MATH 235-04, Spring 2018
Quiz 2 Solutions

1. Let A be the matrix of the reflection of $\mathbb{R}^{2}$ through the line $\ell=\operatorname{span}\left\{\left[\begin{array}{l}2 \\ 1\end{array}\right]\right\}$, and let B be the matrix of reflection through the $x_{1}$-axis. Find the matrix of the linear map which takes any vector $\mathbf{x} \in \mathbb{R}^{2}$ to the vector obtained by first reflecting $\mathbf{x}$ through the $x_{1}$-axis, and then reflecting the result through $\ell$.
What is the geometric interpretation of this map?

The matrix A of the map $\operatorname{Ref}_{\ell}: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ was found in class to be

$$
\mathrm{A}=\left[\begin{array}{cc}
3 / 5 & 4 / 5 \\
4 / 5 & -3 / 5
\end{array}\right]
$$

The matrix B of the map $\operatorname{Ref}_{\text {span } \mathbf{e}_{1}}$ is

$$
\mathrm{B}=\left[\begin{array}{ll}
\operatorname{Ref}_{\text {span } \mathbf{e}_{1}}\left(\mathbf{e}_{1}\right) & \operatorname{Ref}_{\text {span }} \mathbf{e}_{1}\left(\mathbf{e}_{2}\right)
\end{array}\right]=\left[\begin{array}{ll}
\mathbf{e}_{1} & -\mathbf{e}_{2}
\end{array}\right]=\left[\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right] .
$$

The map whose matrix we are to compute is the composition $\operatorname{Ref}_{\ell} \circ \operatorname{Ref}_{\text {span }_{1}}: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$, whence the matrix is given by

$$
\mathrm{AB}=\left[\begin{array}{cc}
3 / 5 & 4 / 5 \\
4 / 5 & -3 / 5
\end{array}\right]\left[\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right]=\left[\begin{array}{cc}
3 / 5 & -4 / 5 \\
4 / 5 & 3 / 5
\end{array}\right]
$$

This matrix is a rotation matrix, and geometrically, the map $\operatorname{Ref}_{\ell} \circ \operatorname{Ref}_{\text {span } \mathbf{e}_{1}}: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ is a counterclockwise rotation of $\mathbb{R}^{2}$ by twice the angle $\varphi=\arccos (2 / \sqrt{5})$ between the $x_{1}$ axis and $\ell$. Thus, it is rotation by the angle $\theta=2 \varphi=\arccos (3 / 5)$. To see this, note that the columns of M are each unit vectors whose components satisfy

$$
\begin{aligned}
\frac{3}{5} & =\left(\frac{2}{\sqrt{5}}\right)^{2}-\left(\frac{1}{\sqrt{5}}\right)^{2}=\cos ^{2} \varphi-\sin ^{2} \varphi=\cos (2 \varphi) \\
\pm \frac{4}{5} & = \pm 2\left(\frac{2}{\sqrt{5}}\right)\left(\frac{1}{\sqrt{5}}\right)= \pm 2 \sin \varphi \cos \varphi= \pm \sin (2 \varphi)
\end{aligned}
$$

Compare this to the general form of a counterclockwise rotation matrix for an angle $\theta>0$ :

$$
\mathrm{R}_{\theta}=\left[\begin{array}{cc}
\cos \theta & -\sin \theta \\
\sin \theta & \cos \theta
\end{array}\right] .
$$

Setting $\theta=2 \varphi$ gives M for $\varphi$ as described.
Generally, a composition of two reflections about a pair of lines meeting at $\mathbf{0}$ with angle of separation $\varphi$ will produce either a clockwise or counterclockwise rotation by the angle $2 \theta$. Whether it is clockwise or counterclockwise depends on which line is the first to be reflected over, and which of the vertical angle pairs is chosen to correspond to $\theta$; one can always realize a counterclockwise rotation by $\theta=2 \varphi$ as a clockwise rotation by $2 \pi-\theta=2(\pi-\varphi)$.
2. For the matrix obtained in the preceding question representing the composition of the two reflections, find the inverse matrix. Call it M , and compute

$$
M\left[\begin{array}{l}
1 \\
2
\end{array}\right] .
$$

The inverse can be computed by the formula

$$
\left[\begin{array}{ll}
a & b \\
c & d
\end{array}\right]^{-1}=\frac{1}{a d-b c}\left[\begin{array}{cc}
d & -b \\
-c & a
\end{array}\right]
$$

if it exists. Thus,

$$
\mathrm{M}=(\mathrm{AB})^{-1}=\frac{1}{(3 / 5)(3 / 5)-(4 / 5)(-4 / 5)}\left[\begin{array}{cc}
3 / 5 & 4 / 5 \\
-4 / 5 & 3 / 5
\end{array}\right]=\left[\begin{array}{cc}
3 / 5 & -4 / 5 \\
4 / 5 & 3 / 5
\end{array}\right]
$$

Knowing what we now know, we also can compute M knowing that both A and B are reflection matrices and thus each is self-inverse, together with the property that $(\mathrm{AB})^{-1}=$ $\mathrm{B}^{-1} \mathrm{~A}^{-1}$. Thus, $\mathrm{M}=\mathrm{B}^{-1} \mathrm{~A}^{-1}=\mathrm{BA}$.

M is also a rotation matrix, but it is a clockwise rotation by twice the angle of separation $\varphi$ between the $x_{1}$-axis and $\ell$.

Finally $\mathrm{M}\left[\begin{array}{l}1 \\ 2\end{array}\right]=\left[\begin{array}{c}3 / 5+8 / 5 \\ -4 / 5+6 / 5\end{array}\right]=\left[\begin{array}{c}11 / 5 \\ 2 / 5\end{array}\right]$.

