathbf{i} \ 1]^T)$ .

4. Write a MATLAB function M-file **trisolve.m** to solve the linear system  $Ax = f$  where

$$A = \begin{pmatrix} a_1 & c_1 & & & \\ b_2 & a_2 & c_2 & & \\ & \ddots & \ddots & \ddots & \\ & & & \ddots & \ddots & c_{n-1} \\ & & & & b_n & a_n \end{pmatrix}$$

is a tridiagonal  $n \times n$  matrix **Assume** that no partial pivoting is required. The inputs are the  $n$ -vectors  $a$ ,  $b$ ,  $c$  and  $f$  and returns the solution  $x$ . Its first line should read:

```
function x = trisolve(a,b,c,f)
```

Test your code with the  $5 \times 5$  system with  $a_i = 2$ ,  $b_i = -1$ ,  $c_i = -1$ , and RHS  $f = [1, 0, 0, 0, 1]^T$ . The exact solution is  $x = [1, 1, 1, 1, 1]^T$ . Use MATLAB's **diary** command to save your MATLAB session output showing that your code works properly. Include a copy of both codes.

**ANS:** Here is the MATLAB code

```
function x = trisolve(a,b,c,f)
%
% A = tridiag(b,a,c)

n = length(a);           % determine system size
x = zeros(n,1);         % allocate x

for i = 1:n-1           % forward eliminatio sweep GE
    m = b(i+1)/a(i);     % compute multiplier
    a(i+1) = a(i+1)-m*c(i); % a (but not c) changes for row operation
    f(i+1) = f(i+1)-m*f(i); % row op applied to RHS f
end

x(n) = f(n)/a(n);       % back substitution
for i = n-1:-1:1
    x(i) = (f(i)-c(i+1)*x(i+1))/a(i);
end
```

and here is the output of the  $5 \times 5$  test system:

```
>> a = 2*ones(5,1); b = -ones(5,1); c=b; f=[1 0 0 0 1]';
>> x = trisolve(a,b,c,f)
```

```
x =

    1.0000
    1.0000
    1.0000
    1.0000
    1.0000
```

5. Consider the 2-point BVP

$$\begin{cases} -u'' = -(x^2 + 3x)e^x \\ u(0) = u(1) = 0 \end{cases}$$

- (a) Show  $u(x) = (x^2 - x)e^x$  is the exact solution.
- (b) Write a MATLAB function M-file to solve the problem using the 2nd order centered FD scheme we discussed in class,  $-D^2v_i = f_i$ , that utilizes your m-file **trisolve.m** from problem 3 above. Note that  $\sigma = 0$  here. Assume a mesh size  $h = 1/n$  where  $n = 2^p$  for  $p$  a positive integer. For  $p = 1 : 12$  present a table with the following data - column 1:  $h$ ; column 2:  $\|u_h - v_h\|_\infty$ ; column 3:  $\|u_h - v_h\|_\infty/h^2$ ; where  $h = 1/n$ . What does the trend in the third column indicate? Include a copy of your code.

**ANS:** (a) is just straightforward substitution.

Here is the output and code for (b). Note that the third column is approaching a constant, indicating second order convergence.

h	inf_error	inf_error/h^2
5.0000e-01	5.1523e-02	2.0609e-01
2.5000e-01	1.3185e-02	2.1096e-01
1.2500e-01	3.3308e-03	2.1317e-01
6.2500e-02	8.4567e-04	2.1649e-01
3.1250e-02	2.1150e-04	2.1657e-01
1.5625e-02	5.2879e-05	2.1659e-01
7.8125e-03	1.3221e-05	2.1662e-01
3.9062e-03	3.3054e-06	2.1662e-01
1.9531e-03	8.2635e-07	2.1662e-01
9.7656e-04	2.0659e-07	2.1662e-01
4.8828e-04	5.1647e-08	2.1662e-01
2.4414e-04	1.2910e-08	2.1659e-01

```
p = (1:12)';
n = 2.^p;
dispvars = zeros(length(p),3);

for i = 1:length(p)
    N = n(i);    h = 1/N;    x = h*(0:N)';

    u_h = (x.^2-x).*exp(x);    % true solution u(0)=u(1)=0
    f_h = -(x.^2+3*x).*exp(x); % -u'' = f

    a = 2*ones(N-1,1)/(h^2);    % create a, b & c
    b = -ones(N-1,1)/(h^2);
    c = -ones(N-1,1)/(h^2);
    ftil = f_h(2:N);            % rhs is f evaluated at n-1 interior pts
```

```

v_h = trisolve(a,b,c,ftil); % solve
v_h = [0;v_h;0];          % set BCs u(0)=u(1)=0

dispvars(i,1) = h;
dispvars(i,2) = max(abs(v_h-u_h));
dispvars(i,3) = dispvars(i,2)/h^2;
end

format short e
disp(' ')
disp('      h      inf_error  inf_error/h^2')
disp('-----')
disp(dispvars)

```