- 1. (17 points) Let θ be an angle, such that $\sin(\theta) \neq 0$, and let $A := \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}$ be the matrix of the rotation of \mathbb{R}^2 about the origin by angle θ counterclockwise.
 - (a) The characteristic polynomial of A is $h(x) = x^2 2\cos(\theta) + 1$.
 - (b) The minimal polynomial m(x) of A is equal to its characteristic polynomial $x^2-2\cos(\theta)+1$. Two ways to see it are: If we work over the complex numbers, then the equality h(x)=m(x) follows, since the two roots $\cos(\theta)+\sin(\theta)i$ and $\cos(\theta)-\sin(\theta)i$ of h(x) are distinct, and m(x) and h(x) have the same set of roots, and m(x) divides h(x), by the Cayley Hamilton Theorem. Over the real numbers the equality m(x)=h(x) follows, since h(x) is a prime polynomial, m(x) has positive degree, and m(x) divides h(x).
 - (c) A is similar to a diagonal matrix in $M_2(\mathbb{C})$, since the minimal polynomial factors as a product of linear terms with distinct roots $m(x) = (x [\cos(\theta) + \sin(\theta)i])(x [\cos(\theta) \sin(\theta)i]).$
 - (d) A is not similar to a diagonal matrix in $M_2(\mathbb{R})$, since its minimal polynomial is prime in $\mathbb{R}[x]$.
- 2. (17 points) Set $A := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$.
 - (a) The characteristic polynomial of A is $x^2 + 1$. Its two eigenvalues are i and -i.
 - (b) A basis of \mathbb{C}^2 consisting of eigenvectors of A. We find first a basis for the i-eigenspace null(A-iI), then for the -i eigenspace null(A+iI), and take their union as a basis for \mathbb{C}^2 .

their union as a basis for \mathbb{C}^2 . $A - iI = \begin{pmatrix} -i & -1 \\ 1 & -i \end{pmatrix} \sim \begin{pmatrix} 1 & -i \\ 0 & 0 \end{pmatrix}.$

Thus, null(A - iI) is spanned by $v_1 := \begin{pmatrix} i \\ 1 \end{pmatrix}$.

 $A+iI=\left(\begin{array}{cc}i&-1\\1&i\end{array}\right)\sim\left(\begin{array}{cc}1&i\\0&0\end{array}\right).$

Thus, null(A+iI) is spanned by $v_2 := \begin{pmatrix} -i \\ 1 \end{pmatrix}$.

(c) Find an invertible matrix P and a diagonal matrix D, both in $M_2(\mathbb{C})$, such that $P^{-1}AP = D$.

Answer: Take $P := (v_1 v_2) = \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix}$. Then $D = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$.

- 3. (17 points) Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be given by multiplication by $A = \begin{pmatrix} -2 & 9 \\ -1 & 4 \end{pmatrix}$.
 - (a) The characteristic polynomial of T is $h(x) = (x-1)^2$.
 - (b) The minimal polynomial m(x) of T divides h(x). If m(x) = x 1, then A = I, which is false. Hence, $m(x) = (x 1)^2$.

- (c) T is not diagonalizable, since its minimal polynomial is a product of linear terms with repeated roots.
- (d) The unique eigenvalue of T is the scalar 1.
- (e) As a basis for the 1-eigenspace of T we can take $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$.
- (f) Find an upper triangular matrix B and an invertible matrix P, such that $B = P^{-1}AP$. Carefully explain, in complete sentences, your method for finding P. Credit will not be given for an answer obtained by trial and error.

Answer: The proof of the Triangular Form Theorem dictates, that we should choose a basis $\{v_1, v_2\}$ for $\mathbb{R}^2 = null((A-I)^2)$, so that $(A-I)v_1 = 0$. Take $v_1 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ and $v_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$. The change of basis matrix is $P = (v_1v_2) = \begin{pmatrix} 3 & 1 \\ 1 & 0 \end{pmatrix}$, and $P^{-1}AP = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$ is upper triangular.

4. (17 points)

(a) Let V be a finite dimensional vector space, T, D, and N, three linear transformations in L(V,V), such that T=D+N. State the three properties that D and N need to satisfy, in order for the above to be the Jordan decomposition of T.

Answer: i) D is diagonalizable, ii) N is nilpotent, iii) DN = ND.

(b) Let
$$A = \begin{pmatrix} 0 & 4 \\ -1 & 4 \end{pmatrix}$$
, $B = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$, and $P = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$. Note, that $P^{-1}AP = B$.

- i. The Jordan decomposition of B is B=D'+N', where $D'=\begin{pmatrix}2&0\\0&2\end{pmatrix}$ and $N'=\begin{pmatrix}0&1\\0&0\end{pmatrix}$.
- ii. The Jordan decomposition A = D + N of A is:

$$A = PBP^{-1} = P(D' + N')P^{-1} = PD'P^{-1} + PN'P^{-1}$$

We see that
$$D=PD'P^{-1}=\left(\begin{array}{cc}2&0\\0&2\end{array}\right)$$
 and $N=PN'P^{-1}=\left(\begin{array}{cc}-2&4\\-1&2\end{array}\right)$.

- iii. We verify that the matrices D and N in part 4(b)ii satisfy the properties in part 4a, by a direct calculation.
- iv. Using Jordan decomposition of A we calculate:

 $A^k = (D+N)^k = D^k + kD^{k-1}N + \dots$, where the other terms involve powers N^i , $i \ge 2$, which vanish. Hence,

$$A^{k} = \begin{pmatrix} 2^{k} & 0 \\ 0 & 2^{k} \end{pmatrix} + k \begin{pmatrix} 2^{k-1} & 0 \\ 0 & 2^{k-1} \end{pmatrix} \begin{pmatrix} -2 & 4 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} (1-k)2^{k} & k2^{k+1} \\ -k2^{k-1} & (k+1)2^{k} \end{pmatrix}.$$

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- 5. (17 points) Let V be an n-dimensional vector space over \mathbb{R} with an inner product and u a unit vector in V. Recall, that the reflection R of V, with respect to the subspace u^{\perp} orthogonal to u, is given by R(v) = v 2(v, u)u.
 - (a) $R^2(v) = R(R(v)) = R(v 2(v, u)u) = [v 2(v, u)u] 2([v 2(v, u)u], u)u = [v 2(v, u)u] + 2(v, u)u = v$. Hence, $R^2 = 1$.
 - (b) The minimal polynomial m(x) of R divides $x^2 1 = (x 1)(x + 1)$, since $R^2 1 = 0$. If m(x) = x 1, then R = 1, which it is clearly not, by part 5d. If m(x) = x + 1, then R = -1, and the -1 eigenspace is the whole of V. This is the case, precisely if V is one dimensional, by part 5d. Hence, if n = 1, then m(x) = x + 1, and if n > 2, then $m(x) = x^2 1$.
 - (c) R is diagonalizable, since its minimal polynomial is a product of linear terms with distinct roots.
 - (d) We compute the -1 eigenspace of R by solving the equation R(v) = -v, which is equivalent to v 2(v, u)u = -v. Solving for v in terms of u, we get that v is in the -1 eigenspace, if and only is v = (v, u)u, i.e., if and only if v is a scalar multiple of u.
 - (e) The characteristic polynomial of R is $h(x) = (x-1)^{d_+}(x+1)^{d_-}$, where d_+ is the dimension of the +1 eigenspace null(R-1) and d_- is the dimension of the -1 eigenspace null(R+1), since R is diagonalizable. Now $d_- = 1$, by part 5d, and $d_+ + d_- = n$, since the characteristic polynomial has degree n. Hence, $d_+ = n 1$ (We also saw in class several times, that the +1 eigenspace is u^{\perp} , which is n 1 dimensional). We conclude, that $h(x) = (x 1)^{n-1}(x + 1)$.
 - (f) The trace tr(R) is the sum of the eigenvalues, repeated according to their multiplicity in the characteristic polynomial. Hence, tr(R) = -1 + (n-1)1 = n-2.
- 6. (17 points) Let V be a finite dimensional vector space over a field F, and $T:V\to V$ a linear transformation.
 - (a) Let $v \in V$ be an eigenvector of T with eigenvalue λ , and $g(x) = c_n x^n + \cdots + c_0$ a polynomial in F[x]. Show that v is an eigenvector of g(T) and find its eigenvalue.

Answer: $T^n(v) = \lambda^n v$. Hence, $g(T)v = c_n T^n(v) + \cdots + c_0 v = (c_n \lambda^n + \cdots + c_0)v = g(\lambda)v$. The eigenvalue is thus $g(\lambda)$.

(b) Use part 6a to show, that every root of the characteristic polynomial h(x) of T is also a root of the minimal polynomial m(x) of T (without using the Cayley-Hamilton Theorem).

Answer: Let λ be a root of the characteristic polynomial of T. Then there exists a non-zero eigenvector v with eigenvalue λ . Then $m(T)v = m(\lambda)v$, by the previous part. On the other hand, m(T) = 0, so m(T)v = 0. Hence, $m(\lambda)v = 0$, and thus $m(\lambda) = 0$.

- 7. (17 points) Let V be a four dimensional vector space over \mathbb{C} . Assume that the characteristic polynomial of T is $h(x) = (x \lambda_1)^2 (x \lambda_2)^2$, and $\lambda_1 \neq \lambda_2$.
 - (a) The four possible minimal polynomials m(x) of T (with leading coefficient 1) are: $(x \lambda_1)^{e_1}(x \lambda_2)^{e_2}$, where $1 \le e_1 \le 2$, and $1 \le e_2 \le 2$, since m(x) divides h(x) and m(x) and h(x) have the same set of roots.
 - (b) Assume that the minimal polynomial of T is $m(x) = (x \lambda_1)^{e_1}(x \lambda_2)^{e_2}$, set $V_i := null[(T \lambda_i \mathbf{1})^{e_i}]$, where $\mathbf{1}$ is the identity transformation, and let $T_i \in L(V_i, V_i)$ be the restriction of T to V_i . Use the Primary Decomposition Theorem to show, that the minimal polynomial of T_i is $(x \lambda_i)^{e_i}$. Hint: Show first that the minimal polynomial $m_i(x)$ of T_i divides m(x) and the product $g(x) := m_1(x)m_2(x)$ satisfies g(T) = 0.

Answer: Step 1 $(m_i(x) \text{ divides } m(x))$: Let v be a vector in V_i . Then $T_i(v) = T(v)$, by definition of T_i . So $m(T_i)v = m(T)v = 0$. Thus the minimal polynomial $m_i(x)$ of T_i divides m(x).

Step 2 (g(T) = 0): Let $\{v_1, \ldots, v_{n_1}\}$ be a basis of V_1 , and $\{w_1, \ldots, w_{n_2}\}$ a basis of V_2 . Their union is a basis of V, so it suffices to show, that $g(T)v_i = 0 = g(T)w_j$. Now $g(T)v_i = m_2(T)(m_1(T)v_i) = m_2(T)(0) = 0$. Similarly, $g(T)w_j = m_1(T)(m_2(T)w_j) = m_1(T)(0) = 0$.

Step 3: m(x) divides $m_1(x)m_2(x)$, since $m_1(T)m_2(T) = 0$, by Step 2. The product $m_1(x)m_2(x)$ divides m(x), since each factor does, by Step 1, and the two factors are relatively prime (they do not have a common factor). Hence, $m(x) = m_1(x)m_2(x)$, since both sides have leading coefficient 1.

(c) Assuming that the minimal polynomial of T is $(x - \lambda_1)^2(x - \lambda_2)$, the dimensions of the null spaces of $T - \lambda_1 \mathbf{1}$, $(T - \lambda_1 \mathbf{1})^2$, $T - \lambda_2 \mathbf{1}$, and $(T - \lambda_2 \mathbf{1})^2$ are: dim $null(T - \lambda_1 \mathbf{1}) = 1$, dim $null[(T - \lambda_1 \mathbf{1})^2] = 2$, dim $null(T - \lambda_2 \mathbf{1}) = 2$, and dim $null[(T - \lambda_2 \mathbf{1})^2] = 2$.

Reason: Let $V_1 := null[(T - \lambda_1 \mathbf{1})^2]$ and $V_2 := null(T - \lambda_2 \mathbf{1})$. Then $V = V_1 \oplus V_2$, by the Primary Decomposition Theorem, and $\dim(V_i) = 2$, for both i = 1, 2, by the Triangular Form Theorem, since the multiplicity of the corresponding eigenvalue, as a root of the characteristic polynomial, is 2. This explains two of the above four equalities.

The equality dim $null(T - \lambda_1 \mathbf{1}) = 1$: We know that $null(T - \lambda_1 \mathbf{1})$ is non-zero, since λ_1 is an eigenvalue, and $null(T - \lambda_1 \mathbf{1})$ is contained in $null[(T - \lambda_1 \mathbf{1})^2]$, which is two dimensional. Hence, $1 \leq \dim null(T - \lambda_1 \mathbf{1}) \leq 2$. If dim $null(T - \lambda_1 \mathbf{1}) = 2$, then we would have had a basis of V consisting of eigenvectors of T, T would have been diagonalizable, and the minimal polynomial would have been $(x - \lambda_1)(x - \lambda_2)$, which it is not.

The equality dim $null[(T - \lambda_2 \mathbf{1})^2] = 2$: This part was not needed for full credit. dim $null[(T - \lambda_2 \mathbf{1})^2] \ge \dim null(T - \lambda_2 \mathbf{1}) = 2$. If strict inequality held, then there would have been a vector v in $null[(T - \lambda_2 \mathbf{1})^2]$, which did not belong to $null(T - \lambda_2 \mathbf{1})$. Then the order $m_v(x)$ of v would have been $(x - \lambda_2)^2$. This is impossible, since the order $m_v(x)$ divides the minimal polynomial.