

Q1. (8 points) Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation.

- (a) (4 points) Give precise definitions of the kernel of  $T$  and the image of  $T$ .
- (b) (4 points) Now suppose that  $T$  is invertible. What is the kernel of  $T$ ? What is the image of  $T$ ?

$$a) \quad \ker(T) = \{ \underline{x} \in \mathbb{R}^n \mid T(\underline{x}) = \underline{0} \}$$

In words, the kernel of  $T$  is the set of all vectors  $\underline{x} \in \mathbb{R}^n$  such that  $T(\underline{x}) = \underline{0}$ .

$$\text{image}(T) = \{ \underline{y} \in \mathbb{R}^m \mid \underline{y} = T(\underline{x}) \text{ for some } \underline{x} \in \mathbb{R}^n \}$$

In words, the image of  $T$  is the set of all vectors  $\underline{y} \in \mathbb{R}^m$  such that  $\underline{y} = T(\underline{x})$  for some  $\underline{x} \in \mathbb{R}^n$ . (The image of  $T$  is also called the range of  $T$ .)

b)  $T$  is invertible  $\Leftrightarrow$  for every  $\underline{y} \in \mathbb{R}^m$  there is exactly one  $\underline{x} \in \mathbb{R}^n$  such that  $T(\underline{x}) = \underline{y}$ .

In particular  $T$  invertible  $\Rightarrow$   $\text{image}(T) = \mathbb{R}^m$   
and  $\ker(T) = \{ \underline{0} \}$

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(because  $\underline{0} \in \mathbb{R}^n$  is the unique vector  $\underline{x}$  such that  $T(\underline{x}) = \underline{0} \in \mathbb{R}^m$ .)

Q2. (6 points) Let  $W \subset \mathbb{R}^3$  be the plane defined by the equation

$$x + 3y + 7z = 0.$$

Find a basis of  $W$ .

$$x + 3y + 7z = 0.$$

Solve by Gaussian Elimination: -

$y$  &  $z$  are free variables, and  $x = -3y - 7z$ .

$$\text{i.e. } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -3y - 7z \\ y \\ z \end{pmatrix} = y \begin{pmatrix} -3 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} -7 \\ 0 \\ 1 \end{pmatrix}$$

$\Rightarrow \begin{pmatrix} -3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -7 \\ 0 \\ 1 \end{pmatrix}$  is a basis of  $W$ .

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Alternatively, if  $W \subset \mathbb{R}^3$  is a plane through the origin, then  $W$  is a subspace of dimension 2, and any two vectors  $\underline{v}_1, \underline{v}_2 \in W$  which are not parallel give a basis of  $W$ .

c) The dimension of a subspace  $W \subset \mathbb{R}^n$  is the number of vectors in a basis of the subspace. So, using (a) & (b),  
 $\dim(\text{image}(T)) = 2$  and  $\dim(\text{ker}(T)) = 3$ .

Q3. (10 points) Let  $T: \mathbb{R}^5 \rightarrow \mathbb{R}^3$  be the linear transformation  $T(\mathbf{x}) = A\mathbf{x}$  with matrix

$$A = \begin{pmatrix} 1 & 3 & 2 & 7 & 2 \\ 1 & 3 & 1 & 2 & 3 \\ 2 & 6 & 3 & 9 & 5 \end{pmatrix}.$$

The reduced row echelon form of the matrix  $A$  is

$$\text{RREF}(A) = \begin{pmatrix} 1 & 3 & 0 & -3 & 4 \\ 0 & 0 & 1 & 5 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

(You do NOT need to check this!)

- (4 points) Find a basis for the image of  $T$ .
- (4 points) Find a basis for the kernel of  $T$ .
- (2 points) What is the dimension of the image of  $T$ ? What is the dimension of the kernel of  $T$ ?

(a) A basis for  $\text{image}(T)$  is given by the columns of  $A$  corresponding to columns of  $\text{RREF}(A)$  containing pivots (= "leading 1's" in the textbook).

In an example, this gives a basis  $\begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$  for  $\text{image}(T)$ .

(b) Solve the equations  $A\underline{x} = \underline{0}$  using  $\text{RREF}(A)$  :-

$$A\underline{x} = \underline{0} \iff \text{RREF}(A) \cdot \underline{x} = \underline{0} \iff \begin{cases} x_1 + 3x_2 - 3x_4 + 4x_5 = 0 \\ x_3 + 5x_4 - x_5 = 0 \end{cases}$$

$$\iff \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} -3x_2 + 3x_4 - 4x_5 \\ x_2 \\ -5x_4 + x_5 \\ x_4 \\ x_5 \end{pmatrix} = x_2 \begin{pmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 3 \\ 0 \\ -5 \\ 1 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} -4 \\ 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

$x_2, x_4$  &  $x_5$  are free.  
 $x_2, x_4, x_5 \in \mathbb{R}$  are arbitrary.

$\therefore$  A basis for  $\text{ker}(T)$  is  $\begin{pmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ -5 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -4 \\ 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$ .